# Molecular hydrodynamics of the moving contact line

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- The no-slip boundary condition and the moving contact line problem
- The generalized Navier boundary condition (GNBC) from molecular dynamics (MD) simulations
- Implementation of the new slip boundary condition in a continuum hydrodynamic model (phase-field formulation)
- Comparison of continuum and MD results
- A variational derivation of the continuum model, for both the bulk equations and the boundary conditions, from Onsager's principle of least energy dissipation (entropy production)

### Wetting phenomena: All the real world complexities we can have!

### Moving contact line: All the simplifications we can make and all the simulations, molecular and continuum, we can carry out!

Numerical experiments

Offer a minimal model with solution to this classical fluid mechanical problem, under a general principle that governs thermodynamic irreversible processes



### **No-Slip** Boundary Condition, A Paradigm

$$v_{\tau}^{slip} = 0$$





**James Clerk Maxwell** 

**Claude-Louis Navier** 

Many of the great names in **mathematics** and **physics** have expressed an opinion on the subject, including Bernoulli, Euler, Coulomb, Navier, Helmholtz, Poisson, Poiseuille, Stokes, Couette, Maxwell, Prandtl, and Taylor.

from Navier Boundary Condition (1823) to **No-Slip** Boundary Condition

 $\dot{\gamma}$  : shear rate at solid surface  $l_s$ : <u>slip length</u>, from nano- to micrometer Practically, **no slip** in macroscopic flows  $\dot{\gamma} \approx U/R \rightarrow v^{slip}/U \approx l_s/R \rightarrow 0$ 

### Hydrodynamic boundary condition



# From no slip to perfect slip (for simple fluids) Interpretation of the (Maxwell-Navier) slip length $\lambda$

*Ch.* 15 in Handbook of Experimental Fluid Dynamics Editors J. Foss, C. Tropea and A. Yarin, Springer, New-York (2005).

## Wetting: Statics and Dynamics

### Lotus Effect



Water drop on lotus plant

Water drops on surface with nano coatings Static wetting phenomena

Partial wetting

Complete wetting



(a)



#### **Dynamics of wetting**



What happens near the moving contact line had been an unsolved problems for decades.







The similarity solution of the biharmonic equation for 2D flow  $\nabla^2(\nabla^2\psi) = 0$  (linearized Navier-Stokes equation)  $\psi(r,\theta) = r(a\sin\theta + b\cos\theta + c\theta\sin\theta + d\theta\cos\theta)$ 8 coefficients in A and B, determined by 8 boundary conditions Shear stress and pressure vary as 1/r Dussan and Davis, J. Fluid Mech. 65, 71-95 (1974):

- 1. Incompressible Newtonian fluid
- 2. Smooth rigid solid walls
- 3. Impenetrable fluid-fluid interface
- 4. No-slip boundary condition

Stress singularity: the tangential force exerted by the fluid on the solid surface is infinite.

Not even Herakles could sink a solid ! by Huh and Scriven (1971).

- a) To construct a continuum hydrodynamic model by removing condition (3) and/or (4).
- b) To make comparison with molecular dynamics simulations

Numerical experiments done for this classic fluid mechanical problem

- Koplik, Banavar and Willemsen, PRL (1988)
- Thompson and Robbins, PRL (1989)
- Slip observed in the vicinity of the MCL
- Boundary condition ???
- Continuum deduction of molecular dynamics !

#### ARTICLES

#### Molecular dynamics of fluid flow at solid surfaces

Joel Koplik,<sup>a)</sup> Jayanth R. Banavar,<sup>b)</sup> and Jorge F. Willemsen Schlumberger-Doll Research, Old Quarry Road, Ridgefield, Connecticut 06877-4108

(Received 6 September 1988; accepted 12 January 1989)



Immiscible two-phase Poiseuille flow

The walls are moving to the left in this reference frame, and away from the contact line the fluid velocity near the wall coincides with the wall velocity. **Near the contact lines the no-slip condition appears to fail**, however.

#### Simulations of Contact-Line Motion: Slip and the Dynamic Contact Angle

Peter A. Thompson and Mark O. Robbins

Department of Physics and Astronomy, The Johns Hopkins University, Baltimore, Maryland 21218 (Received 7 February 1989)



Two classes of models proposed to describe the contact line motion:

#### An Eyring approach:

Molecular adsorption/desorption processes at the contact line (three-phase zone); Molecular dissipation at the tip is dominant. T. D. Blake and J. M. Haynes, *Kinetics of liquid/liquid displacement*, J. Colloid Interf. Sci. **30**, 421 (1969).

#### A hydrodynamic approach:

Dissipation dominated by **viscous shear flow** inside the wedge; For wedges of small (apparent) contact angle, <u>a lubrication</u> <u>approximation</u> used to simplify the calculations;

A (molecular scale) cutoff introduced to remove the logarithmic singularity in viscous dissipation.

F. Brochard-Wyart and P. G. De Gennes, *Dynamics of partial wetting*, Advances in Colloid and Interface Science **39**, 1 (1992).

The kinetic model by Blake and Haynes: The role of interfacial tension A fluctuating three phase **zone**.

Adsorbed molecules of one fluid interchange with those of the other fluid.

In equilibrium the net rate of exchange will be zero.

For a three-phase zone moving relative to the solid wall, the net displacement, is due to a nonzero net rate of exchange, driven by the unbalanced Young stress  $\gamma \cos \theta_d + \gamma_2 - \gamma_1 \neq 0$ 



 $K_{\pm} = k \exp\left[-\frac{1}{k_B T} \left(W \mp \frac{1}{2} F_Y \lambda^2\right)\right], \ v = \lambda (K_+ - K_-) \propto \sinh\left(F_Y \lambda^2 / 2k_B T\right)$ 



F. Brochard-Wyart and P. G. De Gennes,*Dynamics of partial wetting*,Adv. in Colloid and Interface Sci. 39, 1 (1992).

To summarize: a complete discussion of the dynamics would in principle require both terms in Eq. (21).

$$\vec{x}$$
  $T\dot{S} = \frac{3\eta}{\theta}U^2 \ln \frac{x_{\text{max}}}{x_{\text{min}}} + CU^2$  (21)

lubrication approximation:  $v_x(z) = \frac{3U}{2h^2}(2hz - z^2)$ 

hydrodynamic term for the viscous dissipation in the wedge  $\int_{x_{\min}}^{x_{\max}} dx \int_{o}^{h(x)} dz \left[ \eta (\partial_z v_x)^2 \right]$ 

molecular term due to the kinetic adsorption/desorption  $CU^2$ ,  $C = \exp\left(\frac{W}{k_{\rm e}T}\right) \frac{k_{\rm B}T}{\kappa \lambda^3}$ 

Wedge: Molecular cutoff  $X_{\min}$  introduced to the viscous dissipation

**Tip**: Molecular dissipative coefficient C from kinetic mechanism of <u>contact-line slip</u>

DISSIPATION

### **No-slip boundary condition ?**

**Apparent Violation** seen from the *moving/slipping* contact line **Infinite Energy Dissipation** (unphysical singularity)

G. I. Taylor; K. Moffatt; Hua & Scriven;E.B. Dussan & S.H. Davis; L.M. Hocking; P.G. de Gennes;Koplik, Banavar, Willemsen; Thompson & Robbins; etc

### **No-slip boundary condition breaks down !**

 Nature of the true B.C. ? (microscopic *slipping* mechanism)

Qian, Wang & Sheng, Phys. Rev. E 68, 016306 (2003)

• If *slip* occurs within a length scale *S* in the <u>vicinity</u> of the contact line, then what is the magnitude of *S*?

Qian, Wang & Sheng, Phys. Rev. Lett. 93, 094501 (2004)

Molecular dynamics simulations for two-phase Couette flow

- Fluid-fluid molecular interactions System size
- Fluid-solid molecular interactions Speed of the moving walls
- **Densities (liquid)**
- Solid wall structure (fcc)
- **Temperature**



Two identical fluids: same density and viscosity, but in general different fluid-solid interactions

Smooth solid wall: solid atoms put on a crystalline structure

No contact angle hysteresis!

A phenomenon commonly observed at rough surfaces

### Modified Lennard-Jones Potentials

$$U_{ff} = 4\varepsilon [(\sigma/r)^{12} - \delta_{ff} (\sigma/r)^{6}]$$

$$U_{wf} = 4\varepsilon_{wf} \left[ \left( \sigma_{wf} / r \right)^{12} - \delta_{wf} \left( \sigma_{wf} / r \right)^{6} \right]$$

$$\delta_{ff} = 1$$
 for like molecules  
 $\delta_{ff} = -1$  for molecules of different species  
 $\delta_{wf}$  for wetting properties of the fluids



Measurement at Solid–Fluid Boundary





schematic illustration of the boundary layer



fluid force measured according to  $G_x^f(x) = \int_0^{z_0} dz \left(\partial_x \sigma_{xx} + \partial_z \sigma_{zx}\right)$   $= \partial_x \int_0^{z_0} dz \sigma_{xx}(x, z) + \sigma_{zx}(x, z_0)$ 

normalized distribution of wall force  $\int_{0}^{z_{0}}dz[g_{x}^{w}(x,z)/G_{x}^{w}(x)]=1$ 

The Generalized Navier boundary condition

$$\widetilde{G}_x^w = -\beta v_x^{slip} \qquad \qquad \widetilde{G}_x^w + \widetilde{G}_x^f = 0$$

The stress in the immiscible two-phase fluid:viscous partnon-viscous part $\sigma_{zx} = \eta [\partial_z v_x + \partial_x v_z] + \sigma_{zx}^Y$ interfacial forceGNBC from<br/>continuum deduction $\beta v_x^{slip} = \widetilde{G}_x^f = \widetilde{\sigma}_{zx} = \sigma_{zx}^{visc} + \widetilde{\sigma}_{zx}^Y$ 

static Young component subtracted
>>> uncompensated Young stress
A tangential force arising from
the deviation from Young's equation

$$\widetilde{\sigma}_{zx}^{Y} = \sigma_{zx}^{Y} - \sigma_{zx}^{0}$$

 $\int_{\text{int}} \mathrm{d}x \widetilde{\sigma}_{zx}^{Y} = \gamma \cos \theta_d - \gamma \cos \theta_s \neq 0$ 



 $\sigma_{zx}^{r}$  obtained by subtracting the Newtonian viscous component

solid circle: **static** symmetric solid square: **static** asymmetric  $\sigma_{zx}^{0}$ :

 $\sigma_{zx}^{Y}$ : empty circle: **dynamic** symmetric empty square: **dynamic** asymmetric



Slip driven by uncompensated Young stress + shear viscous stress

**Uncompensated Young Stress** missed in the Navier B. C.

• Net force due to hydrodynamic deviation from static force balance (Young's equation)

$$\int_{\text{int}} dx \tilde{\sigma}_{zx}^{Y} = \gamma \cos \theta_d - \gamma \cos \theta_s = \gamma \cos \theta_d + \gamma_2 - \gamma_1 \neq 0$$

- **NBC** not capable of describing the motion of contact line
- Away from the CL, the GNBC implies NBC for single phase flows.

### **Continuum Hydrodynamic Model:**

- Cahn-Hilliard (Landau) free energy functional
- Navier-Stokes equation
- Generalized Navier Boudary Condition (B.C.)
- Advection-diffusion equation
- First-order equation for relaxation of  $\phi$  (B.C.) supplemented with

 $\nabla \cdot \mathbf{v} = 0$  incompressibility

 $v_n = 0$  impermeability B.C.

 $J_n \propto \partial_n \mu = 0$  impermeability B.C.

Phase field modeling for a two-component system

$$\mathscr{F}_{CH}[\phi(\mathbf{r})] = \int d\mathbf{r} \left[ \frac{K}{2} (\nabla \phi)^2 + \left( -\frac{r}{2} \phi^2 + \frac{u}{4} \phi^4 \right) \right]$$
  
interfacial thickness  $\xi = \sqrt{K/r}$ ,  
interfacial tension  $\gamma = 2\sqrt{2r^2\xi}/3u$ ,  
two homogeneous equilibrium phases  
 $\phi_{\pm} = \pm \sqrt{r/u} = \pm 1$ 

total free energy 
$$F = \mathscr{F}[\phi] + \int dS[\gamma_{fs}(\phi)]$$
  
 $\delta \left\{ \mathscr{F}[\phi] + \int dS[\gamma_{fs}(\phi)] \right\} = \int d\mathbf{r}[\mu\delta\phi] + \int dS[L\delta\phi],$   
 $\mu = \delta\mathscr{F}/\delta\phi = -K\nabla^2\phi + \partial f(\phi)/\partial\phi$   
 $L = K\partial_n\phi + \partial\gamma_{fs}(\phi)/\partial\phi$  *n*: outward pointing surface normal

# CH free energy functional

 $F = \int d\mathbf{r} \left[ \frac{1}{2} K (\nabla \phi)^2 + f(\phi) \right] \text{ with } f(\phi) = -\frac{1}{2} r \phi^2 + \frac{1}{4} u \phi^4.$ 

Two equilibrium phases:  $\phi_{\pm} = \pm \sqrt{r/u}$  where  $\partial f/\partial \phi = 0$ 

#### Chemical potential

$$\mu = \frac{\delta F}{\delta \phi} = -K\nabla^2 \phi - r\phi + u\phi^3$$

Continuity equation

Diffusive current

$$\frac{D\phi}{Dt} = \frac{\partial\phi}{\partial t} + \mathbf{v} \cdot \nabla\phi = -\nabla \cdot \mathbf{J} \qquad \qquad \mathbf{J} = -M\nabla\mu$$

#### Interfacial tension

Consider a flat interface parallel to the xy plane

Constant chemical potential:  $-K\partial_z^2\phi - r\phi + u\phi^3 = \text{constant}$  $\lim_{z\to\pm\infty}\phi = \phi_{\pm}$  and  $\lim_{z\to\pm\infty}\mu = 0$  (boundary conditions)

Interfacial profile  $\phi_0(z) = \phi_+ \tanh \frac{z}{\sqrt{2\xi}}$ Interfacial thickness  $\xi = \sqrt{K/r}$ First integral:  $-\frac{1}{2}K(\partial_z \phi)^2 + f(\phi) = C$ , where the integral constant C equals  $f(\phi_{\pm})$ .  $\gamma = \int dz \left[\frac{1}{2}K(\partial_z \phi)^2 + f(\phi) - f(\phi_{\pm})\right] = \int dz K(\partial_z \phi)^2$ 

$$\gamma = \frac{K\phi_{\pm}^2}{\sqrt{2}\xi} \int d\bar{z} \cosh^{-4}\bar{z} = \frac{2\sqrt{2}K\phi_{\pm}^2}{3\xi} = \frac{2\sqrt{2}r^2\xi}{3u}$$

$$\mathcal{F}_{CH}[\phi(\mathbf{r})] = \int d\mathbf{r} \left[ \frac{K}{2} \left( \nabla \phi \right)^2 + \left( -\frac{r}{2} \phi^2 + \frac{u}{4} \phi^4 \right) \right]$$

$$\rho \left[ \frac{\partial \mathbf{v}}{\partial t} + (\mathbf{v} \cdot \nabla) \mathbf{v} \right] = -\nabla p + \nabla \cdot \sigma^{v} + \mu \nabla \phi + \mathbf{f}_{e}$$

$$\sigma^{v} = \eta \left[ (\nabla \mathbf{v}) + (\nabla \mathbf{v})^{T} \right]$$

$$\beta(\phi) v_{\tau}^{slip} = -\eta (\partial_{n} v_{\tau} + \partial_{\tau} v_{n}) + L(\phi) \partial_{\tau} \phi$$

$$\frac{\partial \phi}{\partial t} + \mathbf{v} \cdot \nabla \phi = M \nabla^{2} \mu \qquad \mu = \delta \mathcal{F}_{CH} / \delta \phi$$

$$\frac{\partial \phi}{\partial t} + v_{\tau} \partial_{\tau} \phi = -\Gamma L(\phi) \qquad L(\phi) = K \partial_{n} \phi + \partial \gamma_{fs}(\phi) / \partial \phi$$

supplemented with

$$\nabla \cdot \mathbf{v} = 0 \qquad v_n = 0 \qquad J_n \propto \partial_n \mu = 0$$

# **GNBC**: an equation of tangential force balance

$$-\beta v_x^{slip} + \eta \partial_z v_x - K \partial_z \phi \partial_x \phi + \partial_x \gamma_{fs} = 0$$

$$\widetilde{G}_{x}^{w} + \sigma_{zx}^{visc} + \sigma_{zx}^{Y} + \partial_{x}\gamma_{fs} = 0$$

Dussan and Davis, JFM 65, 71-95 (1974):

- 1. Incompressible Newtonian fluid
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- 3. Impenetrable fluid-fluid interface
- 4. No-slip boundary condition

Stress singularity: the tangential force exerted by the fluid on the solid surface is infinite.

Condition (3) >>> Diffusion across the fluid-fluid interface [Seppecher, Jacqmin, Chen---Jasnow---Vinals, Pismen---Pomeau, Briant---Yeomans]

#### **Condition (4) >>> GNBC**

Stress singularity, i.e., infinite tangential force exerted by the fluid on the solid surface, is removed.

### **Comparison of MD and Continuum Results**

- Most parameters determined from **MD** directly
- M and  $\Gamma$  optimized in fitting the **MD** results for *one* configuration
- All subsequent comparisons are *without adjustable parameters*.

*M* and  $\Gamma$  should not be regarded as fitting parameters, Since they are used to realize the interface <u>impenetrability</u> condition, in accordance with the **MD** simulations.

#### **molecular positions** projected onto the *xz* plane



**Diffusion** versus **Slip** in MD







**symmetric** <u>Couette</u> *V*=0.25 *H*=10.2

**symmetric** <u>Couette</u> *V*=0.275 *H*=13.6



a symmetric case of immiscible Couette flow (V =  $0.25(\epsilon/m)^{1/2}$  and H =  $13.6\sigma$ )



a symmetric case of immiscible Couette flow (V =  $0.05 (\epsilon/m)^{1/2}$  and H = 27.2 $\sigma)$ 



an asymmetric case of immiscible Couette flow  $(V = 0.2(\epsilon/m)^{1/2} \text{ and } H = 13.6\sigma)$ 



an asymmetric case of immiscible Couette flow  $(V = 0.1(\epsilon/m)^{1/2})$  and  $H = 27.2\sigma$ 



Power-law decay of partial slip away from the MCL from <u>complete slip</u> at the MCL to <u>no slip</u> far away, governed by the NBC and the asymptotic *1/r* stress

![](_page_48_Figure_1.jpeg)

### The continuum hydrodynamic model for the moving contact line

A Cahn-Hilliard Navier-Stokes system supplemented with the Generalized Navier boundary condition, first uncovered from molecular dynamics simulations

Continuum predictions in agreement with **MD** results.

Now derived from *the principle of minimum energy dissipation,* for *irreversible* thermodynamic processes (dissipative linear response, Onsager 1931).

Qian, Wang, Sheng, J. Fluid Mech. 564, 333-360 (2006).

Onsager's principle for one-variable irreversible processes

Langevin equation: 
$$\gamma \dot{\alpha} = -\frac{\partial F(\alpha)}{\partial \alpha} + \zeta(t)$$
  
 $\langle \zeta(t)\zeta(t')\rangle = 2\gamma k_B T \delta(t-t')$ 

Fokker-Plank equation for **probability density**  $P(\alpha, t)$ 

$$\frac{\partial P}{\partial t} = D \left[ \frac{\partial^2 P}{\partial \alpha^2} + \frac{1}{k_B T} \frac{\partial}{\partial \alpha} \left( \frac{\partial F}{\partial \alpha} P \right) \right]_{\text{Einstein relation } \gamma D = k_B T}$$

**Transition probability**  $P_2(\alpha', t + \Delta t; \alpha, t)$ 

$$P_2(\alpha', t + \Delta t; \alpha, t) = \frac{1}{\sqrt{4\pi D\Delta t}} \exp\left[-\frac{(\alpha' - \alpha)^2}{4D\Delta t}\right] \exp\left[-\frac{F(\alpha') - F(\alpha)}{2k_B T}\right]$$

The most probable course derived from minimizing

$$A = \frac{\gamma(\alpha' - \alpha)^2}{2\Delta t} + [F(\alpha') - F(\alpha)] \approx \left[\frac{\gamma}{2}\dot{\alpha}^2 + \frac{\partial F(\alpha)}{\partial\alpha}\dot{\alpha}\right]\Delta t$$
  
Euler-Lagrange equation:  $\gamma\dot{\alpha} = \frac{\gamma(\alpha' - \alpha)}{\Delta t} = -\frac{\partial F(\alpha)}{\partial\alpha}$ 

Probability~
$$e^{-Action}$$

Onsager 1931 Onsager-Machlup 1953

$$\langle \zeta(t)\zeta(t')\rangle = 2\gamma k_B T\delta(t-t')$$

Action = 
$$\frac{1}{4\gamma k_{\rm B}T} \int dt [\zeta(t)]^2 = \frac{1}{4\gamma k_{\rm B}T} \int dt \left[ \gamma \dot{\alpha} + \frac{\partial F(\alpha)}{\partial \alpha} \right]^2$$

for the statistical distribution of the noise (random force)

$$\frac{1}{4\gamma k_{\rm B}T} \left[ \gamma \dot{\alpha} + \frac{\partial F(\alpha)}{\partial \alpha} \right]^2 \Delta t \rightarrow \\ \frac{\gamma \dot{\alpha}^2}{4k_{\rm B}T} \Delta t + \frac{1}{2k_{\rm B}T} \frac{\partial F(\alpha)}{\partial \alpha} \dot{\alpha} \Delta t = \frac{\Delta \alpha^2}{4D\Delta t} + \frac{1}{2k_{\rm B}T} \frac{\partial F(\alpha)}{\partial \alpha} \Delta \alpha$$

The principle of minimum energy dissipation (Onsager 1931)

$$\sum_{j=1}^{n} \rho_{ij} \dot{\alpha}_j = -\frac{\partial F(\alpha_1, \cdots, \alpha_n)}{\partial \alpha_i}, \quad (i = 1, \cdots, n)$$

Balance of the viscous force and the "elastic" force from **a variational principle** 

$$\delta \left[ \Phi(\dot{\alpha},\dot{\alpha}) + \dot{F}(\alpha,\dot{\alpha}) \right] = \sum_{i=1}^{n} \left( \frac{\partial \Phi}{\partial \dot{\alpha}_{i}} + \frac{\partial F}{\partial \alpha_{i}} \right) \delta \dot{\alpha}_{i} = 0$$

$$\Phi(\dot{\alpha},\dot{\alpha}) \equiv \frac{1}{2}\sum_{i,j}\rho_{ij}\dot{\alpha}_i\dot{\alpha}_j$$

**dissipation-function**, positive definite and quadratic in the rates, half the rate of energy dissipation

$$\dot{F}(\alpha, \dot{\alpha}) \equiv \sum_{i=1}^{n} \frac{\partial F(\alpha_1, \cdots, \alpha_n)}{\partial \alpha_i} \dot{\alpha}$$

rate of change of the free energy

Minimum dissipation theorem for incompressible single-phase flows (*Helmholtz* 1868)

Consider a flow confined by solid surfaces. *Stokes equation:* 

$$-\nabla p + \eta \nabla^2 \mathbf{v} = 0$$

derived as *the Euler-Lagrange equation* by minimizing the functional

$$R_v\left[\mathbf{v}\right] = \int d\mathbf{r} \left[\frac{\eta}{2}(\partial_i v_j + \partial_j v_i)^2\right]$$

for the rate of **viscous dissipation** in the bulk.

The values of the velocity <u>fixed</u> at the solid surfaces!

Taking into account the dissipation due to the fluid slipping at the fluid-solid interface

$$R_{s}\left[\mathbf{v}\right] = \int dS \left[\beta \left(v_{\tau}^{slip}\right)^{2}\right]$$

Total rate of **dissipation** due to **viscosity** in the bulk and **slipping** at the solid surface

$$R_1\left[\mathbf{v}\right] = \int d\mathbf{r} \left[\frac{\eta}{2} (\partial_i v_j + \partial_j v_i)^2\right] + \int dS \left[\beta \left(v_\tau^{slip}\right)^2\right]$$

One more *Euler-Lagrange equation* at the solid surface with boundary values of the velocity subject to variation

Navier boundary condition:

$$\beta v_{\tau}^{slip} = -\sigma_{n\tau}^{visc} = -\eta (\partial_n v_{\tau} + \partial_{\tau} v_n)$$

From velocity differential to velocity difference  $\nabla \mathbf{V} \rightarrow v^{slip}$ 

Transport coefficient: from viscosity  $\eta$  to slip coefficient  $\beta$ 

$$\eta = \frac{1}{V} \frac{1}{k_{\rm B}T} \int_0^\infty dt \left\langle F_{\tau}(t) F_{\tau}(0) \right\rangle_{eq} \qquad \text{Green-Kubo formula}$$
$$\beta = \frac{1}{S} \frac{1}{k_{\rm B}T} \int_0^\infty dt \left\langle F_{\tau}(t) F_{\tau}(0) \right\rangle_{eq}$$
J.-L. Barrat and L. Bocquet, *Faraday Discuss.* **112**, 119 (1999).

Auto-correlation of the tangential force over atomistically rough surface: Molecular potential roughness

### Generalization to immiscible two-phase flows

A Landau free energy functional to stabilize the interface separating the two immiscible fluids

$$\mathcal{F}[\phi(\mathbf{r})] = \int d\mathbf{r} \left[\frac{K}{2} \left(\nabla\phi\right)^2 + f(\phi)\right]$$

double-well structure for  $f(\phi)$ 

Interfacial free energy per unit area at the fluid-solid interface

$$\gamma_{fs}(\phi)$$

Variation of the total free energy  $F = \mathcal{F}[\phi] + \int dS \left[\gamma_{fs}(\phi)\right]$ 

$$\delta \left\{ \mathcal{F}[\phi] + \int dS \left[ \gamma_{fs}(\phi) \right] \right\} = \int d\mathbf{r} \left[ \mu \delta \phi \right] + \int dS \left[ L \delta \phi \right]$$

for defining  $\mu$  and L.

$$\mu$$
 and  $L$ :  

$$\mu = \delta \mathcal{F} / \delta \phi = -K \nabla^2 \phi + \partial f(\phi) / \partial \phi$$
 chemical potential  
in the bulk:  

$$L(\phi) = K \partial_n \phi + \partial \gamma_{fs}(\phi) / \partial \phi$$
 at the fluid-solid interface

Deviations from the equilibrium measured by  $\nabla \mu$  in the bulk and *L* at the fluid-solid interface.

Minimizing the total free energy subject to the conservation of  $\phi$  leads to the equilibrium conditions:

$$\mu = Const.$$
  $L = 0$  (Young's equation)

For small perturbations away from the two-phase equilibrium, **the additional rate of dissipation** (due to the coexistence of the two phases) arises from system responses (rates) that are linearly proportional to the respective perturbations/deviations.

#### **Dissipation function (half the total rate of energy dissipation)**

$$\Phi = \int d\mathbf{r} \left[ \frac{\eta}{4} (\partial_i v_j + \partial_j v_i)^2 \right] + \int dS \left[ \frac{\beta}{2} \left( v_\tau^{slip} \right)^2 \right] + \int d\mathbf{r} \left[ \frac{\mathbf{J}^2}{2M} \right] + \int dS \left[ \frac{\dot{\phi}^2}{2\Gamma} \right]$$
$$\Phi = \frac{1}{2} R_2 = \frac{1}{2} (R_1 + R_\phi) = \frac{1}{2} (R_v + R_s + R_d + R_r)$$

**Rate of change of the free energy**  

$$\dot{F} = \int d\mathbf{r} \left[ \mu \frac{\partial \phi}{\partial t} \right] + \int dS \left[ L \frac{\partial \phi}{\partial t} \right] \qquad \text{kinematic transport of } \phi \\
\frac{\partial \phi}{\partial t} = \dot{\phi} - \mathbf{v} \cdot \nabla \phi \\
\int d\mathbf{r} \left[ \mu \dot{\phi} \right] = \int d\mathbf{r} \left[ -\mu \nabla \cdot \mathbf{J} \right] \qquad \text{continuity equation for } \phi \\
\int d\mathbf{r} \left[ \nabla \cdot (\mu \mathbf{J}) \right] = \int dS \left[ \mu J_n \right] = 0 \qquad \text{impermeability B.C.} \\
\dot{F} = \int d\mathbf{r} \left[ \nabla \mu \cdot \mathbf{J} - \mu \mathbf{v} \cdot \nabla \phi \right] + \int dS \left[ L(\dot{\phi} - v_\tau \partial_\tau \phi) \right]$$

Minimizing 
$$\Phi + F$$

$$\int d\mathbf{r} \left[ \frac{\eta}{4} (\partial_i v_j + \partial_j v_i)^2 \right] + \int dS \left[ \frac{\beta}{2} \left( v_\tau^{slip} \right)^2 \right] + \int d\mathbf{r} \left[ \frac{\mathbf{J}^2}{2M} \right] + \int dS \left[ \frac{\dot{\phi}^2}{2\Gamma} \right] + \int d\mathbf{r} \left[ \nabla \mu \cdot \mathbf{J} - \mu \mathbf{v} \cdot \nabla \phi \right] + \int dS \left[ L(\dot{\phi} - v_\tau \partial_\tau \phi) \right].$$

with respect to the rates  $\{\mathbf{v}, \mathbf{J}, \phi\}$  yields

 $\phi = \frac{-\tau}{\partial t} + v_{\tau} \partial_{\tau} \phi = -\Gamma L(\phi)$ . 1<sup>st</sup> order relaxational equation