

# Gaussian quasi-likelihood estimation of ergodic square-root diffusion

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## Overview

- 1 Introduction to CIR process and sample setting
- 2 Gaussian quasi-likelihood analysis of CIR model
- 3 Simulation based on GQMLE

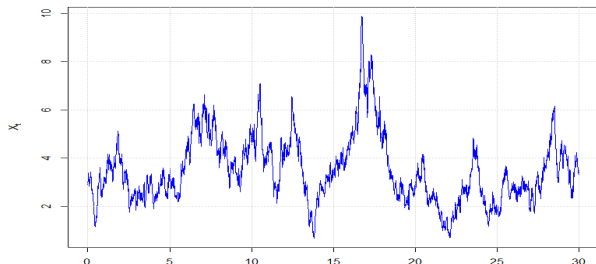
## Cox-Ingersoll-Ross model(CIR model)

CIR process  $(X_t)_{t \geq 0}$  in  $\mathbb{R}$  is a solution to the stochastic differential equation

$$dX_t = (\alpha - \beta X_t)dt + \sqrt{\gamma X_t}dw_t.$$

- $w_t$  is standard brownian motion.
- $\theta := (\alpha, \beta, \gamma) \in (0, \infty)^3$ ,  $\Theta$  is b'dd convex with  $\bar{\Theta} \subset \{(\alpha, \beta, \gamma) \in (0, \infty)^3 : \frac{2\alpha}{\gamma} > 5\}$ .
- It was proposed by Cox, Ingersoll and Ross (1985)  
"A Theory of the Term Structure of Interest Rates"

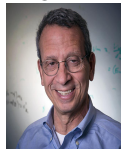
CIR process with  $\alpha = 3$ ,  $\beta = 1$ ,  $\gamma = 1$



Cox\*



Ingersoll\*



Ross\*

\*All photos are from their homepages.

# High frequency sampling

We consider **parametric estimation** of  $\theta = (\alpha, \beta, \gamma)$  based on **discrete-time observations under high frequency sampling**

Discrete observations of  $X_t$  given by  $(X_{t_0}, X_{t_1}, \dots, X_{t_n})$ :

$$X_{t_j} = X_{t_{j-1}} + \int_{t_{j-1}}^{t_j} (\alpha - \beta X_s) ds + \int_{t_{j-1}}^{t_j} \sqrt{\gamma X_s} dw_s,$$

$t_j = jh$  where  $h < 1$ .

## Previous studies

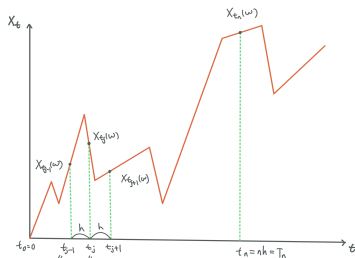
- Overbeck and Rydén 1997  
Study some estimators and their asymptotic properties under **low frequency sampling**.
- Alaya, Kebaier and Tran 2020  
Assume  $\gamma$  is known, consider the LAN property under **high frequency sampling**.

## Our goal

Derive an asymptotically efficient estimator of  $\theta$  under high frequency sampling.

## High-frequency scenario

$h = h_n \rightarrow 0$  as  $n \rightarrow \infty$ ,  
 $T_n := nh \rightarrow \infty$  as  $n \rightarrow \infty$ .



## Gaussian quasi-likelihood

- Gaussian quasi-likelihood function (GQLF)  $\mathbb{H}_n(\theta) := \sum_{j=1}^n \log \phi(X_{t_j}; \mu_{j-1}(\alpha, \beta), \sigma_{j-1}^2(\theta))$   
where  $\phi(\cdot; \mu, \sigma^2)$  denotes Normal density.
- Gaussian quasi-maximum likelihood estimator (GQMLE)  $\hat{\theta}_n = (\hat{\alpha}_n, \hat{\beta}_n, \hat{\gamma}_n) \in \operatorname{argmax}_{\Theta} \mathbb{H}_n(\theta)$

## Theorem (Asymptotic normality)

Under some regularity conditions,

$$\left( \sqrt{nh}(\hat{\alpha}_n - \alpha_0), \sqrt{nh}(\hat{\beta}_n - \beta_0), \sqrt{n}(\hat{\gamma}_n - \gamma_0) \right) \xrightarrow{\mathcal{L}} N(0, \mathcal{I}(\theta_0)^{-1}),$$

$$\text{where } \mathcal{I}(\theta_0) = \begin{pmatrix} \frac{1}{\gamma_0} & \frac{2\beta_0}{2\alpha_0 - \gamma_0} & -\frac{1}{\gamma_0} & 0 \\ -\frac{1}{\gamma_0} & \frac{1}{\gamma_0} & \frac{\alpha_0}{\beta_0} & 0 \\ 0 & 0 & \frac{1}{2\gamma_0^2} & 0 \end{pmatrix}.$$

Since GQMLE itself can't be computed explicitly, we use a **explicit one step estimator** to do simulation

$$\hat{\theta}_n^{(1,1)} = \hat{\theta}_{0,n} + D_n^{-1} \mathcal{I}(\hat{\theta}_{0,n})^{-1} D_n^{-1} \partial_{\theta} \mathbb{H}(\hat{\theta}_{0,n})$$

where Preliminary estimator  $\hat{\theta}_{0,n} = (\hat{\alpha}_{0,n}, \hat{\beta}_{0,n}, \hat{\gamma}_{0,n})$ ,  $D_n = \operatorname{diag}(\sqrt{nh}, \sqrt{nh}, \sqrt{n})$ .

- $(\hat{\alpha}_{0,n}, \hat{\beta}_{0,n})$  is conditional LSE,
- $\hat{\gamma}_{0,n}$  maximizes the plug-in GQLF  $\mathbb{H}_{2,n}(\gamma)$

# Simulation

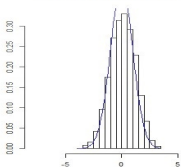
Compute  $\hat{\theta}_{0,n}$ ,  $\hat{\theta}_n^{(1,1)}$ ,  $\hat{u}_{0,n}$  and  $\hat{u}_n$  for 2000 times under  $T_n = 100$ ,  $h_n = 0.01$

where  $\hat{u}_{0,n} := \mathcal{I}(\hat{\theta}_{0,n})^{1/2} D_n(\hat{\theta}_{0,n} - \theta_0)$  and  $\hat{u}_n := \mathcal{I}(\hat{\theta}_n^{(1,1)})^{1/2} D_n(\hat{\theta}_n^{(1,1)} - \theta_0)$ .

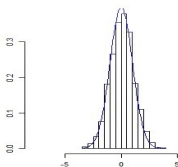
Parameters:	$\alpha$		$\beta$		$\gamma$	
True values:	3		2		1	
	Mean	Sd	Mean	Sd	Mean	Sd
preliminary $\hat{\theta}_{0,n}$	3.059	0.326	2.043	0.233	1.000	0.014
one-step $\hat{\theta}_n$	3.045	0.287	2.034	0.208	0.997	0.014

- For  $\alpha$  and  $\beta$ , one step estimator performs better.
- For  $\gamma$ , preliminary estimator performs better.

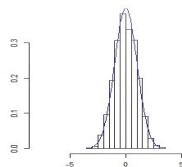
preliminary alpha in hat(u)\_(0,n)



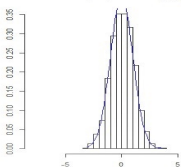
preliminary beta in hat(u)\_(0,n)



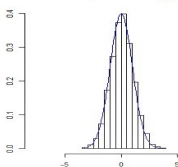
preliminary gamma in hat(u)\_(0,n)



one step alpha in hat(u)\_(n)



one step beta in hat(u)\_(n)



one step gamma in hat(u)\_(n)

