

4 K -theory as the universal localising invariant

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In the last lecture we generalised K_0 to the pair K_0, K_1 by moving from the set $\text{Proj}(R)_{/\cong}$ to the groupoid $\text{Proj}(R)^{\cong}$. In this lecture we generalise this process to get higher K_0, K_1, K_2, \dots by considering ∞ -groupoids. These form an ∞ -category.

4.1 Simplicial sets

References for simplicial sets and ∞ -groupoids (which used to be called Kan complexes):

1. May, Simplicial objects in algebraic topology.
2. Bousfield–Kan, Homotopy limits, completions and localizations.
3. Goerss–Jardine, Simplicial homotopy theory.

$$\begin{array}{ccccccc} \text{Groups} & \subseteq & \text{Groupoids} & \subseteq & \text{Categories} & \rightarrow & \text{Directed graphs} \\ \left(\begin{array}{c} \text{groupoids with} \\ \text{one object} \end{array} \right) & & \left(\begin{array}{c} \text{categories for which} \\ \text{every morphism} \\ \text{is invertible} \end{array} \right) & & & & \end{array}$$

$$\infty\text{-groups} \quad \subseteq \quad \infty\text{-groupoids} \quad \subseteq \quad \infty\text{-categories} \quad \subseteq \quad \text{Simplicial sets}$$

Recall that a directed graph consists of a set G_0 of vertices, a set G_1 of edges and two morphisms

$$d_0, d_1 : G_1 \rightrightarrows G_0$$

which associate to each edge $e \in G_1$ a source $d_1 e \in G_0$ and a target $d_0 e \in G_0$.

We can generalise this in higher dimensions by allowing “ n -dimensional edges” for all $n \in \mathbb{N}$. The information of all these higher edges and how they are related to each other is organised in the concept of a *simplicial set*.

Definition 4.1.1. We write $\Delta \subseteq \text{LinOrdSet}$ for the full subcategory of the category LinOrdSet of linearly ordered sets whose objects are finite and non-empty. In other words, those linearly ordered sets which are isomorphic to the linearly ordered set $[n] = \{0 < 1 < \dots < n\}$ for some $n \geq 0$. Morphisms are those morphisms of sets $p : [n] \rightarrow [m]$ such that $i \leq j \implies p(i) \leq p(j)$.

Example 4.1.2. For each $0 \leq j \leq n$ with $n \neq 0$, the *face* morphism $\delta_j : [n-1] \rightarrow [n]$ are defined as the unique injection which does not have j in its image.

$$\begin{array}{cccccccc} 0 & 1 & \dots & j-1 & j & j+1 & \dots & n-1 \\ \downarrow & \downarrow & & \downarrow & \searrow & \searrow & & \searrow \\ 0 & 1 & \dots & j-1 & j & j+1 & j+2 & \dots & n \end{array}$$

Example 4.1.3. For each $0 \leq j \leq n$ the *degeneracy* morphism $\sigma_j : [n+1] \rightarrow [n]$ is defined as the unique surjection which sends both j and $j+1$ to j .

$$\begin{array}{cccccccc} 0 & 1 & \dots & j & j+1 & j+2 & \dots & n+1 \\ \downarrow & \downarrow & & \downarrow & \swarrow & \swarrow & & \swarrow \\ 0 & 1 & \dots & j & j+1 & \dots & n \end{array}$$

Exercise. Show that every morphism $[n] \rightarrow [m]$ can be written as a composition of face and degeneracy morphisms.

Definition 4.1.4. The category of simplicial sets Set_Δ is the category of functors $\Delta^{op} \rightarrow \text{Set}$, so

$$\text{Set}_\Delta := \text{PSh}(\Delta)$$

Given such a functor $X : \Delta^{op} \rightarrow \text{Set}$ we write $X_n := X([n])$. Elements of X_n are called *n -simplices* of X .

Example 4.1.5. For any simplicial set $X : \Delta^{op} \rightarrow \text{Set}$ the morphisms

$$d_j : X_n \rightarrow X_{n-1}.$$

corresponding to the δ_j are called *face* morphisms. For $x \in X_n$ we call $d_j x$ the *j th face of x* . The morphisms

$$s_j : X_n \rightarrow X_{n+1}.$$

corresponding to the σ_j are called *degeneracy* morphisms.

Example 4.1.6 (Δ^n). For each n , the functor $\Delta^n := \text{hom}_\Delta(-, [n]) : \Delta^{op} \rightarrow \text{Set}$ defines a simplicial set. By Yoneda’s Lemma, for any $X \in \text{Set}_\Delta$,

$$\text{hom}_{\text{Set}_\Delta}(\Delta^n, X) \cong X_n.$$

Example 4.1.7 ($\partial\Delta^n$). Consider the morphisms of simplicial sets $\delta_j : \Delta^{n-1} \rightarrow \Delta^n$. We define

$$\partial\Delta^n = \bigcup_{j=0}^n \delta_j(\Delta^{n-1})$$

as the union of these faces. Explicitly, $(\partial\Delta^n)_j \subseteq (\Delta^n)_j = \text{hom}_\Delta([j], [n])$ is the set of morphisms $[j] \rightarrow [n]$ of linearly ordered sets which are not surjective. This can also be described as the colimit

$$\partial\Delta^n = \varinjlim_{[i] \subsetneq [n]} \Delta^i$$

In particular, for any other simplicial set X we have

$$\text{hom}(\partial\Delta^n, X) = \varprojlim_{\substack{[i] \subsetneq [n] \\ n-2 \leq i \leq n-1}} X_i.$$

That is, a morphism $\partial\Delta^n \rightarrow X$ is the same thing as a set of $(n-1)$ -simplices $x_0, \dots, x_n \in X_{n-1}$ satisfying $d_i x_j = d_j x_i$.

Definition 4.1.8 (Λ_j^n). For $0 \leq j \leq n$ we define the j th horn as the union

$$\Lambda_j^n = \bigcup_{i \neq j} \delta_i(\Delta^{n-1}).$$

Equivalently, $(\Lambda_j^n)_i \subseteq (\Delta^n)_i = \text{hom}_\Delta([i], [n])$ is the set of those $[i] \rightarrow [n]$ whose image does *not contain* the subset $\{0, 1, \dots, j-1, j+1, \dots, n\}$.

Example 4.1.9 ($\text{Sing } X$). Define

$$\Delta_{\text{top}}^n := \left\{ (x_0, \dots, x_n) \mid 0 \leq x_i \leq 1; \sum_{i=0}^n x_i = 1 \right\} \subseteq \mathbb{R}^{n+1}$$

to be the convex hull of the standard basis vectors $e_i = (0, \dots, 0, 1, 0, \dots, 0)$. So Δ_{top}^0 is a point, Δ_{top}^1 is a line segment, Δ_{top}^2 is a triangle, Δ_{top}^3 is a tetrahedron, \dots

Any morphism $p : [n] \rightarrow [m]$ in Δ defines an \mathbb{R} -linear morphism $\mathbb{R}^{n+1} \rightarrow \mathbb{R}^{m+1}$; $e_i \mapsto e_{p(i)}$, which restricts to a continuous morphism $\Delta_{\text{top}}^n \rightarrow \Delta_{\text{top}}^m$. In this way we get a functor

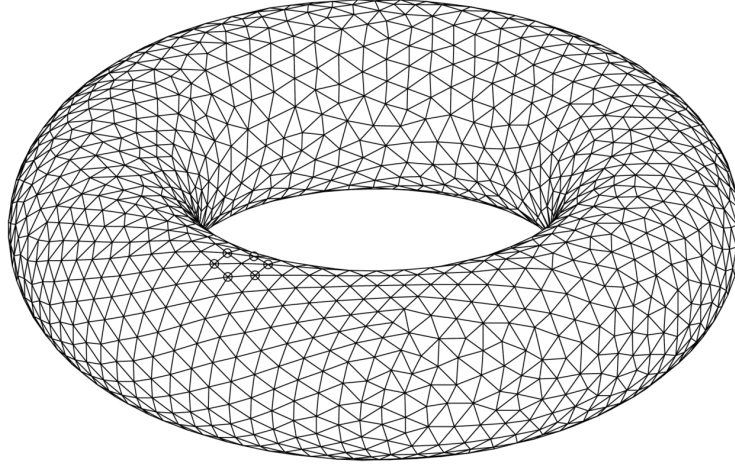
$$\Delta \rightarrow \mathcal{T}\text{op}; \quad [n] \mapsto \Delta_{\text{top}}^n$$

from Δ to the category of topological spaces. For any other topological space X , the assignment

$$\text{Sing } X : [n] \mapsto \text{hom}_{\mathcal{T}\text{op}}(\Delta_{\text{top}}^n, X)$$

defines a simplicial set. Explicitly,

1. $\text{Sing}_0 X$ is the set of points of X ,
2. $\text{Sing}_1 X$ is the set of paths in X ,
3. $\text{Sing}_2 X$ is the set of triangles in X ,
4. ...



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Example 4.1.10 (Product of simplicial sets). For simplicial sets X and Y , their product $X \times Y$ is defined by

$$(X \times Y)_n = X_n \times Y_n$$

with structure morphisms acting componentwise.

Example 4.1.11 (Mapping simplicial sets). For simplicial sets X and Y , the *mapping simplicial set* $\text{Map}(X, Y)$ has n -simplices given by

$$\text{Map}_{\text{Set}_\Delta}(X, Y)_n = \text{hom}_{\text{Set}_\Delta}(X \times \Delta^n, Y)$$

The maps associated to $[n] \rightarrow [m]$ are induced by the corresponding $\Delta^n \rightarrow \Delta^m$.

4.2 Infinity groupoids

Definition 4.2.1 (Kan fibration). A morphism $f : X \rightarrow Y$ of simplicial sets is a *Kan fibration* if for every $0 \leq j \leq n$ with $0 \neq n$ and commutative square

$$\begin{array}{ccc} \Lambda_j^n & \longrightarrow & X \\ \downarrow & \nearrow & \downarrow \\ \Delta^n & \longrightarrow & Y \end{array}$$

a dashed morphism exists making two triangles commutative. A simplicial set X is an ∞ -groupoid if the canonical morphism $X \rightarrow \Delta^0$ is a Kan fibration.

Example 4.2.2. If X is a topological space, then $\text{Sing } X$ is an ∞ -groupoid. In fact, by the homotopy hypothesis, there is an equivalence of ∞ -categories between the ∞ -category of topological spaces and the ∞ -category of ∞ -groupoids.

Definition 4.2.3 (Homotopy groups). For an ∞ -groupoid X and a basepoint $x \in X_0$, the n th homotopy group $\pi_n(X, x)$ is defined as follows. Consider

$$Z_{n,x} := \left\{ \Delta^n \xrightarrow{f} X \left| \begin{array}{ccc} \partial\Delta^n & \longrightarrow & x \\ \downarrow & & \downarrow \\ \Delta^n & \xrightarrow{f} & X \end{array} \text{ commutes} \right. \right\}$$

We define an equivalence relation on $Z_{n,x}$: two morphisms $f, g \in Z_{n,x}$ are equivalent if there exists a morphism $H : \Delta^{n+1} \rightarrow X$ such that

$$\begin{aligned} H|_{\delta_0(\Delta^n)} &= f \\ H|_{\delta_i(\Delta^n)} &= x \quad i = 1, \dots, n-1 \\ H|_{\delta_n(\Delta^n)} &= g \end{aligned}$$

Then

$$\pi_n(X, x) = Z_{n,x} / \sim.$$

Remark 4.2.4. The lifting property defining ∞ -groupoids ensures this actually is an equivalence relation. It is not an equivalence relation in a general simplicial set.

Example 4.2.5. If $n = 0$ then $\pi_0(X, x)$ is the set of connected components of the ∞ -groupoid X .

Example 4.2.6. Suppose $p : E \rightarrow B$ is a Kan fibration between ∞ -groupoids, $e \in E$, $b = p(e)$, and $F = \{b\} \times_B E$. Then there is a long exact sequence of groups

$$\dots \pi_{n+1}(B, b) \rightarrow \pi_n(F, e) \rightarrow \pi_n(E, e) \rightarrow \pi_n(B, b) \rightarrow \dots$$

for $n > 0$ ending with an exact sequence of pointed sets

$$\dots \rightarrow \pi_1(B, b) \rightarrow \pi_0(F, e) \rightarrow \pi_0(E, e) \rightarrow \pi_0(B, b).$$

Here, a sequence $(A, a) \xrightarrow{f} (B, b) \xrightarrow{g} (C, c)$ of pointed sets is exact if $f(A) = g^{-1}(c)$.

Definition 4.2.7 (Weak equivalence). A morphism $f : X \rightarrow Y$ of ∞ -groupoids is a *weak equivalence* if it induces isomorphisms on all homotopy groups:

$$\pi_n(f, x) : \pi_n(X, x) \rightarrow \pi_n(Y, f(x))$$

is a bijection for all $n \geq 0$ and all basepoints $x \in X_0$, and $\pi_0 X \rightarrow \pi_0 Y$ is surjective.

Example 4.2.8. In the notation of Example 4.2.6, if all homotopy groups of F are trivial and $\pi_0(E) \rightarrow \pi_0(B)$ is surjective, then $E \rightarrow B$ is a weak equivalence.

Example 4.2.9. The inclusion

$$X = \{z \in \mathbb{C} \mid |z| = 1\} \rightarrow \mathbb{C} \setminus \{0\} = Y$$

induces a weak equivalence $\text{Sing } X \rightarrow \text{Sing } Y$ of ∞ -groupoids. Indeed, the existence of a deformation retract $Y \rightarrow X; z \mapsto z/|z|$ implies all homotopy groups are isomorphic.

Example 4.2.10 (Homotopy equivalence). Two ∞ -groupoids X and Y are *homotopy equivalent* if there exist morphisms $f : X \rightarrow Y$ and $g : Y \rightarrow X$ such that $g \circ f$ and $f \circ g$ are homotopic to the respective identity morphisms. Here, two morphisms $a, b : A \rightarrow B$ are *homotopic* if there exists a morphism $H : A \times \Delta^1 \rightarrow B$ such that $H|_{A \times \{0\}} = a$ and $H|_{A \times \{1\}} = b$. By Whitehead's theorem for ∞ -groupoids, a morphism is a homotopy equivalence if and only if it is a weak equivalence.

4.3 Infinity categories

The standard reference for ∞ -categories is [Lurie, Higher Topos Theory].

There are also a number of other texts, e.g., [Haugsgeng, Yet another introduction to infinity categories].

Definition 4.3.1 (Boardman, Vogt, 1973). An ∞ -category is a simplicial set C such that for every $0 < i < n$ and each diagram

$$\begin{array}{ccc} \Lambda_i^n & \xrightarrow{\quad} & C \\ \downarrow & \nearrow \text{dashed} & \\ \Delta^n & & \end{array}$$

there exists a (not necessarily unique) dashed arrow making a commutative triangle.

Example 4.3.2. If $I \in \text{Set}_\Delta$ and $C \in \text{Cat}_\infty$, then $\text{Map}(I, C) \in \text{Cat}_\infty$. A morphism $D \rightarrow C$ between two ∞ -categories is called a *functor*.

(Exercise: Show that for any $X \in \text{Set}_\Delta$, if Y is an ∞ -groupoid, resp. ∞ -category, then so is $\text{Map}_{\text{Set}_\Delta}(X, Y)$)

Example 4.3.3. Let C be a small category. Considering the ordered sets $[n]$ as categories¹ $\{0 \rightarrow 1 \rightarrow \cdots \rightarrow n\}$ the assignment

$$N : [n] \mapsto \text{Fun}([n], C)$$

¹So, for $0 \leq i, j \leq n$ there is exactly one morphism $i \rightarrow j$ if $i \leq j$, and no morphisms otherwise.

sending $[n]$ to the set of functors $[n] \rightarrow C$ defines a simplicial set. This is called the *nerve* of C . Explicitly,

1. $N(C)_0$ is the set of objects of C ,
2. $N(C)_1$ is the set of (all) morphisms in C ,
3. The two morphisms $N(C)_1 \rightrightarrows N(C)_0$ induced by the two functors $[0] \rightrightarrows [1]$ send morphisms in $N(C)_1$ to their source and target.

$$(X \xrightarrow{f} Y) \quad \mapsto \quad X, Y$$

4. The morphism $N(C)_0 \rightarrow N(C)_1$ induced by $[1] \rightarrow [0]$ sends each object to its identity morphism.

$$X \quad \mapsto \quad (X \xrightarrow{\text{id}_X} X)$$

5. $N(C)_2$ is the set of composable morphisms $X \xrightarrow{f} Y \xrightarrow{g} Z$.
6. The three maps $d_0, d_1, d_2 : N(C)_2 \rightrightarrows N(C)_1$ induced by the three faithful functors $[1] \rightrightarrows [2]$ send $\xrightarrow{f} \xrightarrow{g}$ to g , $g \circ f$, and f respectively.

$$\begin{array}{ccc} & Y & \\ f \nearrow & & \searrow g \\ X & \xrightarrow{g \circ f} & Z \end{array} \quad \mapsto \quad (Y \xrightarrow{g} Z), \quad (X \xrightarrow{g \circ f} Y), \quad (X \xrightarrow{f} Y)$$

7. More generally, $N(C)_n$ is the set of sequences of n composable morphisms $\xrightarrow{f_1} \dots \xrightarrow{f_n}$ and the various maps $N(C)_n \rightarrow N(C)_m$ come from various combinations of composition and inserting identities.

Definition 4.3.4. Let $C \in \mathcal{Cat}_\infty$. Elements of C_0 are called *objects* and elements of C_1 are called 1-morphisms, or often just *morphisms*. Given two morphisms $f, g \in C_1$ such that $d_0 f = d_1 g$ (equivalently, a morphism of simplicial sets $\Lambda_1^2 \rightarrow C$), for any factorisation $\Lambda_1^2 \rightarrow \Delta^2 \xrightarrow{\sigma} C$, the morphism $d_1 \sigma \in C_1$ will be called a *composition* of g and f . For any object $X \in C_0$, the morphism $s_0 X \in C_1$ is called the *identity morphism* of X , and written id_X .

Example 4.3.5. A morphism $f : X \rightarrow Y$ in an ∞ -category is called an *equivalence* if there exists a morphism $g : Y \rightarrow X$ and 2-cells σ and τ of the form

$$\begin{array}{ccc} & Y & \\ f \nearrow & & \searrow g \\ X & \xrightarrow{\text{id}_X} & X \end{array} \quad \begin{array}{ccc} Y & \xrightarrow{\text{id}_Y} & Y \\ & \searrow \tau & \nearrow f \\ & X & \end{array}$$

Definition 4.3.6 (Mapping space). For an ∞ -category C and objects $x, y \in C_0$, the *mapping space* $\mathrm{Map}_C(x, y)$ is defined as the pullback

$$\mathrm{Map}_C(x, y) := \{x\} \times_C \mathrm{Map}_{\mathrm{Set}_\Delta}(\Delta^1, C) \times_C \{y\}$$

in the 1-category Set_Δ where the fiber products are taken with respect to the source and target maps $d_1, d_0 : C_1 \rightarrow C_0$. The *morphism set* is

$$\mathrm{hom}_C(x, y) = \pi_0 \mathrm{Map}_C(x, y).$$

Example 4.3.7. Any ∞ -groupoid is an ∞ -category. In particular, for any topological space X , the simplicial set $\mathrm{Sing} X$ is an ∞ -category.

Example 4.3.8. There exists an ∞ -category \mathcal{Gpd}_∞ whose objects are small ∞ -groupoids and whose mapping spaces are equivalent to the mapping simplicial set defined above.

$$\mathrm{Map}_{\mathcal{Gpd}_\infty}(X, Y) \simeq \mathrm{Map}_{\mathrm{Set}_\Delta}(X, Y).$$

Example 4.3.9. For any ∞ -category C , there is a maximal sub- ∞ -groupoid

$$C^\cong \subseteq C$$

called the *core* of C . It has the same objects as C , but only the invertible morphisms. More precisely, $(C^\cong)_n$ consists of those n -simplices $x \in C_n$ such that all images of x in C_1 are invertible morphisms in C .

Example 4.3.10. There exists an ∞ -category \mathcal{Cat}_∞ whose objects are small ∞ -categories and whose mapping spaces are equivalent to

$$\mathrm{Map}_{\mathcal{Cat}_\infty}(C, D) \simeq \mathrm{Map}_{\mathrm{Set}_\Delta}(C, D)^\cong.$$

Example 4.3.11. Let $R \in \mathcal{R}\mathrm{ing}$. A *bounded chain complex* of projectives is a sequence of morphisms

$$[\dots \xrightarrow{d_{n+1}} P_n \xrightarrow{d_n} P_{n-1} \xrightarrow{d_{n-1}} \dots]$$

in $\mathrm{Proj}(R)$ such that $d_{n-1}d_n = 0$ and only finitely many P_n are non-zero. A *morphism* of chain complexes $f_\bullet : P_\bullet \rightarrow Q_\bullet$ is a sequence of morphisms $f_n : P_n \rightarrow Q_n$ making commutative squares. A *homotopy* of morphisms $h : f_\bullet \sim g_\bullet$ is a sequence of morphisms $h_n : P_n \rightarrow Q_{n+1}$ such that $f_n - g_n = d_{n+1}h_n + h_{n-1}d_n$.

There exists an ∞ -category $D^b(R)$ whose objects are bounded chain complexes of projectives and morphisms are

$$\mathrm{hom}_{D^b(R)}(P_\bullet, Q_\bullet) \cong \frac{\{f_\bullet : P_\bullet \rightarrow Q_\bullet\}}{\text{homotopy}}$$

For more details on this example, see [Lurie, Higher Algebra, §1.3.1 and §1.3.2].

Example 4.3.12. The simplicial set Δ^1 is an ∞ -category but not an ∞ -groupoid (the unique non-identity morphism is not invertible). The pushout $\Delta^0 \sqcup_{\partial\Delta^1} \Delta^1$ of simplicial sets is not an ∞ -category. (The unique non-degenerate 1-simplex cannot be composed with itself).

4.4 Limits

Definition 4.4.1 (Limits in ∞ -categories). Let $C \in \mathcal{C}at_\infty$ and $I \in \mathcal{S}et_\Delta$. Given an object $X \in C$, write $\gamma(X) \in \text{Fun}(I, C)$ for the constant functor $I \rightarrow \Delta^0 \xrightarrow{X} C$.

For a morphism $F : I \rightarrow C$, a *limit* of F is an object $\varprojlim F \in C$ together with a morphism $\gamma(\varprojlim F) \rightarrow F$ in $\text{Fun}(I, C)$ such that for any object $X \in C$, the natural map

$$\text{Map}_C(X, \varprojlim F) \rightarrow \text{Map}_{\text{Fun}(I, C)}(\gamma(X), F)$$

is an equivalence of ∞ -groupoids. Dually, a *colimit* of F is an object $\varinjlim F \in C$ together with a natural transformation $F \rightarrow \gamma(\varinjlim F)$ such that for any object $X \in C$, the natural map

$$\text{Map}_C(\varinjlim F, X) \rightarrow \text{Map}_{\text{Fun}(I, C)}(F, \gamma(X))$$

is an equivalence of ∞ -groupoids.

Example 4.4.2 (Initial and terminal objects). An *initial object* \emptyset , resp. *terminal object* $*$, in an ∞ -category C is a limit, resp. colimit, of the unique functor $\emptyset \rightarrow C$ from the empty ∞ -category. Equivalently, it is an object such that for any $X \in C$, the mapping space $\text{Map}_C(\emptyset, X)$, resp. $\text{Map}_C(X, *)$, is *contractible*, i.e., all homotopy groups are trivial, or equivalently, $\text{Map} \cong \Delta^0$.

1. In the ∞ -category of ∞ -groupoids $\mathcal{G}pd_\infty$:

- Initial object \emptyset , resp. terminal object $*$: the empty ∞ -groupoid, resp. the point Δ^0 . Note that just as we can have very large categories which are equivalent to the punctual category, we can have quite large ∞ -groupoids which are terminal objects. For example,
 - (a) for any n , the ∞ -groupoid $\text{Sing } \mathbb{R}^n$ is a terminal object of $\mathcal{G}pd_\infty$.
 - (b) For any $X \in \mathcal{G}pd_\infty$ and $x \in X$, the ∞ -groupoid $\text{Map}(\Delta^1, X) \times_X \{x\}$ of paths towards x is a terminal object of $\mathcal{G}pd_\infty$.

2. In the ∞ -category of pointed ∞ -groupoids:

- Initial and terminal object: Δ^0 (the point, which is both initial and terminal, making this a pointed category)

3. In the ∞ -category \mathcal{Cat}_∞ of ∞ -categories:

- Initial object \emptyset , resp. terminal object $*$: the empty ∞ -category \emptyset , resp. the terminal ∞ -category Δ^0 with one object and only identity morphisms
- Terminal object: $*$ (the terminal ∞ -category with one object and only identity morphisms)

4. In the derived category $D^b(R)$:

- Initial object: 0 (the zero chain complex)
- Terminal object: 0 (the zero chain complex)

As in \mathcal{Gpd}_∞ we can have “large” objects which are also initial / terminal. For example $[\cdots \rightarrow 0 \rightarrow P \xrightarrow{\cong} P \rightarrow 0 \rightarrow \cdots]$ is equivalent to 0 for any P . So it is also an initial / terminal object.

Example 4.4.3 (Products and disjoint unions). Products and Coproducts are limits and colimits over $\Delta^1 = \Delta^0 \sqcup \Delta^0$.

1. In \mathcal{Gpd}_∞ and \mathcal{Cat}_∞ , products and coproducts are as in the 1-category \mathcal{Set}_Δ .
2. In $D^b(R)$ coproducts and products are isomorphic:

$$(P_\bullet \times Q_\bullet)_n = P_n \oplus Q_n = (P_\bullet \sqcup Q_\bullet)_n.$$

Example 4.4.4 (Pullbacks).

1. In \mathcal{Gpd}_∞ the limit of a diagram $X \rightarrow Z \leftarrow Y$ is modelled by the simplicial set

$$X \times_Z \text{Map}(\Delta^1, Z) \times_Z Y.$$

If $X = \{z\} = Y$ is a vertex of Z , then the limit $\{z\} \times_Z \{z\}$ in \mathcal{Gpd}_∞ is the space of loops from z to z .

2. In \mathcal{Cat}_∞ : The limit of a diagram $C \rightarrow D \leftarrow E$ is modelled by the simplicial set

$$C \times_D \text{Map}(\text{Iso}(\Delta^1), D) \times_D E.$$

where $\text{Iso}(\Delta^1)$ is the free ∞ -groupoid generated by Δ^1 . Explicitly, we have $\text{Iso}(\Delta^1)_m = \prod_{i \in [m]} \{0, 1\}$

3. In $D^b(R)$: For chain complexes $P_\bullet \xrightarrow{f} R_\bullet \xleftarrow{g} Q_\bullet$, the limit is modelled by the complex

$$\text{Cone}(P_\bullet \oplus Q_\bullet \xrightarrow{(f, -g)} R_\bullet)[-1].$$

Here, for a general morphism of complexes $A_\bullet \xrightarrow{f} B_\bullet$ one defines

$$\text{Cone}(A_\bullet \xrightarrow{f} B_\bullet)_n = B_n \oplus A_{n-1}$$

with differential $\begin{bmatrix} d_B & f \\ 0 & d_A \end{bmatrix}$ and

$$A_\bullet[m]_n = A_{n-m}$$

Example 4.4.5. Suppose that a quasi-projective variety X is the union of two basic opens $X = U \cup V$. Then the derived category $D^b(X)$ is equivalent to the pullback

$$D^b(X) = D^b(U) \times_{D^b(U \cap V)} D^b(V)$$

in \mathcal{Cat}_∞ where we define $D^b(Y) := D^b(\mathcal{O}_Y(Y))$ for affine varieties. More generally, if X is a union of finitely many basic opens $X = \cup_{i=1}^n U_i$ then the derived category is the limit

$$D^b(X) = \varprojlim_{i_0 < \dots < i_m} D^b(U_{i_0} \cap \dots \cap U_{i_m})$$

Pushouts in \mathcal{Cat}_∞ and \mathcal{Gpd}_∞ are not so explicit in general.

Example 4.4.6. The pushout of a diagram $P_\bullet \leftarrow R_\bullet \rightarrow Q_\bullet$ in $D^b(R)$ is modelled by the chain complex

$$\text{Cone}(R_\bullet \rightarrow P_\bullet \oplus Q_\bullet).$$

4.5 Stable infinity categories

Definition 4.5.1. An ∞ -category \mathcal{C} is *stable* if it satisfies the following conditions:

- (Sta0) It is pointed. That is, it admits both an initial object \emptyset and a final object $*$ and an equivalence $\emptyset \cong *$. We write 0 for such an object.
- (Sta1) It admits *fibres* and *cofibres*. That is, for every $f : X \rightarrow Y$, both

$$\text{fib}(f) := X \times_Y 0 \quad \text{and} \quad \text{cof}(f) = 0 \sqcup_X Y$$

exist.

(Sta2) A commutative square of the form

$$\begin{array}{ccc} X & \xrightarrow{f} & Y \\ \downarrow & & \downarrow g \\ 0 & \longrightarrow & Z \end{array} \quad (1)$$

is cartesian if and only if it is cocartesian.

Example 4.5.2. For $R \in \mathcal{R}\text{ing}$ the category $D^b(R)$ is stable.

Example 4.5.3. Suppose that C is a pointed ∞ -category. The stabilisation $\text{Sp}(C)$ is defined as the limit

$$\text{Sp}(C) = \varprojlim (\dots \xrightarrow{\Omega} C \xrightarrow{\Omega} C \xrightarrow{\Omega} C)$$

in Cat_∞ where $\Omega X := * \times_X *$. Every object in $\text{Sp}(C)$ gives rise to a sequence of objects E_0, E_1, \dots in C equipped with equivalences $E_{n-1} \xrightarrow{\sim} \Omega E_n$. We also have a canonical functor

$$\Omega^\infty : \text{Sp}(C) \rightarrow C$$

namely, projection to the last component.

Proposition 4.5.4 ([HA, Cor.1.4.2.23]). *Let C be an ∞ -category which admits finite limits, and T a stable quasi-category. Then composition with the functor Ω^∞ induces an equivalence of ∞ -categories*

$$\text{Fun}^{Lex}(T, \text{Sp}(C)) \rightarrow \text{Fun}^{Lex}(T, C)$$

where Fun^{Lex} means the full subcategory of functors sending finite limits to finite limits, i.e., left exact functors.

Definition 4.5.5. The stabilisation of the category of pointed ∞ -groupoids is called the category of *spectra* and is denoted

$$\mathcal{S}\text{pt} = \text{Sp}(\mathcal{G}\text{pd}_{\infty,*}).$$

Remark 4.5.6. The equivalences $E_n \xrightarrow{\sim} \Omega E_{n+1}$ induces isomorphisms

$$\pi_i E_n \xrightarrow{\sim} \pi_{i+1} E_{n+1}.$$

Given a spectrum E we define

$$\pi_i E := \pi_{i+j} E_j; \quad i \in \mathbb{Z}$$

for any j such that the right hand side is defined.

Example 4.5.7. Suppose that $C \subseteq D$ in $\mathcal{C}at_{\infty}^{\text{ex}}$ is a full sub- ∞ -category closed under finite limits and finite colimits. The *Verdier localisation* D/C is a stable ∞ -category with the same objects as D and mapping spaces

$$\text{Map}_{D/C}(X, Y) = \varinjlim_{X' \rightarrow X} \text{Map}_D(X', Y)$$

where the colimit is over the ∞ -category of morphisms $s : X' \rightarrow X$ such that $\text{fib}(s) \in C$.

Example 4.5.8. The canonical functor $D^b(\mathbb{Z}) \rightarrow D^b(\mathbb{Q})$ identifies $D^b(\mathbb{Q})$ with the Verdier quotient of $D^b(\mathbb{Z})$ by the full sub- ∞ -category $D^b(\mathbb{Z})_{\text{tor}} \subseteq D^b(\mathbb{Z})$ of those complexes P_{\bullet} whose homology groups $H_n(P) = \frac{\ker(P_n \rightarrow P_{n-1})}{\text{im}(P_{n+1} \rightarrow P_n)}$ are torsion.

$$D^b(\mathbb{Z})/D^b(\mathbb{Z})_{\text{tor}} \cong D^b(\mathbb{Q}).$$

Example 4.5.9. Let $X \in \mathcal{Q}\text{Proj}$. The coherent $\mathcal{O}_{\mathbb{P}^n}$ -modules $\mathcal{O}, \mathcal{O}(1), \dots, \mathcal{O}(n)$ induce a sequence of stable sub- ∞ -categories

$$0 = C_{-1} \subset C_0 \subset \dots \subset C_n = D^b(\mathbb{P}^n \times X).$$

Namely, C_i is generated by $\mathcal{O}, \dots, \mathcal{O}(i)$. We have equivalences

$$C_i/C_{i-1} \cong D^b(X).$$

via the functors

$$\begin{aligned} D^b(X) &\rightarrow D^b(\mathbb{P}^n \times X) \\ F &\mapsto \mathcal{O}(i) \otimes p^*F \end{aligned}$$

4.6 Localising invariants

The original reference for the characterisation of algebraic K -theory as the universal localising invariant is [Antieau–Gepner–Tabuada]. For a course about this see [Hebestreit–Wagner, Algebraic and Hermitian K-Theory, Winter Term 2020/21, University of Bonn]

Write

$$\mathcal{C}at_{\infty}^{\text{ex}}$$

for the ∞ -category whose objects are stably ∞ -categories and morphisms are exact functors. That is, functors which preserve finite limits and finite colimits.

Definition 4.6.1 (Idempotent completion). A stable ∞ -category C is *idempotent complete* if every idempotent endomorphism $p : X \rightarrow X$ (i.e., $p \circ p \simeq p$) admits a splitting. That is, there exists an isomorphism

$$X \cong Y \oplus Z$$

such that p is identified with the composition $X \rightarrow Y \rightarrow X$. We write $\mathcal{C}at_{\infty}^{\text{perf}} \subseteq \mathcal{C}at_{\infty}^{\text{ex}}$ for the full subcategory of idempotent complete stable ∞ -categories. The inclusion admits a left adjoint

$$(-)^{\natural} : \mathcal{C}at_{\infty}^{\text{ex}} \rightarrow \mathcal{C}at_{\infty}^{\text{perf}}$$

called idempotent completion.

Proposition 4.6.2. *A square*

$$\begin{array}{ccc} C & \xrightarrow{i} & D \\ \downarrow & & \downarrow p \\ 0 & \longrightarrow & E \end{array}$$

of small stable ∞ -categories is a bifibre square in $\mathcal{C}at_{\infty}^{\text{ex}}$ if it is a cartesian square in $\mathcal{C}at_{\infty}$ and E is (equivalent to) the Verdier localisation D/C of D along C . Such a square is a fibre square in $\mathcal{C}at_{\infty}^{\text{perf}}$ if $E \cong (D/C)^{\natural}$.

Definition 4.6.3. A functor $F : \mathcal{C}at_{\infty}^{\text{perf}} \rightarrow \mathcal{S}pt$ is called a *localising invariant* if it sends bifibre squares to bifibre squares.

4.7 K -theory

Theorem 4.7.1. *The ∞ -category of localising functors $F : \mathcal{C}at_{\infty}^{\text{perf}} \rightarrow \mathcal{S}pt$ equipped with a natural transformation*

$$(-)^{\cong} \rightarrow \Omega^{\infty} F$$

admits an initial object K .

Remark 4.7.2. That is, K is the localising invariant “as close as possible” to the core functor which sends $C \in \mathcal{C}at_{\infty}^{\text{perf}}$ to its associated ∞ -groupoid C^{\cong} . Note that in a precise mathematical sense, $D^b(R)$ is the closest stable ∞ -category to $\text{Proj}(R)$, [Lurie, Higher Algebra, Thm.1.3.3.2, Thm.1.3.3.8].

Theorem 4.7.3. *For $n \leq 1$ and $R \in \mathcal{R}ing$, the homotopy groups*

$$\pi_n K(D^b(R))$$

are the groups $K_n(R)$ we saw last time.

Example 4.7.4. Using the decomposition associated to $\mathcal{O}, \mathcal{O}(1), \dots, \mathcal{O}(n)$, we have

$$K(D^b(\mathbb{P}_R^n)) \cong \bigoplus_{i=0}^n K(R).$$

Example 4.7.5. For a finite field \mathbb{F}_q with q elements, we have:

$$K_n(\mathbb{F}_q) = 0 \quad \text{for } n \leq -1 \quad (2)$$

$$K_0(\mathbb{F}_q) \cong \mathbb{Z} \quad (3)$$

$$K_1(\mathbb{F}_q) \cong \mathbb{F}_q^\times \cong \mathbb{Z}/(q-1)\mathbb{Z} \quad (4)$$

$$K_{2i}(\mathbb{F}_q) = 0 \quad \text{for } i \geq 1 \quad (5)$$

$$K_{2i-1}(\mathbb{F}_q) \cong \mathbb{Z}/(q^i - 1)\mathbb{Z} \quad \text{for } i \geq 1 \quad (6)$$

The pattern in positive degrees follows from Quillen's computation, while negative K -groups vanish since \mathbb{F}_q has finite global dimension.

Example 4.7.6. For the field of rational numbers \mathbb{Q} :

$$K_n(\mathbb{Q}) = 0 \quad \text{for } n \leq -1 \quad (7)$$

$$K_0(\mathbb{Q}) \cong \mathbb{Z} \quad (8)$$

$$K_1(\mathbb{Q}) \cong \mathbb{Q}^\times \quad (9)$$

$$K_2(\mathbb{Q}) \cong (\mathbb{Z}/4)^* \times \prod_{p \text{ odd prime}} (\mathbb{Z}/p)^* \quad (10)$$

The computation of $K_2(\mathbb{Q})$ is due to Tate and follows from Gauss's first proof of quadratic reciprocity. For higher K -groups, Borel proved that (modulo torsion):

$$\begin{aligned} K_{4k+1}(\mathbb{Z})/\text{tors} &= \mathbb{Z} \quad \text{for } k > 0 \\ K_i(\mathbb{Z})/\text{tors} &= 0 \quad \text{for } i > 2; i \neq 4k+1 \end{aligned}$$

Example 4.7.7 (Matsumoto's theorem). For any field k , Matsumoto's theorem states that the second K -group is given by

$$K_2(k) = \frac{k^\times \otimes_{\mathbb{Z}} k^\times}{\langle a \otimes (1-a) \mid a \neq 0, 1 \rangle}.$$

The relations $a \otimes (1-a) = 0$ are called the *Steinberg relations*.