

The constrained TV-flow

S. Moll

Based on joint works with

L. Giacomelli (U. Roma I),
M. Łasica (U. Roma I) and
J. Mazón (U. Valencia)

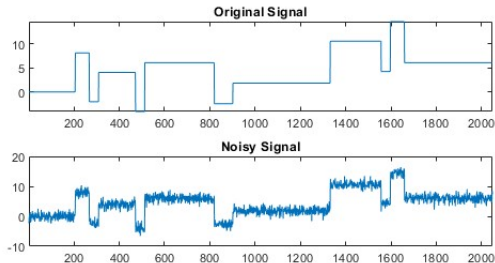


VNIVERSITAT
ID VALÈNCIA

Denoising problem (simplified).

Let $u_0 : \Omega \subset \mathbb{R}^N \rightarrow \mathbb{R}^+$ be a given noisy (observed) image. Suppose that the observed image differs from the real image $u : \Omega \subset \mathbb{R}^N \rightarrow \mathbb{R}^+$ by a gaussian noise n with known variance; i.e.

$$u_0 = u + n, \quad \int_{\Omega} n dx = 0 \quad \int_{\Omega} n^2 dx = \sigma^2 \quad \Rightarrow u?$$



The use of total variation in image processing.

Let $\mathbf{u} : \Omega \subset \mathbb{R}^m \rightarrow \mathbb{R}^N$,

$$E[\mathbf{u}] = \int_{\Omega} d|D\mathbf{u}| := \sup \left\{ \int_{\Omega} u^{\ell} \operatorname{div} \varphi^{\ell} dx : \varphi \in [C_0^1(\Omega; \mathbb{R}^N)]^m, \|\varphi\|_{\infty} \leq 1 \right\}.$$

The use of total variation in image processing.

Let $\mathbf{u} : \Omega \subset \mathbb{R}^m \rightarrow \mathbb{R}^N$,

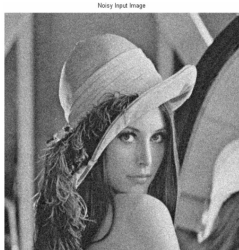
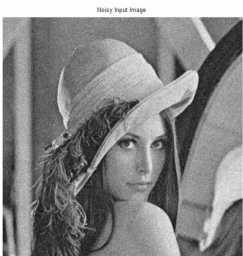
$$E[\mathbf{u}] = \int_{\Omega} d|D\mathbf{u}| := \sup \left\{ \int_{\Omega} u^{\ell} \operatorname{div} \varphi^{\ell} dx : \varphi \in [C_0^1(\Omega; \mathbb{R}^N)]^m, \|\varphi\|_{\infty} \leq 1 \right\}.$$

Some features:

- It allows discontinuities (minimizers can be discontinuous).
- It is a convex functional.
- Applied to indicator functions, it gives the perimeter.

L. Rudin, S. Osher, E. Fatemi (1990)

$$\min \left\{ \int_{\Omega} d|Du| : u \in BV(\Omega), \int_{\Omega} u = \int_{\Omega} u_0, \int_{\Omega} (u - u_0)^2 = \sigma^2 \right\}$$



Need for TV into manifolds

Color images: B.Tang, G. Sapiro, V. Caselles '00.

- Given $I : \Omega \subset \mathbb{R}^N \rightarrow \mathbb{R}^3$ a noisy image, separate it into its **brightness**
 $M : \Omega \rightarrow \mathbb{R}^+$

$$M(x) = \sqrt{\sum_{i=1}^3 I_i(x)^2}$$

and **chromaticity** $\mathbf{u} : \Omega \rightarrow (S^2)^+$,

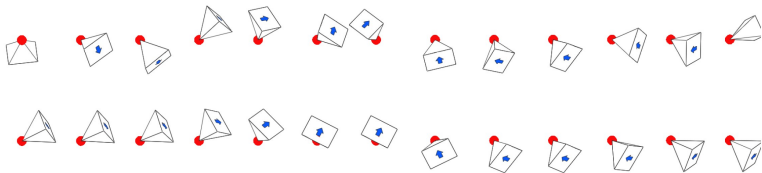
$$\mathbf{u}(x) := \frac{I(x)}{M(x)}.$$

- Denoise the brightness by scalar TV-flow.
- Denoise the chromaticity by the constrained TV-flow ($(S^2)^+$ -valued).
- Recover the denoised image.

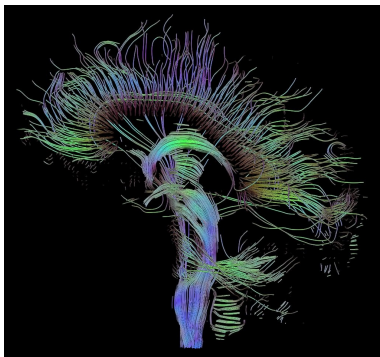
Example of denoising.



- **Optical flow:** $\mathbf{u} : \Omega \subset \mathbb{R}^2 \rightarrow S^2$.
- **LCh-color space:** $\mathbf{u} : \Omega \subset \mathbb{R}^2 \rightarrow \mathbb{R} \times S^1$.
- **Camera trajectories:** $\mathbf{u} : [0, T] \rightarrow SE(3)$



- **Brain images:** $u : \Omega \rightarrow \mathbb{P}(3)^+$



p-harmonic functions and p-harmonic flows

Let $\Omega \subset \mathbb{R}^m$ and $\mathbf{u} : \Omega \rightarrow \mathcal{N}$, where (\mathcal{N}, g) is a smooth manifold. We embed isometrically \mathcal{N} in \mathbb{R}^N and denote again $\mathbf{u} := \iota \circ \mathbf{u}$ and consider

$$|\nabla \mathbf{u}|^2 := u_{x_j}^i{}^2$$

Definition

The p -energy of \mathbf{u} is defined as $E_p(\mathbf{u}) := \frac{1}{p} \int_{\Omega} |\nabla \mathbf{u}|^p dx$

Definition

The p -harmonic functions are the regular critical points of E_p :

$$0 = \frac{\delta E_p}{\delta \mathbf{u}} = -\pi_{\mathbf{u}} \left(-\operatorname{div}(|\nabla \mathbf{u}|^{p-2} \nabla \mathbf{u}) \right), \quad \mathbf{u}(\Omega) \subseteq \mathcal{N}$$

The p -harmonic flow is the formal gradient descent flow in L^2 of E_p :

$$\frac{\partial \mathbf{u}}{\partial t} = -\frac{\delta E_p}{\delta \mathbf{u}}, \quad \mathbf{u}(\Omega) \subseteq \mathcal{N} \quad (t, x) \in (0, T) \times \Omega$$

Some known results.

- Non-positive sectional curvature:
 - $p = 2$ [Eels-Sampson, '64]. Existence of global solutions to the flow and convergence of a subsequence to a harmonic map. The heat flow solved the homotopy problem.
 - $p > 1$ [Fardoun-Regbaoui '02]. Existence and uniqueness, regularity and convergence to a p -harmonic map.
- $\mathcal{N} = S^{N-1}$
 - $p = 2$, [Chen-Struwe '89] Existence of a weak solution possibly singular in a finite number of points of $D^2 \times [0, +\infty[$. Blow up in finite time [Chan-Ding-Ye '92]
 - $p > 2$: [Chen-Hong-Hungerbuehler '94].
 - $1 < p < 2$: [Liu '97], [Misawa '02].
 - Blow-up in finite time, $p \notin \{1, 2\}$ [Iagar-M, '14]
 - Uniqueness? NOT in general [Bertsch-Dal Passo, van der Hout '02].

The case $p = 1$

- Regular solutions
 - Smooth and small data (periodic) [Giga & coll. '03–]
 - Lipschitz data M. Łasica, L. Giacomelli, S.M. '17.
- BV -solutions in the case of $\mathcal{N} = S^{N-1}$.
 - Piecewise constant evolution [Giga & coll. '05–]
 - Rotational symmetry, blow-up (Dirichlet) [DalPasso-Giacomelli-M., '08-'10]
 - S^1 . Existence and uniqueness [Giacomelli, Mazón, S. M. '13]
 - Existence in the case $(S^{N-1})^+$. [Giacomelli, Mazón, M. '14]
- BV -solutions in the case \mathcal{N} is a smooth curve in the plane. [DiCastro-Giacomelli '16]
- BV -solutions for 1-D domain. Giacomelli, Łasica, M. '18

The regular case

$$\mathbf{u}_t = \pi_{\mathbf{u}} \operatorname{div} \left(\frac{\nabla \mathbf{u}}{|\nabla \mathbf{u}|} \right) \quad (\text{TVF})$$

The meaning of $\frac{\nabla \mathbf{u}}{|\nabla \mathbf{u}|}$ as a multivalued function:

$$\frac{\nabla \mathbf{u}}{|\nabla \mathbf{u}|} : (t, \mathbf{x}) \mapsto \begin{cases} \frac{\nabla \mathbf{u}(t, \mathbf{x})}{|\nabla \mathbf{u}(t, \mathbf{x})|} & \text{if } \nabla \mathbf{u}(t, \mathbf{x}) \neq \mathbf{0} \\ B(0, 1) \subset \mathbb{R}^m \times T_{\mathbf{u}(t, \mathbf{x})} \mathcal{N} & \text{if } \nabla \mathbf{u}(t, \mathbf{x}) = \mathbf{0} \end{cases}$$

Definition

Let $T \in]0, \infty]$. We say that $\mathbf{u} \in W^{1,2}([0, T[\times \Omega, \mathcal{N})$ with $\nabla \mathbf{u} \in L_{loc}^\infty([0, T[\times \overline{\Omega}, \mathbb{R}^{m \cdot N})$ is a (regular) solution to (TVF) if there exists $\mathbf{Z} \in L^\infty([0, T[\times \Omega, \mathbb{R}^m \times \mathbb{R}^N)$ with $\operatorname{div} \mathbf{Z} \in L_{loc}^2([0, T[\times \overline{\Omega}, \mathbb{R}^N)$ satisfying \mathcal{L}^{1+m} - a. e. in $]0, T[\times \Omega$.

$$\mathbf{Z} \in \frac{\nabla \mathbf{u}}{|\nabla \mathbf{u}|},$$

$$\mathbf{u}_t = \pi_{\mathbf{u}} \operatorname{div} \mathbf{Z}$$

Homogeneous Neumann boundary condition:

$$\nu^\Omega \cdot \mathbf{Z} = \mathbf{0}, \quad \mathcal{L}^1 \otimes \mathcal{H}^{m-1} - \text{a. e. in }]0, T[\times \partial\Omega.$$

Existence and regularity

$$\mathcal{K}_{\mathcal{N}} = \sup_{\mathbf{p} \in \mathcal{N}} \max_{\mathbf{v}, \mathbf{w} \in T_{\mathbf{p}} \mathcal{N} \setminus \{0\}} \frac{\mathbf{v} \cdot \mathcal{R}_{\mathbf{p}}^{\mathcal{N}}(\mathbf{v}, \mathbf{w}) \mathbf{w}}{|\mathbf{v}|^2 |\mathbf{w}|^2 - (\mathbf{v} \cdot \mathbf{w})^2}.$$

Theorem

Suppose that Ω is convex, the embedding is closed and $\sup \mathcal{K}_{\mathcal{N}} < \infty$.

Given $\mathbf{u}_0 \in W^{1,\infty}(\Omega, \mathcal{N})$, there exists $T = T(\mathcal{N}, \|\nabla \mathbf{u}_0\|_{L^\infty})$ and a regular solution $\mathbf{u} \in L^\infty(]0, T[, W^{1,\infty}(\Omega, \mathcal{N}))$ satisfying

$$\operatorname{ess\,sup}_{t \in [0, T[} \int_{\Omega} |\nabla \mathbf{u}(t, \cdot)| + \int_0^T \int_{\Omega} \mathbf{u}_t^2 \leq \int_{\Omega} |\nabla \mathbf{u}_0|,$$

and

$$\mathbf{u}(0, \cdot) = \mathbf{u}_0$$

The approximate system

$$\left\{ \begin{array}{ll} \mathbf{u}_t^\varepsilon = \pi_{\mathbf{u}^\varepsilon} \operatorname{div} \left(\frac{\nabla \mathbf{u}^\varepsilon}{\sqrt{\varepsilon^2 + |\nabla \mathbf{u}^\varepsilon|^2}} \right) & \text{in }]0, T[\times \Omega \\ \nu^\Omega \cdot \nabla \mathbf{u}^\varepsilon = 0 & \text{in }]0, T[\times \partial\Omega \\ \mathbf{u}^\varepsilon(0, \cdot) = \mathbf{u}_0 & \end{array} \right.$$

Theorem

Suppose that Ω is smooth and convex, that $\sup \mathcal{K}_{\mathcal{N}} < \infty$. Let $\mathbf{u}_0 \in C^{3+\alpha}(\Omega, \mathcal{N})$ satisfy Neumann b. c. + a compatibility condition. Then, There exist $T_\dagger = T_\dagger(\|\nabla \mathbf{u}_0^\varepsilon\|_{L^\infty}, \mathcal{K}_{\mathcal{N}}) > 0$, and unique solution

$$\mathbf{u}^\varepsilon \in C_{loc}^{\frac{3+\alpha}{2}, 3+\alpha}(\overline{\Omega}_{[0, T_\dagger[}, \mathcal{N})$$

to the system with initial datum \mathbf{u}_0 .

Sketch of proof.

- Step 1. Uniform bounds: Let $\mathbf{u}^\varepsilon \in C^{\frac{3+\alpha}{2}, 3+\alpha}(\overline{\Omega}_{[0,T[}, \mathcal{N})$ be a solution. Then,

- (i) Energy estimate:

$$\sup_{t \in [0, T[} \int_{\Omega} \sqrt{\varepsilon^2 + |\nabla \mathbf{u}^\varepsilon|^2} + \int_0^T \int_{\Omega} \mathbf{u}_t^2 \leq \int_{\Omega} \sqrt{\varepsilon^2 + |\nabla \mathbf{u}_0^\varepsilon|^2}.$$

- (ii) Parabolic Bochner formula:

$$\frac{1}{2} \frac{d}{dt} |\nabla \mathbf{u}|^2 = \operatorname{div}(\nabla \mathbf{u} \cdot \nabla Z) - (\pi_{\mathbf{u}} \nabla^2 \mathbf{u}) : \nabla Z + Z_i \cdot \mathcal{R}_{\mathbf{u}}^{\mathcal{N}}(\mathbf{u}_{x^i}, \mathbf{u}_{x^j}) \mathbf{u}_{x^j}.$$

- (iii) Lipschitz bound:

$$\|\sqrt{\varepsilon^2 + |\nabla \mathbf{u}^\varepsilon(t \cdot)|^2}\|_{L^\infty} \leq \frac{\sqrt{\varepsilon^2 + |\nabla \mathbf{u}_0|^2}}{1 - t \mathcal{K}_N \sqrt{\varepsilon^2 + |\nabla \mathbf{u}_0|^2}}$$

- Step 2. Unconstraining the problem:

- (i) Construct a totally geodesic embedding ι of (\mathcal{N}, g) into a Riemannian manifold (\mathbb{R}^N, h) . Then,

$$u_t^i = \operatorname{div} \frac{\nabla u^i}{\sqrt{\varepsilon^2 + |\nabla \mathbf{u}|_h^2}} + \frac{1}{\sqrt{\varepsilon^2 + |\nabla \mathbf{u}|_h^2}} \Gamma_{jk}^i(\mathbf{u}) u_{x_l}^j u_{x_l}^k, \quad i = 1, \dots, N,$$

- (ii) Local existence and uniqueness of solution

$\mathbf{u}^\varepsilon \in C^{1+\frac{\alpha}{2}}([0, T_0], L^p(\Omega, \mathbb{R}^N)) \cap C^{\frac{\alpha}{2}}([0, T_0], W^{2,p}(\Omega, \mathbb{R}^N))$ with a $T_0 > 0$ for $\mathbf{u}_0 \in C^{2+\alpha}(\overline{\Omega}, \mathcal{N})$ satisfying Neumann b. c. (Acquistapace and Terreni)

- (iii) Hölder regularity+maximal time of existence by classical results.

- Step 3. The solution stays into \mathcal{N} by uniqueness.

Sketch of passing with $\varepsilon \rightarrow 0$

- Case $u_0 \in C^{3+\alpha}(\Omega; \mathcal{N})$ + compatibility conditions. Since the bounds do not depend on ε , there exists a subsequence \mathbf{u}_k from (\mathbf{u}^ε) such that

$$\begin{cases} \mathbf{u}_k \rightarrow \bar{\mathbf{u}} & \text{in } C([0, T] \times \bar{\Omega}) \\ \nabla \mathbf{u}_k \rightharpoonup \nabla \bar{\mathbf{u}} & \text{weakly in } L^2([0, T] \times \Omega) \end{cases} .$$

Then, one can pass to the limit in the weak formulation in extrinsic coordinates:

$$\mathbf{u}_t^\varepsilon = \operatorname{div} \frac{\nabla \mathbf{u}^\varepsilon}{|\nabla \mathbf{u}^\varepsilon|} + A(\mathbf{u}^\varepsilon)(\mathbf{Z}^\varepsilon, \nabla \mathbf{u}^\varepsilon),$$

- General case: By approximation with $C^\infty(\bar{\Omega}; \mathcal{N})$ functions.
- A general convex domain.

Theorem

Suppose that $\mathbf{u}_1, \mathbf{u}_2 \in L^\infty(]0, T[, W^{1,\infty}(\Omega, \mathcal{N}))$ are two regular solutions to (TVF) such that $\mathbf{u}_1(0, \cdot) = \mathbf{u}_2(0, \cdot) = \mathbf{u}_0$. Then $\mathbf{u}_1 \equiv \mathbf{u}_2$.

Theorem

Given $\mathbf{p}_0 \in \mathcal{N}$ and $\mathbf{u}_0 \in W^{1,\infty}(\Omega)$ such that $\mathbf{u}_0(\Omega) \subset \overline{B_g(\mathbf{p}_0, R)}$, $R > 0$.

Then, there exist:

- A constant $R_*(\mathbf{p}_0)$ such that if $R < R_*$, then $\mathbf{u}(t, \Omega) \subset \overline{B_g(\mathbf{p}_0, R)}$, for all $t > 0$.
- constants $0 < \tilde{R}_*(\mathbf{p}_0) < R_*$, $C(\mathbf{p}_0)$ and $u_* \in \mathcal{N}$ such that, if $R < \min\{\tilde{R}, \frac{T}{C}\}$, then $u(t, \cdot) \equiv u_*$ for $t \in]CR, T[$.

Finite extinction time. Sketch of proof.

Consider the barycenter

$$m(t) := \operatorname{argmin}_{w \in \mathcal{N}} \int_{\Omega} d(u(x), w)^2 dx.$$

Then, consider geodesic polar coordinates centered at $m(t)$ and estimate

$$\frac{1}{2} \frac{d}{dt} \int_{\Omega} d(\mathbf{u}(x, t), m(t))^2 dx = \frac{1}{2} \frac{d}{dt} \int_{\Omega} (u^r)^2 dx$$

using the equation in this coordinates, , integration by parts and Poincaré-Sobolev inequality, obtaining

$$\frac{1}{2} \frac{d}{dt} \int_{\Omega} d(\mathbf{u}(x, t), m(t))^2 dx \leq -CR^{\frac{2}{m}-1} \left(\frac{1}{2} \int_{\Omega} d(\mathbf{u}(x, t), m(t))^2 dx \right)^{1-\frac{1}{m}}.$$

□

Theorem

Suppose that Ω is convex and $\mathcal{K}_{\mathcal{N}} \leq 0$ (or suppose that $m = 1$). Let $\mathbf{u}_0 \in W^{1,2}(\Omega, \mathcal{N}) \cap L^\infty(\Omega, \mathcal{N})$. There exists a *global* regular solution. Furthermore, if $\mathbf{u}_0 \in W^{1,p}(\Omega, \mathcal{N})$, $2 \leq p \leq \infty$, then $\mathbf{u} \in L^\infty(]0, \infty[, W^{1,p}(\Omega, \mathcal{N}))$ with

$$\operatorname{ess\,sup}_{t>0} \|\nabla \mathbf{u}(t, \cdot)\|_{L^p(\Omega)} \leq \|\nabla \mathbf{u}_0\|_{L^p(\Omega)}.$$

The homotopy problem

Given (\mathcal{M}, γ) and (\mathcal{N}, g) two Riemannian manifolds and $\mathbf{u}_0 : \mathcal{M} \rightarrow \mathcal{N}$, is there a weak 1-harmonic map \mathbf{u}_* homotopic to \mathbf{u}_0 ?

$$TV_{\mathcal{M}}^{\mathcal{N}}[\mathbf{u}] := \int_{\mathcal{M}} |d\mathbf{u}|_{\gamma} d\mu_{\gamma}$$

$$(TVF) : \mathbf{u}_t = \pi_{\mathbf{u}} \left(\operatorname{div}_{\gamma} \frac{d\mathbf{u}}{|d\mathbf{u}|} \right)$$

$$\frac{d\mathbf{u}}{|d\mathbf{u}|_{\gamma}} : (t, \mathbf{x}) \mapsto \begin{cases} \frac{d\mathbf{u}(t, \mathbf{x})}{|d\mathbf{u}(t, \mathbf{x})|_{\gamma}} & \text{if } d\mathbf{u}(t, \mathbf{x}) \neq 0 \\ B_{\gamma}(0, 1) \subset T_{\mathbf{x}}^* \mathcal{M} \times T_{\mathbf{u}(t, \mathbf{x})} \mathcal{N} & \text{if } d\mathbf{u}(t, \mathbf{x}) = 0. \end{cases}$$

Definition

Let $T \in]0, \infty]$. We say that

$$\mathbf{u} \in W_{loc}^{1,2}([0, T[\times \mathcal{M}, \mathcal{N}) \text{ with } d\mathbf{u} \in L_{loc}^{\infty}([0, T[\times T^* \mathcal{M} \times \mathbb{R}^N)$$

is a solution if there exists $\mathbf{Z} \in L^{\infty}(]0, T[\times T^* \mathcal{M} \times \mathbb{R}^N)$ with $\operatorname{div}_{\gamma} \mathbf{Z} \in L_{loc}^2([0, T[\times \mathcal{M}, \mathbb{R}^N)$ satisfying

$$\mathbf{Z} \in \frac{d\mathbf{u}}{|d\mathbf{u}|_{\gamma}},$$

$$\mathbf{u}_t = \pi_{\mathbf{u}}(\operatorname{div}_{\gamma} \mathbf{Z})$$

\mathcal{L}^{1+m} – a. e. in $]0, T[\times \mathcal{M}$.

$$Ric_{\mathcal{M}} = \min_{\mathbf{p} \in \mathcal{M}} \min_{\mathbf{v}, \mathbf{w} \in T_{\mathbf{p}}\mathcal{M} \setminus \{\vec{0}\}} \frac{Ric_{\mathbf{p}}^{\mathcal{M}}(\mathbf{v}, \mathbf{w})}{|\mathbf{v}|_{\gamma} |\mathbf{w}|_{\gamma}}.$$

Theorem

Let (\mathcal{M}, γ) be a compact, orientable and let (\mathcal{N}, g) be a compact submanifold in \mathbb{R}^N . Given $\mathbf{u}_0 \in W^{1,\infty}(\mathcal{M}, \mathcal{N})$, there exists $T \in]0, \infty]$ and a unique regular solution in $[0, T[$.

If $K_{\mathcal{N}} \leq 0$, the solution exists in $[0, \infty[$.

If $Ric_{\mathcal{M}} \geq 0$, there exists $(t_k) \subset]0, \infty[$, $t_k \rightarrow \infty$, $\mathbf{u}_* \in W^{1,\infty}(\mathcal{M}, \mathcal{N})$ and $\mathbf{Z}_* \in L^{\infty}(T^*\mathcal{M} \times \mathbb{R}^N)$ with $\operatorname{div}_{\gamma} \mathbf{Z}_* \in L^{\infty}(\mathcal{M}, \mathbb{R}^N)$ such that

$$\pi_{\mathbf{u}_*}(\operatorname{div}_{\gamma} \mathbf{Z}_*) = \vec{0}, \quad \mathbf{Z}_* \in \frac{d\mathbf{u}_*}{|d\mathbf{u}_*|_{\gamma}},$$

$$\mathbf{u}(t_k, \cdot) \rightarrow \mathbf{u}_* \text{ in } C(\mathcal{M}, \mathcal{N}).$$

BV-solutions

BV-solution

Proper interpretation of

$$\mathbf{u}_t = \operatorname{div} \left(\frac{D\mathbf{u}}{|D\mathbf{u}|} \right) + A(\mathbf{u}) \left(\frac{D\mathbf{u}}{|D\mathbf{u}|}, D\mathbf{u} \right)$$

for $\mathbf{u} \in BV(\Omega; \mathcal{N})$,?

$$\mathbf{u}_t = \operatorname{div} (\mathbf{Z}) + \mu$$

- Special cases:

$$- \mathcal{N} = \mathbb{S}_+^{n-1}: \quad \mu = \mathbf{u} |\tilde{D}\mathbf{u}| + \frac{\mathbf{u}^*}{|\mathbf{u}^*|} |D^j \mathbf{u}|, \quad (\mathbf{Z}, D\mathbf{u}) = |\mathbf{u}^*| |D\mathbf{u}|$$

$$- \mathcal{N} \subset \mathbb{R}^2: \quad \mu = -\kappa(\mathbf{u}) N(\mathbf{u}) |\tilde{D}\mathbf{u}| + (T(\mathbf{u}_-) - T(\mathbf{u}_+)) \mathcal{H}^{m-1} \llcorner J_{\mathbf{u}}$$

The equation for $\mathcal{N} = S^{N-1}$

$$\mathbf{u}_t = \operatorname{div} \left(\frac{D\mathbf{u}}{|D\mathbf{u}|} \right) + \mathbf{u}|D\mathbf{u}|$$

Approximation. Parabolic regularization.

Lemma (Barrett-Feng-Prohl '08)

Let $\varepsilon > 0$, $T > 0$ and $\alpha > 0$. If $\mathbf{u}_0^\varepsilon \in W^{1,2}(\Omega; \mathbb{S}^{N-1})$, then there exists $\mathbf{u}^\varepsilon \in L^\infty(0, T; W^{1,2}(\Omega; \mathbb{R}^N)) \cap W^{1,2}(0, T; L^2(\Omega; \mathbb{R}^N))$ such that $\mathbf{u}^\varepsilon(0, \cdot) = \mathbf{u}_0^\varepsilon$, $|\mathbf{u}^\varepsilon| = 1$ a.e. in Q_T , and \mathbf{u}^ε is a weak solution to

$$\begin{cases} \mathbf{u}_t^\varepsilon = \pi_{\mathbf{u}^\varepsilon} \operatorname{div}(\mathbf{Z}^\varepsilon) & \text{in } Q_T \\ [\mathbf{Z}^\varepsilon, \nu] = 0 & \text{in } S_T, \end{cases},$$

where $\mathbf{Z}^\varepsilon := \varepsilon^\alpha \nabla \mathbf{u}^\varepsilon + \frac{\nabla \mathbf{u}^\varepsilon}{\sqrt{|\nabla \mathbf{u}^\varepsilon|^2 + \varepsilon^2}}$.

We let

$$\boldsymbol{\mu}^\varepsilon := \varepsilon^\alpha \mathbf{u}^\varepsilon |\nabla \mathbf{u}^\varepsilon|^2 + \mathbf{u}^\varepsilon \frac{|\nabla \mathbf{u}^\varepsilon|^2}{\sqrt{|\nabla \mathbf{u}^\varepsilon|^2 + \varepsilon^2}}$$

With good a-priori estimates and approximation of the initial datum, one can pass to the limit,

$$\mathbf{u}_t - \operatorname{div} \mathbf{Z} = \boldsymbol{\mu} \quad \text{in } [L^2(0, T; C_0(\Omega; \mathbb{R}^N))]',$$

$$\mathbf{Z}^T \mathbf{u} = 0 \quad \text{a.e. in } Q_T,$$

$$\mathbf{u}_t \cdot \mathbf{u} = 0 \quad \text{a.e. in } Q_T,$$

$$\mathbf{u}_t(t) \wedge \mathbf{u}(t) = \operatorname{div}(\mathbf{Z}(t) \wedge \mathbf{u}(t)) \quad \text{in } L^2(\Omega; \Lambda_2(\mathbb{R}^N)) \text{ for a.e. } t \in [0, T].$$

Then,

$$\boldsymbol{\mu}(t) = ((\mathbf{Z}(t) \wedge \mathbf{u}(t)) \wedge D\mathbf{u}(t)) \implies |\boldsymbol{\mu}(t)| \ll |D\mathbf{u}(t)|$$

Therefore,

$$\boldsymbol{\mu}(t) = \frac{\boldsymbol{\mu}(t)}{|D\mathbf{u}(t)|} (|\nabla \mathbf{u}(t)| \mathcal{L}^m + |D^c(\mathbf{u}(t))|) + \frac{\boldsymbol{\mu}(t)}{|D\mathbf{u}(t)|} |\mathbf{u}(t)_+ - \mathbf{u}(t)_-| \mathcal{H}^{m-1} \llcorner J_{\mathbf{u}(t)}$$

If we show that

$$\frac{\boldsymbol{\mu}(t)}{|D\mathbf{u}(t)|} \cdot \frac{\mathbf{u}(t)^*}{|\mathbf{u}(t)^*|} \geq 1 \quad |D\mathbf{u}(t)| - a.e.,$$

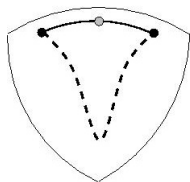
then

$$\boldsymbol{\mu}(t) = \frac{\mathbf{u}(t)^*}{|\mathbf{u}(t)^*|} |D\mathbf{u}(t)|$$

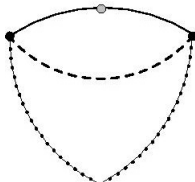
- For the diffuse part one can rely on l.s.c. results about linear growth functionals in S^{N-1} by Alicandro-Corbo-Esposito and Leone '07.
- For the jump part, one can obtain \mathcal{H}^{m-1} -a.e $x \in J_{\mathbf{u}(t)}$,

$$\frac{\mathbf{u}^*}{|\mathbf{u}^*|} \cdot \tilde{\boldsymbol{\mu}} \geq \inf \left\{ \int_0^1 \frac{\mathbf{u}^*}{|\mathbf{u}^*|} \cdot \boldsymbol{\gamma}(\tau) |\dot{\boldsymbol{\gamma}}(\tau)| d\tau : \boldsymbol{\gamma} \in W^{1,1}(I; \mathbb{S}_+^{N-1}), \boldsymbol{\gamma}(0) = \mathbf{u}_-, \boldsymbol{\gamma}(1) = \mathbf{u}_+ \right\}$$

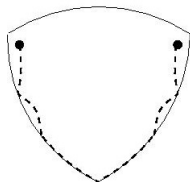
Therefore, showing that the above infimum is equal to $|\mathbf{u}_+ - \mathbf{u}_-|$ finishes the proof. In fact, a standard geodesic in the sphere joining \mathbf{u}_+ and \mathbf{u}_- yields the optimal bound. Unfortunately, the problem is genuinely non-convex.



(a)



(b)



(c)

The case of a 1-D domain

$$\Omega := I =]0, 1[$$

Definition

Let $\mathbf{u} \in W^{1,2}(0, T; L^2(I, \mathcal{N})) \cap L^\infty(0, T; BV(I, \mathcal{N}))$ be such that $\text{dist}_g(\mathbf{u}_-, \mathbf{u}_+) < \text{inj}\mathcal{N}$ on $J_{\mathbf{u}}$. \mathbf{u} is a solution to the 1-harmonic flow if there exists $\mathbf{Z} \in L^\infty(]0, T[\times I)^n$ such that a.e. $t \in]0, T[$,

$$\mathbf{u}_t = \pi_{\mathcal{N}}(\mathbf{u})\mathbf{Z}_x^a$$

$$\mathbf{Z} \in T_{\mathbf{u}}\mathcal{N}, \quad |\mathbf{Z}| \leq 1$$

$$Z = \frac{\mathbf{u}_x}{|\mathbf{u}_x|}, \quad |\tilde{\mathbf{u}}_x| - a.e.$$

$$\mathbf{Z}^\pm = T(\mathbf{u}^\pm) \quad \text{on } J_{\mathbf{u}}$$

$$\mathbf{Z} = 0 \text{ on } \{0, 1\}$$

Theorem

Let $\mathbf{u}_0 \in BV(I, \mathcal{N})$ satisfy $\text{dist}_g((\mathbf{u}_0)_-, (\mathbf{u}_0)_+) < R_*(\mathcal{N})$ on $J_{\mathbf{u}}$. Then, for any $T > 0$, there exists a solution to the 1-harmonic flow starting at \mathbf{u}_0 .

In case that $\mathcal{K}_{\mathcal{N}} \leq 0$, then the functional is convex. Then, there is a unique abstract solution in the sense of gradient flow given by Ambrosio-Gigli-Savaré's theory. Our solution coincides with this one and it is therefore unique.

Relaxed total variation

Given $\mathbf{u} \in BV(I, \mathcal{N})$,

$$TV_g(\mathbf{u}) = \inf \left\{ \liminf \int_I |\mathbf{u}_x^k| : \mathbf{u}^k \in W^{1,\infty}(I, \mathcal{N}), \mathbf{u}^k \xrightarrow{*} \mathbf{u} \right\}$$

Then (Giacquinta-Mucci '06),

$$TV_g(\mathbf{u}) = \int_I |\mathbf{u}_x|_g,$$

with

$$|\mathbf{u}_x|_g = |\tilde{\mathbf{u}}_x| \llcorner I \setminus J_{\mathbf{u}} + \text{dist}_g(\mathbf{u}_-, \mathbf{u}_+) \mathcal{H}^0(J_{\mathbf{u}})$$

Sketch of proof.

- Smooth the initial data and obtain a global regular solution u_ε .
- Use the completely local estimate (Giacomelli-Łasica '18):

$$|\mathbf{u}_x(t, \cdot)|_g \leq |(\mathbf{u}_0)_x|_g$$

to obtain uniform bounds and to compute

$$\frac{\mathbf{u}_x}{|(\mathbf{u}_0)_x|}, \quad \frac{|\mathbf{u}_x|}{|(\mathbf{u}_0)_x|}$$

outside $J_{\mathbf{u}_0}$.

- Use chain rule to compute $\frac{\mathbf{u}_x}{|\mathbf{u}_x|}$.

Jump part+uniqueness

- Choose special coordinates on the jump (Fermi coordinates)
- Use lower semicontinuity of the energy
- Show that the energy converges;

$$TV_g(u_\varepsilon) \rightarrow TV_g(u)$$

- For uniqueness, show that \mathbf{u} satisfies

$$\frac{1}{2} \frac{d}{dt} d_g^2(\mathbf{u}(t), \mathbf{v}) + TV_g(\mathbf{u}(t)) \leq TV_g(\mathbf{v})$$

for any $\mathbf{v} \in BV(I, \mathcal{N})$.

Future directions

- Uniqueness in case $\mathcal{N} = S_+^{N-1}$
- *BV*-solutions for smooth manifolds with unique geodesics.
- Non-smooth curves (Wulff shape of a 2-D crystalline norm).
- Non-smooth manifolds.

どうもありがとう