

NOTES ON PROJECTIVE STRUCTURES WITH TORSION

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ABSTRACT. We show that projective structures with torsion are related to connections in a parallel way to the torsion-free ones. This is done in terms of Cartan connections by following Kobayashi and Nagano. For this purpose, we make use of a bundle of formal frames, which is a generalization of a bundle of frames. We will also describe projective structures in terms of Thomas–Whitehead connections by following Roberts. In particular, we formulate normal projective connections and show the fundamental theorem for Thomas–Whitehead connections regardless the triviality of the torsion. We will study some examples of projective structures of which the torsion is non-trivial while the curvature is trivial. In this article, projective structures are considered to be the same if they have the same geodesics and the same torsions.

INTRODUCTION

Projective structures are quite well-studied. They can be described by Cartan connections and frame bundles, as studied by Kobayashi and Nagano [5], et. al. Projective structures can be also described in terms of Thomas–Whitehead connections (TW-connections for short) which are linear connections on a certain line bundle [7]. Associated with projective structures are torsions, which are 2-forms. If the torsion of a projective structure vanishes, then the structure is said to be *torsion-free* or without torsion. Actually, the above-mentioned studies are done in the torsion-free case. One of the most fundamental results is the existence of normal projective connections [5, Proposition 3] which is a Cartan connection of special kind. A corresponding result for TW-connections is known as the Fundamental theorem for TW-connections [7]. On the other hand, linear connections always induce projective structures even if they are with torsions. In this article, we study how linear connections with torsions induce projective structures. Indeed, we will study projective structures with torsion and show that they can be treated in a parallel way to the torsion-free case. For this purpose, we need a notion of formal frame bundles [1] which is a generalization of frame bundles. Usually, a 2-frame at a point is given by a pair $(a^i_j, a^i_{jk}) \in \mathrm{GL}_n(\mathbb{R}) \times \mathbb{R}^{n^3}$ such that $a^i_{jk} = a^i_{kj}$. The symmetricity condition is quite related with torsion-freeness and we have to drop this condition

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in order to deal with torsions. This leads us to formal frames. A formal 2-frame at a point is a pair $(a^i_j, a^i_{jk}) \in \mathrm{GL}_n(\mathbb{R}) \times \mathbb{R}^{n^3}$. We refer to [1] for the precise definition and details of formal frames. Expecting a better understanding of the torsion, we will study some examples of projective structures of which the torsion is non-trivial while the curvature is trivial. Finally, we remark that a slightly different approach to projective structures with torsion is presented in [6, Section 7].

In this article, projective structures are considered to be the same if they have the same (unparameterized) geodesics and the same torsions except last part of Section 2. Throughout this article, (U, φ) and $(\widehat{U}, \widehat{\varphi})$ denote charts, and ψ denotes the transition function. Representing (local) tensors, we make use of the Einstein convention. For example, $a^i_\alpha b^\alpha_{jk}$ means $\sum_\alpha a^i_\alpha b^\alpha_{jk}$. The range of α will be from 1 to $\dim M$ or from 1 to $\dim M + 1$. We basically retain notations of [5] and [7]. Finally, the order of lower indices of the Christoffel symbols are reversed in this article (see Notation 2.15).

1. CARTAN CONNECTIONS

We recall basics of Cartan connections after [4]. We will work in the real category, however, we can work in the complex category (not necessarily the holomorphic category) after obvious modifications.

Let G be a Lie group and H a closed subgroup of G . We assume that P is a principal H -bundle over M . In what follows, the Lie algebra is represented by the corresponding lower German letter, e.g., \mathfrak{g} will denote the Lie algebra of G .

Definition 1.1. A *Cartan connection* is a 1-form ω on P with values in \mathfrak{g} which satisfies the following conditions:

- 1) $\omega(A^*) = A$ for any $A \in \mathfrak{h}$, where A^* denotes the fundamental vector field associated with A .
- 2) $R_a^* \omega = \mathrm{Ad}_{a^{-1}} \omega$ for any $a \in H$.
- 3) $\omega(X) \neq 0$ for any non-zero vector X on P .

Notation 1.2. In what follows, we assume that $G = \mathrm{PGL}_{n+1}(\mathbb{R}) = \mathrm{GL}_{n+1}(\mathbb{R})/Z$, where $Z = \{\lambda I_{n+1} \mid \lambda \neq 0\}$. Let $[x^0 : \cdots : x^n]$ be the homogeneous coordinates for $\mathbb{R}P^n$, and $H \subset G$ the isotropy group of $[0 : \cdots : 0 : 1]$. Finally we set $\mathfrak{m} = \mathbb{R}^n$, which is understood as a space of column vectors, and let \mathfrak{m}^* denote its dual.

Definition 1.3. We set

$$G_0 = \left\{ \begin{pmatrix} A & 0 \\ \xi & a \end{pmatrix} \in \mathrm{GL}_{n+1}(\mathbb{R}) \mid a \det A = 1 \right\} / Z,$$

$$G_1 = \left\{ \begin{pmatrix} I_n & 0 \\ \xi & 1 \end{pmatrix} \in \mathrm{GL}_{n+1}(\mathbb{R}) \mid \xi \in \mathfrak{m}^* \right\}.$$

Note that G_1 is naturally a subgroup of G and G_0 . We have

$$\mathfrak{g}_0 = \left\{ \begin{pmatrix} A & 0 \\ 0 & a \end{pmatrix} \mid \operatorname{tr} A + a = 0 \right\},$$

$$\mathfrak{g}_1 = \left\{ \begin{pmatrix} 0 & 0 \\ \xi & 0 \end{pmatrix} \right\}.$$

If we set

$$\mathfrak{g}_{-1} = \left\{ \begin{pmatrix} 0 & v \\ 0 & 0 \end{pmatrix} \right\},$$

then we have

$$\mathfrak{g} = \mathfrak{g}_{-1} \oplus \mathfrak{g}_0 \oplus \mathfrak{g}_1.$$

We have $\mathfrak{g}_{-1} \cong \mathfrak{m}$, $\mathfrak{g}_0 \cong \mathfrak{gl}_n(\mathbb{R})$ and $\mathfrak{g}_1 \cong \mathfrak{m}^*$ so that $\mathfrak{g} \cong \mathfrak{m} \oplus \mathfrak{gl}_n(\mathbb{R}) \oplus \mathfrak{m}^*$. We also have $\mathfrak{h} \cong \mathfrak{gl}_n(\mathbb{R}) \oplus \mathfrak{m}^*$. The identifications are given by

$$\begin{pmatrix} 0 & v \\ 0 & 0 \end{pmatrix} \in \mathfrak{g}_{-1} \mapsto v \in \mathfrak{m},$$

$$\begin{pmatrix} A & 0 \\ 0 & a \end{pmatrix} \in \mathfrak{g}_0 \mapsto U = A - aI_n \in \mathfrak{gl}_n(\mathbb{R}),$$

$$\begin{pmatrix} 0 & 0 \\ \xi & 0 \end{pmatrix} \in \mathfrak{g}_1 \mapsto \xi \in \mathfrak{m}^*.$$

Note that $U \in \mathfrak{gl}_n(\mathbb{R})$ corresponds to $\begin{pmatrix} U & 0 \\ 0 & 0 \end{pmatrix} - \frac{1}{n+1}(\operatorname{tr} U)I_{n+1}$. Under these identifications, the Lie brackets are given as follows. Let $u, v \in \mathfrak{m}$, $u^*, v^* \in \mathfrak{m}^*$ and $U, V \in \mathfrak{gl}_n(\mathbb{R})$. Then, we have

$$\begin{aligned} [u, v] &= 0, \\ [u^*, v^*] &= 0, \\ [U, u] &= Uu \in \mathfrak{m}, \\ [u^*, U] &= u^*U \in \mathfrak{m}^*, \\ [U, V] &= UV - VU \in \mathfrak{gl}_n(\mathbb{R}), \\ [u, u^*] &= uu^* + u^*uI_n \in \mathfrak{gl}_n(\mathbb{R}). \end{aligned}$$

In what follows, we always make use of these identifications. If ω is a Cartan connection on P , then we represent $\omega = (\omega^i, \omega^i_j, \omega_j)$ according to the identification $\mathfrak{g} = \mathfrak{m} \oplus \mathfrak{gl}_n(\mathbb{R}) \oplus \mathfrak{m}^*$.

Remark 1.4. Each element g of $\operatorname{PGL}_{n+1}(\mathbb{R})$ admits a representative of the form $\begin{pmatrix} A & \xi^* \\ \xi & 1 \end{pmatrix}$. By associating g with (ξ, A, ξ^*) , we can consider (a^i, a^i_j, a_j) as coordinates for $\operatorname{PGL}_{n+1}(\mathbb{R})$. With respect to these coordinates, we have $H = \{(0, a^i_j, a_j)\}$. Let $o = [0 : \cdots : 0 : 1]$ denote $H \in \operatorname{PGL}_{n+1}(\mathbb{R})/H$. If $h = (0, a^i_j, a_j) \in H$ and if

$x = (x^i) = [x^1 : \cdots : x^n : 1]$ is close enough to o , then we have

$$\begin{aligned} h.x &= \frac{a^i_j x^j}{a_j x^j + 1} \\ &= a^i_j x^j - a^i_j x^j a_k x^k + \cdots \\ &= a^i_j x^j - \frac{1}{2}(a^i_j a_k + a^i_k a_j) x^j x^k + \cdots . \end{aligned}$$

Definition 1.5. Let $\omega = (\omega^i, \omega^i_j, \omega_j)$ be a Cartan connection on P . We set

$$\begin{aligned} \Omega^i &= d\omega^i + \omega^i_k \wedge \omega^k, \\ \Omega^i_j &= d\omega^i_j + \omega^i_k \wedge \omega^k_j + \omega^i \wedge \omega_j - \delta^i_j \omega_k \wedge \omega^k, \\ \Omega_j &= d\omega_j + \omega_k \wedge \omega^k_j. \end{aligned}$$

We call Ω^i the *torsion* and (Ω^i_j, Ω_j) the *curvature* of ω , respectively.

We refer to (Ω^i_j) as the *curvature matrix* of ω and consider trace of it.

We have the following

Proposition 1.6 ([5, Proposition 2]). . We can represent the torsion and the curvature as

$$\begin{aligned} \Omega^i &= \frac{1}{2} K^i_{kl} \omega^j \wedge \omega^k, & K^i_{lk} &= -K^i_{kl}, \\ \Omega^i_j &= \frac{1}{2} K^i_{jkl} \omega^k \wedge \omega^l, & K^i_{jlk} &= -K^i_{jkl}, \\ \Omega_j &= \frac{1}{2} K_{jkl} \omega^k \wedge \omega^l, & K_{jlk} &= -K_{jkl}, \end{aligned}$$

where K^i_{kl} , K^i_{jkl} and K_{jkl} are functions on P .

Remark 1.7. If ω is a Cartan connection on P , then we have the following:

- $\omega^i(A^*) = 0$ and $\omega^i_j(A^*) = A^i_j$ for any $A = (A^i_j, A_j) \in \mathfrak{h} = \mathfrak{gl}_{n+1}(\mathbb{R}) \oplus \mathfrak{m}^*$.
- $R_a^*(\omega^i, \omega^i_j) = \text{Ad}_{a^{-1}}(\omega^i, \omega^i_j)$ for any $a \in H$.
- Let $X \in TP$. We have $\omega^i(X) = 0$ if and only if X is vertical, namely, tangent to a fiber of $P \rightarrow M$.

Proposition 3 in [5] holds in the following form. A point is that we do not need the condition $\Omega^i_i = 0$. See also Remark 2.6.

Proposition 1.8. Let ω^i and ω^i_j satisfy the conditions in Remark 1.7. Then, there is a Cartan connection of the form $\omega = (\omega^i, \omega^i_j, \omega_j)$. If $n \geq 2$, there uniquely exists a Cartan connection such that $K^i_{jil} = 0$, that is, ω is Ricci-flat. If moreover $n \geq 3$ and if ω is torsion-free, then $\Omega^i_i = 0$, namely, the curvature matrix (Ω^i_j) is trace-free.

Proof. First we show the existence of a Cartan connection. Let $\{U_\alpha\}$ be a locally finite open covering of M and $\{f_\alpha\}$ a partition of unity subordinate to $\{U_\alpha\}$. Let

$\pi: P \rightarrow M$ is the projection. Suppose that for each α , there is a Cartan connection ω_α on $\pi^{-1}(U_\alpha)$ such that $\omega_\alpha = (\omega^i, \omega^i_j, \omega_{j,\alpha})$ for some $\omega^i_{j,\alpha}$. If we set $\omega = \sum(f_\alpha \circ \pi)\omega_\alpha$, then ω is a Cartan connection of the form $(\omega^i, \omega^i_j, \omega_j)$. On the other hand, we may assume that $\pi^{-1}(U_\alpha)$ is trivial. We fix a trivialization $\pi^{-1}(U_\alpha) \cong U_\alpha \times H$. If $(x, h) \in U_\alpha \times H$ and if $Y \in T_{(x,h)}P$, then we can represent Y as $Y = X + A$, where $Y \in T_xM$ and $A \in \mathfrak{h}$. If we set $\omega_\alpha(Y) = \text{Ad}_{a^{-1}}(\omega^i(X), \omega^i_j(X), 0) + A$, then ω_α is a Cartan connection of the form $(\omega^i, \omega^i_j, \omega_{j,\alpha})$.

From now on, we assume that $n \geq 2$. We show the uniqueness. Suppose that $\omega = (\omega^i, \omega^i_j, \omega_j)$ and $\omega' = (\omega^i, \omega^i_j, \omega'_j)$ are Cartan connections as in the proposition. By the conditions a) and c), we have $\omega_j - \omega'_j = A_{jk}\omega^k$ for some functions A_{jk} on P . We have

$$\Omega^i_j - \Omega'^i_j = \omega^i \wedge (\omega_j - \omega'_j) - \delta^i_j(\omega_k - \omega'_k) \wedge \omega^k.$$

It follows that

$$K^i_{jkl} - K'^i_{jkl} = -\delta^i_l A_{jk} + \delta^i_k A_{jl} + \delta^i_j A_{kl} - \delta^i_j A_{lk}.$$

Therefore, we have

$$\begin{aligned} K^i_{jil} - K'^i_{jil} &= -\delta^i_l A_{ji} + \delta^i_i A_{jl} + \delta^i_j A_{il} - \delta^i_j A_{li} \\ &= (n-1)A_{jl} + (A_{jl} - A_{lj}) \\ &= nA_{jl} - A_{lj}. \end{aligned}$$

It follows that

$$(1.8a) \quad A_{jk} = \frac{1}{n^2-1}(n(K^i_{jik} - K'^i_{jik}) + (K^i_{kij} - K'^i_{kij})).$$

Since ω and ω' are Ricci-flat, we have $A_{jk} = 0$.

Next, we show that the existence of a Cartan connection which is Ricci-flat. Let ω' be a Cartan connection of the form $(\omega^i, \omega^i_j, \omega'_j)$ which is not necessarily Ricci-flat. If ω is a Cartan connection which is Ricci-flat, then we have by (1.8a) that

$$(1.8b) \quad A_{jk} = -\frac{1}{n^2-1}(nK'^i_{jik} + K'^i_{kij}).$$

If we conversely define A_{jk} by the equality (1.8b) and set $\omega_j = \omega'_j + A_{jk}\omega^k$, then $(\omega^i, \omega^i_j, \omega_j)$ is a desired Cartan connection.

Finally, we assume that ω is torsion-free. Then $\Omega^i_i = 0$ by Proposition 1.9 provided that $\dim M \geq 3$. \square

Proposition 1.9. *Suppose that $n \geq 3$ and let $\omega = (\omega^i, \omega^i_j, \omega_j)$ be a Cartan connection. Then, we have the following:*

- 1) If $d\Omega^i + \omega^i_j \wedge \Omega^j = 0$, then we have $K^i_{jkl} + K^i_{klj} + K^i_{ljk} = 0$.
- 2) If $d\Omega^i + \omega^i_j \wedge \Omega^j = 0$ and if $K^i_{jil} = 0$, then $\Omega^i_i = 0$.
- 3) If $\Omega^i = 0$ and if $\Omega^i_i = 0$, then we have $K_{jkl} + K_{klj} + K_{ljk} = 0$.
- 4) If $\Omega^i = 0$ and if $\Omega^i_j = 0$, then $\Omega_j = 0$.

Proof. First we will show 1). We have $\Omega^i = d\omega^i + \omega^i_j \wedge \omega^j$. Hence we have

$$\begin{aligned} & d\Omega^i + \omega^i_j \wedge \Omega^j \\ &= d\omega^i_j \wedge \omega^j - \omega^i_j \wedge d\omega^j + \omega^i_j \wedge (d\omega^j + \omega^j_k \wedge \omega^k) \\ &= d\omega^i_j \wedge \omega^j + \omega^i_j \wedge \omega^j_k \wedge \omega^k \\ &= \Omega^i_j \wedge \omega^j \\ &= \frac{1}{2} K^i_{jkl} \omega^k \wedge \omega^l \wedge \omega^j. \end{aligned}$$

It follows that $K^i_{jkl} + K^i_{klj} + K^i_{ljk} = 0$ if $d\Omega^i + \omega^i_j \wedge \Omega^j = 0$. Next, we show 2). Suppose in addition that $K^i_{jil} = 0$. Then, we have $0 = K^i_{ikl} + K^i_{kli} = K^i_{ikl} - K^i_{kil} = K^i_{ikl}$. Next, we show 3). We have

$$\begin{aligned} d\Omega^i_j &= d\omega^i_k \wedge \omega^k_j - \omega^i_k \wedge d\omega^k_j + d\omega^i \wedge \omega_j - \omega^i \wedge d\omega_j - \delta^i_j (d\omega_k \wedge \omega^k - \omega_k \wedge d\omega^k) \\ &= (\Omega^i_k - \omega^i_l \wedge \omega^l_k - \omega^i \wedge \omega_k + \delta^i_k \omega_l \wedge \omega^l) \wedge \omega^k_j \\ &\quad - \omega^i_k \wedge (\Omega^k_j - \omega^k_l \wedge \omega^l_j - \omega^k \wedge \omega_j + \delta^k_j \omega_l \wedge \omega^l) \\ &\quad + (\Omega^i - \omega^i_k \wedge \omega^k) \wedge \omega_j - \omega^i \wedge (\Omega_j - \omega_k \wedge \omega^k_j) \\ &\quad - \delta^i_j ((\Omega_k \wedge \omega^k - \omega_l \wedge \omega^l_k) \wedge \omega^k - \omega_k \wedge (\Omega^k + \omega^k_l \wedge \omega^l)) \\ &= \Omega^i_k \wedge \omega^k_j - \omega^i_k \wedge \Omega^k_j + \Omega^i \wedge \omega_j - \omega^i \wedge \Omega_j - \delta^i_j (\Omega_k \wedge \omega^k - \omega_k \wedge \Omega^k). \end{aligned}$$

Taking the trace, we obtain

$$d\Omega^i_i = (n+1)(\Omega^i \wedge \omega_i - \omega^i \wedge \Omega_i).$$

If $\Omega^i = 0$ and if $\Omega^i_i = 0$, then we have $\omega^i \wedge \Omega_i = 0$. Hence $K_{jkl} + K_{klj} + K_{ljk} = 0$. Finally, we show 4). If $\Omega^i = 0$ and if $\Omega^i_j = 0$, then we have $\omega^i \wedge \Omega_j = 0$ by 3). As $n \geq 3$, we have $\Omega_i = 0$. \square

2. CARTAN CONNECTIONS, AFFINE CONNECTIONS AND PROJECTIVE STRUCTURES

We follow the arguments in [5], taking torsions into account.

First, we briefly recall bundles of formal frames $\tilde{P}^r(M)$ and groups \tilde{G}^r which act on $\tilde{P}^r(M)$ on the right [1], where $r = 1, 2$.

Let M be a manifold, and $P^r(M)$ and G^r the bundle of r -frames and the group of r -jets [4].

Definition 2.1. 1) We set $\tilde{P}^1(M) = P^1(M)$ and $\tilde{G}^1 = G^1 \cong \text{GL}_n(\mathbb{R})$.

2) We set $\tilde{G}^2 = \text{GL}_n(\mathbb{R}) \times \mathbb{R}^{n^3}$, where the multiplication law is given by $(a^i_j, a^i_{jk})(b^j_i, b^j_{ik}) = (a^i_l b^l_j, a^i_l b^l_{jk} + a^i_{lm} b^l_j b^m_k)$ which is the same as the one in G^2 . Indeed, $G^2 = \{(a^i_j, a^i_{jk}) \in \tilde{G}^2 \mid a^i_{jk} = a^i_{kj}\}$.

The group \tilde{G}^2 consists of the 1-jets of certain bundle homomorphisms, and the bundle $\tilde{P}^2(M)$ is a principal \tilde{G}^2 -bundle which also consists of the 1-jets of certain bundle homomorphisms. We have $\tilde{P}^2(M) = P^2(M) \times_{G^2} \tilde{G}^2$.

In view of Remark 1.4, we introduce the following

Definition 2.2. We define a subgroup H^2 of \tilde{G}^2 by setting

$$H^2 = \{(a^i_j, a^i_{jk}) \in \tilde{G}^2 \mid \exists a_i, a^i_{jk} = -(a^i_j a_k + a_j a^i_k)\}.$$

We regard (a^i_j, a_j) as coordinates for H^2 .

It is easy to see that H^2 is indeed a subgroup of \tilde{G}^2 isomorphic to H and satisfies $G^1 = \tilde{G}^1 < H^2 < G^2 < \tilde{G}^2$.

Definition 2.3. 1) A *projective structure* on M is a subbundle P of $\tilde{P}^2(M)$ with structure group H^2 .

2) A *projective connection* associated with a projective structure P is a Cartan connection $\omega = (\omega^i, \omega^i_j, \omega_j)$ on P such that ω^i coincides with the restriction of the canonical form of order 0 to P . In order to distinguish from TW-connections, we refer to projective connections also as *Cartan projective connections*.

Remark 2.4. Let (θ^i, θ^i_j) be the canonical form on $\tilde{P}^2(M)$. We set $\Theta^i = d\theta^i + \theta^i_j \wedge \theta^j$. Then we have $\sigma^* \Omega^i = \sigma^* \Theta^i$. We have $\Theta^i = 0$ on $P^2(M)$. Indeed, this is just the structural equation. See [1] for details.

Theorem 2.5 (cf. [6, Theorem 7]). *For each projective structure P of a manifold M , there is a projective connection $\omega = (\omega^i, \omega^i_j, \omega_j)$ with the projective structure P . If $n \geq 2$, then there exists a unique ω with the following properties:*

- 1) (ω^i, ω^i_j) coincides with the restriction of the canonical form on $\tilde{P}^2(M)$ to P .
- 2) $K^i_{jil} = 0$.

If moreover ω is torsion-free, namely, if $\Omega^i = 0$, then $\Omega^i_i = 0$, or equivalently, $K^i_{ikl} = 0$.

Proof. This is a consequence of Proposition 1.8. Indeed, the restriction of the canonical form satisfies the conditions in Remark 1.7. If $n = 2$, then the last part will be later shown as Lemma 2.24. \square

Remark 2.6. *Theorem 2.5 is well-known in the torsion-free case. Since we do not assume projective structures to be torsion-free, we need canonical forms on $\tilde{P}^2(M)$ which realize torsions. A point is that the condition $\Omega^i_i = 0$ is not needed for the uniqueness in Proposition 1.8.*

Remark 2.7. *Let (U, φ) be a chart. Then, $u \in \tilde{P}^2(M)|_U$ naturally corresponds to $(u^i, u^i_j, u^i_{jk}) \in \mathbb{R}^n \times \text{GL}_n(\mathbb{R}) \times \mathbb{R}^{n^3}$, which are called the natural coordinates ([5, p. 225], [1, Definition 1.8]). If $u \in P^2(M)$ and if u is represented by $f: \mathbb{R}^n \rightarrow M$, then $(u^i, u^i_j, u^i_{jk}) = (f^i(o), DF^i_j(o), D^2F^i_{jk}(o))$. The canonical form (θ^0, θ^1)*

is represented as

$$\begin{aligned}\theta^0_u &= v^i_\alpha du^\alpha, \\ \theta^1_u &= v^i_\alpha du^\alpha_j - v^i_\alpha u^\alpha_{j\beta} v^\beta_\gamma du^\gamma,\end{aligned}$$

where $(v^i_j) = (u^i_j)^{-1}$.

Definition 2.8. Let $n \geq 2$. The projective connection given by Theorem 2.5 is called the *normal projective connection* associated with P .

The following is clear.

Proposition 2.9. 1) *There is a one-to-one correspondence between the following objects:*

- a) *Sections from M to $\tilde{P}^2(M)/\tilde{G}^1$.*
- b) *Sections from $\tilde{P}^1(M)$ to $\tilde{P}^2(M)$ equivariant under the \tilde{G}^1 -action.*
- c) *Affine connections on M .*

2) *There is a one-to-one correspondence between the following objects:*

- a) *Sections from M to $\tilde{P}^2(M)/H^2$.*
- b) *Projective structures on M .*

If ∇ is an affine connection, then ∇ corresponds to a section from M to $\tilde{P}^2(M)/\tilde{G}^1$. Since $\tilde{G}^1 = G^1$ is a subgroup of H^2 , ∇ induces a section from M to $\tilde{P}^2(M)/H^2$, namely, a projective structure. Conversely, given a projective structure, we can find an affine connection which induces the projective structure because H^2/\tilde{G}^1 is contractible.

We introduce the following definition after [4] (see also Tanaka [9], Weyl [11]).

Definition 2.10. Let ∇ and ∇' be linear connections on TM . Let ω and ω' be the connection forms of associated connection on $P^1(M)$. We say that ∇ and ∇' are *projectively equivalent* if there is an \mathfrak{m}^* -valued function, say p , on $P^1(M)$ such that

$$\omega' - \omega = [\theta, p],$$

where θ denotes the canonical form on $P^1(M)$.

Note that p necessarily satisfy $R_g^* p = pg$, where $g \in \text{GL}_n(\mathbb{R})$.

Remark 2.11. *The torsion is invariant under the projective equivalences in the sense of Definition 2.10. On the other hand, we can consider the usual equivalence relation based on unparameterized geodesics, then any affine connection is equivalent to a torsion-free one. See Corollary 2.26 and Remark 2.27.*

Lemma 2.12. *Linear connections ∇ and ∇' on TM are projectively equivalent if and only if there is a 1-form, say ρ , on M such that $\nabla' - \nabla = \rho \otimes \text{id} + \text{id} \otimes \rho$.*

Proof. If ∇ and ∇' are projectively equivalent, then there is an \mathfrak{m}^* -valued function p such that $\omega' - \omega = [\theta, p]$. If $x \in M$ and if $v \in T_x M$, then we fix a frame u of $T_x M$

and represent $v = uw$. We set $\rho_x(v) = p(u)w$, and we have $\nabla' - \nabla = \rho \otimes \text{id} + \text{id} \otimes \rho$. Conversely if $\nabla' - \nabla = \rho \otimes \text{id} + \text{id} \otimes \rho$ holds for a 1-form ρ . Let $u = (e_1, \dots, e_n)$ be a frame and (e^1, \dots, e^n) its dual. We represent ρ as $\rho = \rho_1 e^1 + \dots + \rho_n e^n$ and set $p(u) = (\rho_1, \dots, \rho_n)$. Then we have $\omega' - \omega = [\theta, p]$. \square

Remark 2.13. Let (x^1, \dots, x^n) be local coordinates and choose $\left(\frac{\partial}{\partial x^1}, \dots, \frac{\partial}{\partial x^n}\right)$ as a frame. If we represent ρ as $\rho = \rho_i dx^i$, then we have

$$\begin{aligned} (\rho \otimes \text{id})^i_{jk} &= \delta^i_j \rho_k, \\ (\text{id} \otimes \rho)^i_{jk} &= \delta^i_k \rho_j, \end{aligned}$$

$$\text{where } \delta^i_j = \begin{cases} 1, & i = j, \\ 0, & i \neq j. \end{cases}$$

Lemma 2.14. If we have $\nabla' - \nabla = \rho \otimes \text{id} + \text{id} \otimes \rho = \rho' \otimes \text{id} + \text{id} \otimes \rho'$, then $\rho' = \rho$.

Proof. We have $(\rho \otimes \text{id} + \text{id} \otimes \rho)(e_i, e_i) = 2\rho(e_i)$. Hence $\rho(e_i) = 0$ if $\rho \otimes \text{id} + \text{id} \otimes \rho = 0$. \square

We will make use of the Christoffel symbols reversing the order of lower indices. This is convenient when formal frames are considered.

Notation 2.15. We set $\Gamma^i_{jk} = dx^i \left(\nabla \frac{\partial}{\partial x^k} \frac{\partial}{\partial x^j} \right)$.

Lemma 2.16. Affine connections ∇ and ∇' induce the same projective structure if and only if they are projectively equivalent.

Proof. Let Γ^i_{jk} and Γ'^i_{jk} be the Christoffel symbols for ∇ and ∇' , respectively. Then, ∇ corresponds to a section from M to $\tilde{P}^2(M)/\tilde{G}^1$ represented by $x \mapsto \sigma_\nabla(x) = (x, \delta^i_j, -\Gamma^i_{jk})$. Then, sections σ_∇ and $\sigma_{\nabla'}$ determine the same projective structure if and only if there is an H^2 -valued function, say $a = (a^i_j, -(a^i_j a_k + a_j a^i_k))$ such that $\sigma_\nabla \cdot a = \sigma_{\nabla'}$. This condition is equivalent to that

$$(x, a^i_j, -\Gamma^i_{lm} a^l_j a^m_k - (a^l_j a_k + a_j a^l_k)) = (x, \delta^i_j, -\Gamma'^i_{jk}).$$

holds in $\tilde{P}^2(M)/\tilde{G}^1$. The left hand side is equal to $(x, \delta^i_j, -\Gamma^i_{jk} - (\delta^i_j a_k + \delta^i_k a_j))$. Hence ∇ and ∇' correspond to the same projective structure if and only if we have $\Gamma'^i_{jk} = \Gamma^i_{jk} + \delta^i_j a_k + \delta^i_k a_j$, that is, ∇ and ∇' are projectively equivalent. \square

Remark 2.17. Affine connections decide geodesics and hence projective structures. The most standard projective structure is the one on $\mathbb{R}P^n$ and equivalences should be described in terms of linear fractional transformations even if we allow torsions. This leads to above definitions. Recall that projective structures are considered to be the same if they have the same (unparameterized) geodesics and the same torsions in this article.

Let ∇ be an affine connection. We will describe the projective structure given by ∇ and the associated normal projective connection. For this purpose, we introduce the following

Definition 2.18. Let ∇ be an affine connection and $\{\Gamma^i_{jk}\}$ the Christoffel symbols with respect to a chart. We define one-forms μ and ν by setting $\mu_j = \frac{1}{2}(\Gamma^\alpha_{\alpha j} - \Gamma^\alpha_{j\alpha})$ and $\nu_j = -\frac{1}{2(n+1)}(\Gamma^\alpha_{\alpha j} + \Gamma^\alpha_{j\alpha})$. We refer to μ as the *reduced torsion* of ∇ .

Remark 2.19. 1) The differential form $\Gamma^\alpha_{\alpha j} dx^j$ is the connection form of the connection on $\mathcal{E}(M)$ induced by ∇ . The other differential form $\Gamma^\alpha_{k\alpha} dx^k$ also correspond to a connection on $\mathcal{E}(M)$. These connections are the same if ∇ is torsion-free.

2) The differential form $-\mu = -\mu_j dx^j$ is a kind of the Ricci tensor of the torsion.

Cartan connections can be found as follows.

Lemma 2.20. Let $(\omega^i, \omega^i_j, \omega_j)$ be a Cartan connection on P . Let $\sigma: U \rightarrow P$ be a section, and set $\psi^i = \sigma^* \omega^i = \Pi^i_j dx^j$, $\psi^i_j = \sigma^* \omega^i_j = \Pi^i_{jk} dx^k$ and $\psi_j = \sigma^* \omega_j = \Pi_{jk} dx^k$. Let (a^i_j, a_j) be the coordinates for H^2 as in Definition 2.2 and (x^i, a^i_j, a_j) be the product coordinates for $P|_U \cong U \times H^2$, where the identification is given by σ . If we set $(b^i_j) = (a^i_j)^{-1}$, then we have

$$\begin{aligned} \omega^i &= b^i_\alpha \psi^\alpha \\ &= b^i_\alpha \Pi^\alpha_\beta dx^\beta, \\ \omega^i_j &= b^i_\alpha da^\alpha_j + b^i_\alpha \psi^\alpha_\beta a^\beta_j + b^i_\alpha \psi^\alpha a_j + \delta^i_j a_\alpha b^\alpha_\beta \psi^\beta \\ &= b^i_\alpha da^\alpha_j + b^i_\alpha \Pi^\alpha_{\beta\gamma} a^\beta_j dx^\gamma + b^i_\alpha \Pi^\alpha_\beta a_j dx^\beta + \delta^i_j a_\alpha b^\alpha_\beta \Pi^\beta_\gamma dx^\gamma \\ \omega_j &= da_j - a_\alpha b^\alpha_\beta da^\beta_j - a_\alpha b^\alpha_\beta \psi^\beta_\gamma a^\gamma_j + \psi_\alpha a^\alpha_j - a_\alpha b^\alpha_\beta \psi^\beta a_j \\ &= da_j - a_\alpha b^\alpha_\beta da^\beta_j - a_\alpha b^\alpha_\beta \Pi^\beta_{\gamma\delta} a^\gamma_j dx^\delta + \Pi_{\alpha\beta} a^\alpha_j dx^\beta - a_\alpha b^\alpha_\beta \Pi^\beta_\gamma a_j dx^\gamma. \end{aligned}$$

Let U be a chart of M and x^i the local coordinates on U .

Proposition 2.21. Suppose that $n \geq 2$ and let $\omega = (\omega^i, \omega^i_j, \omega_j)$ be the normal projective connection for the projective structure P determined by ∇ . Then, there is a unique section $\sigma: U \rightarrow P$ with the following properties:

- 1) We have $\sigma^* \omega^i = dx^i$.
- 2) If we set $\sigma^* \omega^i_j = \Psi^i_j = \Pi^i_{jk} dx^k$, then we have $\Pi^i_{ik} = \mu_k$.

We have moreover that

$$2') \Pi^i_{ji} = -\mu_j,$$

and

$$\begin{aligned}\Pi^i_{jk} &= \Gamma^i_{jk} + \delta^i_j \nu_k + \delta^i_k \nu_j \\ &= \Gamma^i_{jk} - \frac{1}{2(n+1)} (\delta^i_j (\Gamma^\alpha_{\alpha k} + \Gamma^\alpha_{k\alpha}) + \delta^i_k (\Gamma^\alpha_{\alpha j} + \Gamma^\alpha_{j\alpha})), \\ \Pi_{jk} &= \frac{-1}{n^2-1} \left(n \left(\frac{\partial \Pi^i_{jk}}{\partial x^i} + \frac{\partial \mu_j}{\partial x^k} - \mu_\alpha \Pi^\alpha_{jk} - \Pi^\alpha_{j\beta} \Pi^\beta_{\alpha k} \right) \right. \\ &\quad \left. + \left(\frac{\partial \Pi^i_{kj}}{\partial x^i} + \frac{\partial \mu_k}{\partial x^j} - \mu_\alpha \Pi^\alpha_{kj} - \Pi^\alpha_{k\beta} \Pi^\beta_{\alpha j} \right) \right),\end{aligned}$$

where $\{\Gamma^i_{jk}\}$ denote the Christoffel symbols and $\sigma^* \omega_j = \Psi_j = \Pi_{jk} dx^k$. Finally, we can exchange conditions 2) and 2').

Proof. Let σ_0 be the section from M to $\tilde{P}^2(M)/\tilde{G}^1$ given by the connection, namely, $\sigma_0(x) = (x^i, \delta^i_j, -\Gamma^i_{jk})$. Let $\bar{\sigma}_0$ denote the section from M to $\tilde{P}^2(M)/H^2$ induced by σ_0 . By the condition 1), σ should be of the form $\bar{\sigma}_0.h$, where $h = (\delta^i_j, -(\delta^i_k \nu'_j + \delta^i_j \nu'_k))$ for some ν'_j . If $\sigma(x) = (x^i, \delta^i_j, -\Pi^i_{jk})$, then we have $\Pi^i_{jk} = \Gamma^i_{jk} + \delta^i_j \nu'_k + \delta^i_k \nu'_j$ (see Remark 2.7). Suppose that ν'_j can be so chosen that $\Pi^i_{ik} = \mu_k$ or $\Pi^i_{ji} = -\mu_j$. Then, we accordingly have

$$\begin{aligned}\mu_k &= \Pi^i_{ik} = \Gamma^i_{ik} + (n+1)\nu'_k, \text{ or} \\ -\mu_j &= \Pi^i_{ji} = \Gamma^i_{ji} + (n+1)\nu'_j.\end{aligned}$$

The both conditions are equivalent to

$$(n+1)\nu'_k = -\frac{1}{2}(\Gamma^\alpha_{\alpha k} + \Gamma^\alpha_{k\alpha}).$$

Hence we have $\nu' = \nu$ in the both cases. The uniqueness also holds. Conversely, if we define Π^i_{jk} as in the statement and if we set $\sigma(x) = (x^i, \delta^i_j, -\Pi^i_{jk})$, then σ induces a section to $\tilde{P}^2(M)/H^2$ by Lemma 2.23 below. We have $\sigma^* \omega^i = dx^i$ and $\sigma^* \omega^i_j = \Psi^i_j$. If we set $\Psi_j = \sigma^* \omega_j$, then we have

$$(2.21a) \quad \sigma^* \Omega^i_j = d\Psi^i_j + \Psi^i_k \wedge \Psi^k_j + dx^i \wedge \Psi_j - \delta^i_j \Psi_k \wedge dx^k.$$

If we define k^i_{jkl} by the conditions that $\sigma^* \Omega^i_j = \frac{1}{2} k^i_{jkl} dx^k \wedge dx^l$ and $k^i_{jkl} + k^i_{jlk} = 0$, then (2.21a) is equivalent to

$$k^i_{jkl} = \frac{\partial \Pi^i_{jl}}{\partial x^k} - \frac{\partial \Pi^i_{jk}}{\partial x^l} + \Pi^i_{\alpha k} \Pi^\alpha_{jl} - \Pi^i_{\alpha l} \Pi^\alpha_{jk} + \delta^i_k \Pi_{jl} - \delta^i_l \Pi_{jk} - \delta^i_j (\Pi_{lk} - \Pi_{kl}).$$

Since ω is a normal projective connection, we have

$$\begin{aligned}0 &= k^i_{jil} \\ &= \frac{\partial \Pi^i_{jl}}{\partial x^i} - \frac{\partial \Pi^i_{ji}}{\partial x^l} + \Pi^i_{\alpha i} \Pi^\alpha_{jl} - \Pi^i_{\alpha l} \Pi^\alpha_{ji} + n\Pi_{jl} - \Pi_{jl} - (\Pi_{lj} - \Pi_{jl}) \\ &= \frac{\partial \Pi^i_{jl}}{\partial x^i} + \frac{\partial \mu_j}{\partial x^l} - \mu_\alpha \Pi^\alpha_{jl} - \Pi^i_{\alpha l} \Pi^\alpha_{ji} + n\Pi_{jl} - \Pi_{lj}.\end{aligned}$$

Regarding this equality as an equation with respect to Π_{jk} , we see that Π_{jk} is given as in the statement. \square

Remark 2.22. *If we replace ν_j by $-\frac{1}{2(n+1)}(a\Gamma_{\alpha j}^\alpha + b\Gamma_{j\alpha}^\alpha)$ in Definition 2.18, then Proposition 2.21 holds after replacing the conditions by*

$$\begin{aligned}\Pi_{\alpha k}^\alpha &= \left(1 - \frac{a}{2}\right)\Gamma_{\alpha k}^\alpha - \frac{b}{2}\Gamma_{k\alpha}^\alpha, \\ \Pi_{j\alpha}^\alpha &= -\frac{a}{2}\Gamma_{\alpha k}^\alpha + \left(1 - \frac{b}{2}\right)\Gamma_{k\alpha}^\alpha.\end{aligned}$$

These are proportional to the reduced torsion if and only if $a + b = 2$. We choose $a = b = 1$ as the simplest case, taking symmetricity into account. The situation is similar in Theorem 4.28.

As in the classical case, we have the following. We choose a branch of the logarithmic function in the complex category.

Lemma 2.23. *Let (U, φ) and $(\widehat{U}, \widehat{\varphi})$ be charts. We assume that $U = \widehat{U}$ and set $\psi = \widehat{\varphi} \circ \varphi^{-1}$. If σ and $\widehat{\sigma}$ denote the sections given by Proposition 2.21, then we have*

$$\psi_*\sigma = \widehat{\sigma} \cdot (a_j^i, -(a_j a_k^i + a_k a_j^i)),$$

where $a_j^i = D\psi^i_j$ and $a_j = -\frac{1}{n+1} \frac{\partial \log J\psi}{\partial x^j}$ with $J\psi = \det D\psi$.

Proof. We have

$$\Gamma_{jk}^i = (D\psi^{-1})^\alpha_i H\psi^\alpha_{jk} + (D\psi^{-1})^\alpha_i \widehat{\Gamma}^\alpha_{\beta\gamma} D\psi^\beta_j D\psi^\gamma_k,$$

where D denotes the derivative and H denotes the Hessian. It follows that

$$\begin{aligned}\Pi_{jk}^i &= (D\psi^{-1})^\alpha_i H\psi^\alpha_{jk} + (D\psi^{-1})^\alpha_i \widehat{\Gamma}^\alpha_{\beta\gamma} D\psi^\beta_j D\psi^\gamma_k \\ &\quad - \frac{1}{2(n+1)} \delta^i_j \left(\left(\frac{\partial \log J}{\partial x^k} + \widehat{\Gamma}^\alpha_{\alpha\beta} D\psi^\beta_k \right) + \left(\frac{\partial \log J}{\partial x^k} + \widehat{\Gamma}^\alpha_{\gamma\alpha} D\psi^\gamma_k \right) \right) \\ &\quad - \frac{1}{2(n+1)} \delta^i_k \left(\left(\frac{\partial \log J}{\partial x^j} + \widehat{\Gamma}^\alpha_{\alpha\beta} D\psi^\beta_j \right) + \left(\frac{\partial \log J}{\partial x^j} + \widehat{\Gamma}^\alpha_{\gamma\alpha} D\psi^\gamma_j \right) \right) \\ &= (D\psi^{-1})^\alpha_i H\psi^\alpha_{jk} + (D\psi^{-1})^\alpha_i \widehat{\Pi}^\alpha_{\beta\gamma} D\psi^\beta_j D\psi^\gamma_k \\ &\quad - \frac{1}{n+1} \left(\delta^i_j \frac{\partial \log J}{\partial x^k} + \delta^i_k \frac{\partial \log J}{\partial x^j} \right),\end{aligned}$$

from which the lemma follows. \square

If ∇ is torsion-free, then Π_{jk}^i and Π_{jk} are well-known as follows [5, Proposition 17], [7, Fundamental theorem for TW-connections].

Lemma 2.24. *If ∇ is torsion-free, then we have $\mu_j = 0$ and $\Pi^i_{jk} = \Pi^i_{kj}$. We have*

$$\begin{aligned}\Pi^i_{jk} &= \Gamma^i_{jk} - \frac{1}{n+1}(\delta^i_j \Gamma^\alpha_{\alpha k} + \delta^i_k \Gamma^\alpha_{\alpha j}), \\ \Pi_{jk} &= \Pi_{kj} = -\frac{1}{n-1} \left(\frac{\partial \Pi^i_{jk}}{\partial x^i} - \Pi^\alpha_{j\beta} \Pi^\beta_{\alpha k} \right).\end{aligned}$$

Moreover, $\Omega^i_{ikl} = 0$.

Proof. The first part is straightforward. To show that Ω^i_j is trace-free, it suffices to show that $k^i_{ikl} = 0$. We have

$$\begin{aligned}k^i_{ikl} &= \frac{\partial \Pi^i_{il}}{\partial x^k} - \frac{\partial \Pi^i_{ik}}{\partial x^l} + \Pi^i_{\alpha k} \Pi^\alpha_{il} - \Pi^i_{\alpha l} \Pi^\alpha_{ik} + \Pi_{kl} - \Pi_{lk} - n(\Pi_{lk} - \Pi_{kl}) \\ &= \frac{\partial \mu_l}{\partial x^k} - \frac{\partial \mu_k}{\partial x^l} + (n+1)(\Pi_{kl} - \Pi_{lk}) \\ &= 0.\end{aligned}$$

□

In this article, we are working with projective structures keeping torsion invariant. If we allow to modify torsions, we have the following lemma and corollary [11], [6, Lemma 11]. We include a sketch of a proof for completeness.

Lemma 2.25. *Let ∇ and $\bar{\nabla}$ be connections of which the Christoffel symbols are $\{\Gamma^i_{jk}\}$ and $\{\bar{\Gamma}^i_{jk}\}$. Then, the unparameterized geodesics of ∇ and $\bar{\nabla}$ are the same if and only if $\bar{\Gamma}^i_{jk} = \Gamma^i_{jk} + \delta^i_j \varphi_k + \delta^i_k \varphi_j + a^i_{jk}$, where $\{\varphi_k\}$ are components of a 1-form of M , and $\{a^i_{jk}\}$ are components of TM -valued 2-form on M such that $a^i_{kj} = -a^i_{jk}$.*

Proof. We follow the proof of [5, Proposition 12]. We only show that the geodesic equation of ∇ and $\bar{\nabla}$ are equivalent. Let s and \bar{s} be parameters of geodesic of ∇ and $\bar{\nabla}$, respectively. Writing down the geodesic equation, we have

$$\begin{aligned}0 &= \frac{d^2 x^i}{d\bar{s}^2} + \bar{\Gamma}^i_{jk} \frac{dx^j}{d\bar{s}} \frac{dx^k}{d\bar{s}} \\ &= \left(\frac{d^2 x^i}{ds^2} + \Gamma^i_{jk} \frac{dx^j}{ds} \frac{dx^k}{ds} \right) \left(\frac{ds}{d\bar{s}} \right)^2 + \frac{dx^i}{ds} \left(2\varphi_j \frac{dx^j}{d\bar{s}} + \frac{d^2 s}{d\bar{s}^2} \right) + a^i_{jk} \frac{dx^j}{d\bar{s}} \frac{dx^k}{d\bar{s}} \\ &= \left(\frac{d^2 x^i}{ds^2} + \Gamma^i_{jk} \frac{dx^j}{ds} \frac{dx^k}{ds} \right) \left(\frac{ds}{d\bar{s}} \right)^2 + \frac{dx^i}{ds} \left(2\varphi_j \frac{dx^j}{d\bar{s}} + \frac{d^2 s}{d\bar{s}^2} \right),\end{aligned}$$

because $a^i_{kj} = -a^i_{jk}$. Hence, it suffices to solve the equation $2\varphi_j \frac{dx^j}{d\bar{s}} + \frac{d^2 s}{d\bar{s}^2} = 0$. □

Corollary 2.26. *Given an affine connection ∇ , we can find a torsion-free affine connection $\bar{\nabla}$ of which the geodesics are the same.*

Proof. Let T be the torsion of ∇ . It suffices to set $\bar{\nabla} = \nabla + \frac{1}{2}T$. □

Remark 2.27. A projective connection similar to the normal projective connection as in Theorem 2.5 is given by Hlavatý [2]. We refer to this connection as the Hlavatý connection. The components of the Hlavatý connection is given by

$$\Phi^i_{jk} = \Gamma^i_{jk} + \frac{1}{n^2 - 1} (\delta^i_j (\Gamma^\alpha_{k\alpha} - n\Gamma^\alpha_{\alpha k}) + \delta^i_k (\Gamma^\alpha_{\alpha j} - n\Gamma^\alpha_{j\alpha})).$$

We have $\Phi^\alpha_{\alpha k} = 0$ and $\Phi^\alpha_{j\alpha} = 0$. The Hlavatý connection can be obtained as follows. First consider an affine connection $\bar{\nabla}$ of which the Christoffel symbols $\{\bar{\Gamma}^i_{jk}\}$ are given by

$$\bar{\Gamma}^i_{jk} = \Gamma^i_{jk} - \frac{1}{n-1} (\delta^i_j \mu_k - \delta^i_k \mu_j).$$

The geodesics of ∇ and $\bar{\nabla}$ are the same. On the other hand, if T and \bar{T} denote the torsion of ∇ and $\bar{\nabla}$, then we have $\bar{T}^i_{jk} = T^i_{jk} + \frac{2}{n-1} (\delta^i_j \mu_k - \delta^i_k \mu_j)$. We have

$$\begin{aligned} \bar{\Gamma}^\alpha_{\alpha k} &= \Gamma^\alpha_{\alpha k} - \mu_k = \frac{1}{2} (\Gamma^\alpha_{\alpha k} + \Gamma^\alpha_{k\alpha}) = -(n+1)\nu_k, \\ \bar{\Gamma}^\alpha_{j\alpha} &= \Gamma^\alpha_{j\alpha} + \mu_j = \frac{1}{2} (\Gamma^\alpha_{\alpha j} + \Gamma^\alpha_{j\alpha}) = -(n+1)\nu_j. \end{aligned}$$

Hence we have

$$\begin{aligned} \bar{\mu}_j &= \frac{1}{2} (\bar{\Gamma}^\alpha_{\alpha j} - \bar{\Gamma}^\alpha_{j\alpha}) = 0, \\ \bar{\nu}_j &= -\frac{1}{2(n+1)} (\bar{\Gamma}^\alpha_{\alpha j} + \bar{\Gamma}^\alpha_{j\alpha}) = \nu_j. \end{aligned}$$

By some straightforward calculations, we see that $\bar{\Pi}^i_{jk} = \Phi^i_{jk}$. Note that we have $\Phi^i_{jk} - \Pi^i_{jk} = \bar{\Gamma}^i_{jk} - \Gamma^i_{jk} = -\frac{1}{n-1} (\delta^i_j \mu_k - \delta^i_k \mu_j)$. As $\bar{\mu}_j = 0$, we have

$$\bar{\Pi}_{jk} = \frac{-1}{n^2 - 1} \left(n \left(\frac{\partial \Pi^i_{jk}}{\partial x^i} - \Pi^\alpha_{j\beta} \Pi^\beta_{\alpha k} \right) + \left(\frac{\partial \Pi^i_{kj}}{\partial x^i} - \Pi^\alpha_{k\beta} \Pi^\beta_{\alpha j} \right) \right).$$

3. GEODESICS AND COMPLETENESS, FLATNESS OF PROJECTIVE STRUCTURES

Carefully examining arguments in [5, Sections 7 and 8], we see that results presented there remain valid for projective structures with torsion. We always consider equivalences in the sense of Definition 2.10, namely, we require the geodesics to be the same and also the torsions are the same.

As mentioned in the previous section, we have the following

Proposition 3.1 ([11], [5, Proposition 12]). *Let P be a projective structure of M and ∇ an affine connection which belongs to P . If we disregard parametrizations, then geodesics of ∇ are geodesics of P and vice versa.*

Definition 3.2. 1) Let M and M' be manifolds with projective structures P and P' . A diffeomorphism $f: M \rightarrow M'$ is said to be a *projective isomorphism* if $f_*: \tilde{P}^2(M) \rightarrow \tilde{P}^2(M')$ induces a bundle isomorphism from P to P' .

- 2) Let M and M' be manifolds with projective structures P and P' . A mapping $f: M \rightarrow M'$ is said to be a *projective morphism* if for each $p \in M$, there exists an open neighborhood U of p such that the restriction of f to U is a projective isomorphism to its image.
- 3) A projective structure P on a manifold M is said to be *flat*, if for each $p \in M$, there exists an open neighborhood U of p and a projective isomorphism from U to an open subset of $\mathbb{R}P^n$, where $n = \dim M$.

If a projective structure P is flat, then the normal projective connection is torsion-free. Hence we are in the classical settings so that we have the following.

Theorem 3.3 ([5, Theorem 15]). *A projective structure P of a manifold M is flat if and only if the torsion and the curvature of the normal projective connection vanish.*

Remark 3.4. *We also have estimates of the dimension of transformation groups which concern projective structures. The results are parallel to Theorems 13 and 14 of [5].*

4. THOMAS–WHITEHEAD CONNECTIONS

We follow arguments by Roberts [7]. Projective structures are described by means of connections on bundle of volumes. Such connections are called Thomas–Whitehead connections.

Definition 4.1. Let M be a manifold of dimension n . If M is orientable, then let $\mathcal{E}(M)$ be the principal $\mathbb{R}_{>0}$ -bundle associated with $\bigwedge^n TM$. If M is non-orientable, we consider $\mathcal{E}(M)/\{\pm 1\}$. We equip an \mathbb{R} -action on $\mathcal{E}(M)$ by setting $va = ve^a$ for $v \in \mathcal{E}(M)$ and $a \in \mathbb{R}$. We call $\mathcal{E}(M)$ the *bundle of volume elements* over M .

Lemma 4.2. *The bundle of volume elements $\mathcal{E}(M)$ is a principal \mathbb{R} -bundle.*

Proof. If M is orientable, then we only consider charts compatible with the orientation. Let (U, φ) be a chart. Then, $TM|_U$ is trivialized by $\left\{ \frac{\partial}{\partial x^i} \right\}$ so that $\mathcal{E}(M)|_U$ is trivialized by $\epsilon = \frac{\partial}{\partial x^1} \wedge \cdots \wedge \frac{\partial}{\partial x^n}$. Indeed, if $p \in U$ and if $v_p \in \mathcal{E}_p(M)$, then we have $v_p = a\epsilon_p$ for some $a > 0$. Hence we can associate with v_p a pair $(\epsilon_p, \log a)$. In other words, the inverse of the mapping $(x^1, x^2, \dots, x^n, x^{n+1}) \mapsto (\varphi^{-1}(x^1, \dots, x^n), \epsilon_{\varphi^{-1}(x^1, \dots, x^n)} e^{x^{n+1}})$ is a local trivialization of $\mathcal{E}(M)$. If $(\widehat{U}, \widehat{\varphi})$ is another chart and if ψ is the transition function from U to \widehat{U} , then we have $\widehat{\epsilon} \det D\psi = \epsilon$. Hence the transition function from $\mathcal{E}(M)|_U$ to $\mathcal{E}(M)|_{\widehat{U}}$ is given by $(p, t) \mapsto (p, t + \log \det D\psi)$ if M is orientable and $(p, t) \mapsto (p, t + \log |\det D\psi|)$ if M is non-orientable. \square

Remark 4.3. *In the complex category, we fix branches of the logarithms when choosing local trivializations.*

Definition 4.4. We locally set $\Psi = e^{-x^{n+1}} dx^1 \wedge \cdots \wedge dx^n \wedge dx^{n+1}$ and call Ψ the *canonical positive odd density*.

Remark 4.5. If M is orientable, then Ψ is indeed an $(n+1)$ -form.

Definition 4.6. For $a \in \mathbb{R}$ and $v \in \mathcal{E}(M)$, we set $R_a v = v.a$. Let $\text{Lie}(\mathbb{R})$ denote the Lie algebra of \mathbb{R} . If $b \in \text{Lie}(\mathbb{R})$, then the vector field X defined by $X_u = \left. \frac{\partial}{\partial t} R_{bt} u \right|_{t=0}$ is called the *fundamental vector field* associated with b . In particular, the fundamental vector field associate with $1 \in \text{Lie}(\mathbb{R})$ is called the *canonical fundamental vector field* and denoted by ξ .

We can reduce the definition of connection forms on $\mathcal{E}(M)$ as follows.

Definition 4.7. A $\text{Lie}(\mathbb{R})$ -valued 1-form $\underline{\omega}$ on $\mathcal{E}(M)$ is called a *connection form* if we have

- 1) $\underline{\omega}(\xi) = 1$, and
- 2) $R_a^* \underline{\omega} = \text{Ad}_{-a} \underline{\omega} = \underline{\omega}$ for $a \in \mathbb{R}$.

Definition 4.8. We set $\mathcal{F} = \left(\frac{\partial}{\partial x^1}, \dots, \frac{\partial}{\partial x^n}, \frac{\partial}{\partial x^{n+1}} \right)$ on $T\mathcal{E}(M)$.

If ψ denotes a change of coordinates, then the transition function is given by $\begin{pmatrix} D\psi & 0 \\ \partial \log J\psi & 1 \end{pmatrix}$, where $J\psi = \det D\psi$ and $\partial \log J\psi = \left(\frac{\partial \log J\psi}{\partial x^1}, \dots, \frac{\partial \log J\psi}{\partial x^n} \right)$.

Definition 4.9 ([7], see also [10]). A *Thomas–Whitehead projective connection*, or a *TW-connection*, is a linear connection ∇ on $T\mathcal{E}(M)$ with the following properties. Let $\omega = (\omega^i_j)$ be the connection form of ∇ with respect to \mathcal{F} .

- 1) $\nabla \xi = -\frac{1}{n+1} \text{id}$, namely, we have

$$\omega^i_{n+1,j} = -\frac{\delta^i_j}{n+1},$$

$$\text{where } \delta^i_j = \begin{cases} 1, & i = j, \\ 0, & i \neq j. \end{cases}$$

- 2) We have $\omega^i_{j,n+1} = -\frac{\delta^i_j}{n+1}$.
- 3) $R_{a*}(\nabla_X Y) = \nabla_{R_{a*}X}(R_{a*}Y)$ for any $X, Y \in \mathfrak{X}(\mathcal{E}(M))$, namely, ∇ is invariant under the right action of \mathbb{R} .

We refer to ∇^ω as a *TW-connection* on TM induced by ∇ and $\underline{\omega}$.

Remark 4.10. *TW-connections* are usually assumed to be *torsion-free*. In this case, the conditions 1) and 2) in Definition 4.9 are equivalent.

Definition 4.11. Let ∇ be a TW-connection on $T\mathcal{E}(M)$ and $\underline{\omega}$ a connection form on $\mathcal{E}(M)$. If $X, Y \in \mathfrak{X}(M)$, then let $\tilde{X}, \tilde{Y} \in \mathfrak{X}(\mathcal{E}(M))$ be lifts of X, Y horizontal with respect to $\underline{\omega}$. We set

$$\nabla_{\tilde{X}}^\omega Y = \pi_* \left(\nabla_{\tilde{X}} \tilde{Y} \right),$$

where $\pi: \mathcal{E}(M) \rightarrow M$ is the projection.

Lemma 4.12 (see also Lemma 4.20). ∇^ω is a connection on TM . If ∇ is torsion-free, then so is ∇^ω .

Proof. It is easy to see that ∇^ω is a connection. If ∇ is torsion-free, then we have

$$\begin{aligned} \nabla_X^\omega Y - \nabla_Y^\omega X &= \pi_* \left(\nabla_{\tilde{X}} \tilde{Y} - \nabla_{\tilde{Y}} \tilde{X} \right) \\ &= \pi_* \left([\tilde{X}, \tilde{Y}] \right) \\ &= [\pi_* \tilde{X}, \pi_* \tilde{Y}] \\ &= [X, Y]. \end{aligned} \quad \square$$

Let ω be a connection form on $\mathcal{E}(M)$. We locally have

$$\omega = f_1 dx^1 + \cdots + f_n dx^n + dx^{n+1}$$

for some functions f_1, \dots, f_n .

Remark 4.13. 1) The functions f_1, \dots, f_n are independent of x^{n+1} by 2) of Definition 4.7.

2) Despite 1), $f_1 dx^1 + \cdots + f_n dx^n$ is not necessarily well-defined on M .

Definition 4.14. Let e_i be the horizontal lift of $\frac{\partial}{\partial x^i}$ to $T\mathcal{E}(M)$ with respect to ω , that is, we set

$$e_i = \frac{\partial}{\partial x^i} - f_i \frac{\partial}{\partial x^{n+1}}.$$

We set $e_{n+1} = \frac{\partial}{\partial x^{n+1}}$ and $\mathcal{F}^H = (e_1, \dots, e_n, e_{n+1})$.

Lemma 4.15. Let ψ be the transition function from (x^1, \dots, x^n) to $(\hat{x}^1, \dots, \hat{x}^n)$. We have

$$(4.15a) \quad (\hat{e}_1, \dots, \hat{e}_n, \hat{e}_{n+1}) \begin{pmatrix} D\psi & \\ 0 & 1 \end{pmatrix} = (e_1, \dots, e_n, e_{n+1}).$$

Proof. If we set $f = (f_1 \cdots f_n)$, then we have

$$(e_1, \dots, e_n, e_{n+1}) \begin{pmatrix} I_n & \\ f & 1 \end{pmatrix} = \left(\frac{\partial}{\partial x^1}, \dots, \frac{\partial}{\partial x^n}, \frac{\partial}{\partial x^{n+1}} \right).$$

If we set $J = \det D\psi$, then we have

$$\begin{aligned}
& (\widehat{e}_1, \dots, \widehat{e}_n, \widehat{e}_{n+1}) \begin{pmatrix} I_n \\ \widehat{f} & 1 \end{pmatrix} \begin{pmatrix} D\psi \\ D \log J & 1 \end{pmatrix} \\
&= \begin{pmatrix} \frac{\partial}{\partial \widehat{x}^1}, \dots, \frac{\partial}{\partial \widehat{x}^n}, \frac{\partial}{\partial \widehat{x}^{n+1}} \end{pmatrix} \begin{pmatrix} D\psi \\ D \log J & 1 \end{pmatrix} \\
&= \begin{pmatrix} \frac{\partial}{\partial x^1}, \dots, \frac{\partial}{\partial x^n}, \frac{\partial}{\partial x^{n+1}} \end{pmatrix} \\
&= (e_1, \dots, e_n, e_{n+1}) \begin{pmatrix} I_n \\ f & 1 \end{pmatrix}.
\end{aligned}$$

On the other hand, if we set $dx = {}^t(dx^1 \cdots dx^n)$, then we have $\underline{\omega} = (f \ 1) \begin{pmatrix} dx \\ dx^{n+1} \end{pmatrix}$.

Hence we have

$$(f \ 1) \begin{pmatrix} dx \\ dx^{n+1} \end{pmatrix} = (\widehat{f} \ 1) \begin{pmatrix} d\widehat{x} \\ d\widehat{x}^{n+1} \end{pmatrix} = (\widehat{f} \ 1) \begin{pmatrix} D\psi \\ D \log J & 1 \end{pmatrix} \begin{pmatrix} dx \\ dx^{n+1} \end{pmatrix}$$

and consequently that

$$\begin{pmatrix} I_n \\ \widehat{f} & 1 \end{pmatrix} \begin{pmatrix} D\psi \\ D \log J & 1 \end{pmatrix} = \begin{pmatrix} D\psi \\ f & 1 \end{pmatrix} = \begin{pmatrix} D\psi \\ 0 & 1 \end{pmatrix} \begin{pmatrix} I_n \\ f & 1 \end{pmatrix}.$$

Combining these equalities, we obtain the relation as desired. \square

Let ω be the connection form of a TW-connection with respect to \mathcal{F} . If we define ω' by the property

$$\omega = \omega' - \frac{1}{n+1} \begin{pmatrix} I_n dx^{n+1} & dx \\ 0 & dx^{n+1} \end{pmatrix},$$

then $\omega' = \begin{pmatrix} \alpha & 0 \\ \beta & 0 \end{pmatrix}$, where α and β do not involve dx^{n+1} . Moreover, as ∇ is invariant under the \mathbb{R} -action, α and β projects to M .

Remark 4.16. *The connection ∇ is torsion-free if and only if we have $\alpha^i_{jk} = \alpha^i_{kj}$ and $\beta^i_{jk} = \beta^i_{kj}$.*

Remark 4.17. *The transition rule of α and β under changes of coordinates is given as follows. We have*

$$\begin{aligned}
\omega &= \begin{pmatrix} D\psi & 0 \\ \partial \log J\psi & 1 \end{pmatrix}^{-1} d \begin{pmatrix} D\psi & 0 \\ \partial \log J\psi & 1 \end{pmatrix} + \begin{pmatrix} D\psi & 0 \\ \partial \log J\psi & 1 \end{pmatrix}^{-1} \widehat{\omega} \begin{pmatrix} D\psi & 0 \\ \partial \log J\psi & 1 \end{pmatrix} \\
&= \begin{pmatrix} (D\psi)^{-1}dD\psi & 0 \\ -(\partial \log J\psi)(D\psi^{-1})dD\psi + d\partial \log J\psi & 0 \end{pmatrix} \\
&\quad + \begin{pmatrix} (D\psi)^{-1}\widehat{\alpha}D\psi & 0 \\ -(\partial \log J)(D\psi)^{-1}\widehat{\alpha}D\psi + \widehat{\beta}D\psi & 0 \end{pmatrix} \\
&\quad - \frac{1}{n+1} \left(I_{n+1}d\widehat{x}^{n+1} + \begin{pmatrix} (D\psi)^{-1}d\widehat{x}\partial \log J\psi & (D\psi)^{-1}d\widehat{x} \\ -(\partial \log J\psi)(D\psi^{-1})d\widehat{x}\partial \log J\psi & -\partial(\log J\psi)(D\psi)^{-1}d\widehat{x} \end{pmatrix} \right) \\
&= \begin{pmatrix} (D\psi)^{-1}dD\psi & 0 \\ -(\partial \log J\psi)(D\psi^{-1})dD\psi + d\partial \log J\psi & 0 \end{pmatrix} \\
&\quad + \begin{pmatrix} (D\psi)^{-1}\widehat{\alpha}D\psi & 0 \\ -(\partial \log J)(D\psi)^{-1}\widehat{\alpha}D\psi + \widehat{\beta}D\psi & 0 \end{pmatrix} \\
&\quad - \frac{1}{n+1} \begin{pmatrix} I_n dx^{n+1} & dx \\ 0 & dx^{n+1} \end{pmatrix} \\
&\quad - \frac{1}{n+1} \begin{pmatrix} I_n d \log J\psi + dx \partial \log J\psi & 0 \\ -(d \log J\psi) \partial \log J\psi & 0 \end{pmatrix}.
\end{aligned}$$

It follows that

$$\begin{aligned}
\alpha &= (D\psi)^{-1}dD\psi - \frac{1}{n+1}(I_n d \log J\psi + dx \partial \log J\psi) + (D\psi)^{-1}\widehat{\alpha}D\psi, \\
\beta &= -(\partial \log J\psi)(D\psi^{-1})dD\psi + d\partial \log J\psi + \frac{1}{n+1}(d \log J\psi)\partial \log J\psi \\
&\quad - (\partial \log J\psi)(D\psi)^{-1}\widehat{\alpha}D\psi + \widehat{\beta}D\psi.
\end{aligned}$$

Note that we have

$$\begin{aligned}
\alpha^i &= \widehat{\alpha}^i, \\
\beta &= -(\partial \log J\psi)\alpha - \frac{1}{n+1}((\partial \log J\psi)d \log J\psi + d \log J\psi(\partial \log J\psi)) \\
&\quad + \frac{1}{n+1}d\partial \log J\psi + \widehat{\beta}D\psi \\
&= \frac{1}{n+1}(d\partial \log J\psi - 2(\partial \log J\psi)d \log J\psi) - (\partial \log J\psi)\alpha + \widehat{\beta}D\psi.
\end{aligned}$$

Remark 4.18. If ω^H denotes the connection matrix of ∇ with respect to \mathcal{F}^H , then we have by the equality (4.15a) that

$$\begin{aligned}\omega^H &= \begin{pmatrix} I_n & \\ -f & 1 \end{pmatrix}^{-1} d \begin{pmatrix} I_n & \\ -f & 1 \end{pmatrix} + \begin{pmatrix} I_n & \\ -f & 1 \end{pmatrix}^{-1} \omega \begin{pmatrix} I_n & \\ -f & 1 \end{pmatrix} \\ &= \begin{pmatrix} O_n & \\ -df & 0 \end{pmatrix} + \begin{pmatrix} \alpha & 0 \\ f\alpha + \beta & 0 \end{pmatrix} \\ &\quad - \frac{1}{n+1} \begin{pmatrix} I_n dx^{n+1} - dx f & dx \\ f dx^{n+1} - (f dx + dx^{n+1}) f & f dx + dx^{n+1} \end{pmatrix} \\ &= \begin{pmatrix} \alpha + \frac{1}{n+1}(I_n f dx + dx f) & 0 \\ -df + \frac{1}{n+1} f dx f + f\alpha + \beta & 0 \end{pmatrix} - \frac{1}{n+1} \begin{pmatrix} I_n \underline{\omega} & dx \\ 0 & \underline{\omega} \end{pmatrix}.\end{aligned}$$

Note that $(dx^1, \dots, dx^n, \underline{\omega})$ is the dual to \mathcal{F}^H .

Definition 4.19. We set

$$\begin{aligned}\alpha^H &= \alpha + \frac{1}{n+1}(I_n f dx + dx f), \\ \beta^H &= -df + \frac{1}{n+1} f dx f + f\alpha + \beta.\end{aligned}$$

We have the following

Lemma 4.20. The connection form of ∇^ω with respect to $\left(\frac{\partial}{\partial x^1}, \dots, \frac{\partial}{\partial x^n}\right)$ is equal to α^H . Indeed, we have

$$\begin{aligned}\alpha^H &= D\psi^{-1} dD\psi + D\psi^{-1} \hat{\alpha}^H D\psi, \\ \beta^H &= \hat{\beta}^H D\psi.\end{aligned}$$

Proof. The first part follows directly from Definition 4.11. Let (U, φ) and $(\hat{U}, \hat{\varphi})$ be charts, and ω^H and $\hat{\omega}^H$ connection forms of ∇ with respect to \mathcal{F}^H and $\hat{\mathcal{F}}^H$, respectively. Then, by Lemma 4.15, we have

$$\begin{aligned}\omega^H &= \begin{pmatrix} D\psi & \\ & 1 \end{pmatrix}^{-1} d \begin{pmatrix} D\psi & \\ & 1 \end{pmatrix} + \begin{pmatrix} D\psi & \\ & 1 \end{pmatrix}^{-1} \hat{\omega}^H \begin{pmatrix} D\psi & \\ & 1 \end{pmatrix} \\ &= \begin{pmatrix} D\psi^{-1} dD\psi & 0 \\ 0 & 0 \end{pmatrix} + \begin{pmatrix} D\psi^{-1} \hat{\alpha}^H D\psi & 0 \\ \hat{\beta}^H D\psi & 0 \end{pmatrix} - \frac{1}{n+1} \begin{pmatrix} I_n \underline{\omega} & D\psi^{-1} d\hat{x} \\ 0 & \underline{\omega} \end{pmatrix} \\ &= \begin{pmatrix} D\psi^{-1} dD\psi + D\psi^{-1} \hat{\alpha}^H D\psi & 0 \\ \hat{\beta}^H D\psi & 0 \end{pmatrix} - \frac{1}{n+1} \begin{pmatrix} I_n \underline{\omega} & dx \\ 0 & \underline{\omega} \end{pmatrix}. \quad \square\end{aligned}$$

Theorem 4.21. If ∇ is a TW-connection on $T\mathcal{E}(M)$ and if $\underline{\omega}$ and $\underline{\omega}'$ are connection forms on $\mathcal{E}(M)$, then

- 1) $\underline{\omega}' - \underline{\omega} = \pi^* \rho$ for some 1-form ρ on M , and
- 2) We have

$$\nabla^{\underline{\omega}'} - \nabla^{\underline{\omega}} = \frac{1}{n+1} \rho \otimes \text{id} + \frac{1}{n+1} \text{id} \otimes \rho.$$

3) $\nabla^{\underline{\omega}}$ and $\nabla^{\underline{\omega}'}$ are projectively equivalent.

Proof. First, we have $\omega'(\xi) - \omega(\xi) = 0$ and $R_a^*(\omega' - \omega) = \omega' - \omega$. Hence we have $\omega' - \omega = \pi^*\rho$ for some 1-form on M . 2) follows from Remark 4.18 and Lemma 4.20. 3) follows from 2) and Lemma 2.12. \square

Theorem 4.22. Fix a TW-connection ∇ on $T\mathcal{E}(M)$ and a connection form $\underline{\omega}$ on $\mathcal{E}(M)$. Then, there is a one-to-one correspondence between the set of connection forms on $\mathcal{E}(M)$ and the set of linear connections in the projective equivalence class represented by $\nabla^{\underline{\omega}}$.

Proof. Let \mathcal{D} be a linear connection projectively equivalent to $\nabla^{\underline{\omega}}$. There is a 1-form ρ such that $\mathcal{D} - \nabla^{\underline{\omega}} = \frac{1}{n+1}\rho \otimes \text{id} + \frac{1}{n+1}\text{id} \otimes \rho$. If we set $\underline{\omega}' = \omega + \pi^*\rho$, then we have $\nabla^{\underline{\omega}'} = \mathcal{D}$ by Theorem 4.21. Suppose conversely that $\nabla^{\underline{\omega}_1} = \nabla^{\underline{\omega}_2}$. Then $\underline{\omega}_1 = \underline{\omega}_2$ by Lemma 2.14. \square

Definition 4.23. If ω is a $\mathfrak{gl}_n(\mathbb{R})$ -valued 1-form, then we set $R(\omega) = d\omega + \omega \wedge \omega$.

Needless to say that $R(\omega)$ is the curvature form if ω is a connection form of a linear connection.

Lemma 4.24. The curvature form of a TW-connection with respect to \mathcal{F} is given by

$$R(\omega) = d\omega + \omega \wedge \omega = \begin{pmatrix} d\alpha + \alpha \wedge \alpha - \frac{1}{n+1}dx \wedge \beta & -\frac{1}{n+1}\alpha \wedge dx \\ d\beta + \beta \wedge \alpha & -\frac{1}{n+1}\beta \wedge dx \end{pmatrix}.$$

The TW-connection is torsion free if and only if $\alpha \wedge dx = 0$ and $\beta \wedge dx = 0$,

Proof. We have

$$\begin{aligned} & d\omega + \omega \wedge \omega \\ &= d\omega' + \omega' \wedge \omega' \\ & \quad - \frac{1}{n+1}\omega' \wedge \begin{pmatrix} I_n dx^{n+1} & dx \\ 0 & dx^{n+1} \end{pmatrix} - \frac{1}{n+1} \begin{pmatrix} I_n dx^{n+1} & dx \\ 0 & dx^{n+1} \end{pmatrix} \wedge \omega' \\ & \quad + \frac{1}{(n+1)^2} \begin{pmatrix} I_n dx^{n+1} & dx \\ 0 & dx^{n+1} \end{pmatrix} \wedge \begin{pmatrix} I_n dx^{n+1} & dx \\ 0 & dx^{n+1} \end{pmatrix} \\ &= \begin{pmatrix} d\alpha + \alpha \wedge \alpha & 0 \\ d\beta + \beta \wedge \alpha & 0 \end{pmatrix} - \frac{1}{n+1} \begin{pmatrix} \alpha \wedge dx^{n+1} + dx^{n+1} \wedge \alpha + dx \wedge \beta & \alpha \wedge dx \\ \beta \wedge dx^{n+1} + dx^{n+1} \wedge \beta & \beta \wedge dx \end{pmatrix} \\ &= \begin{pmatrix} d\alpha + \alpha \wedge \alpha & 0 \\ d\beta + \beta \wedge \alpha & 0 \end{pmatrix} - \frac{1}{n+1} \begin{pmatrix} dx \wedge \beta & \alpha \wedge dx \\ 0 & \beta \wedge dx \end{pmatrix}. \end{aligned}$$

If ∇ is torsion-free, then we have $(\alpha \wedge dx)^i = \alpha^i_{jk} dx^k \wedge dx^j = 0$. Similarly, we have $\beta \wedge dx = 0$. The converse is easy. \square

In view of Definition 1.5, we introduce the following

Definition 4.25. We regard the curvature form $d\omega + \omega \wedge \omega$ as being valued in $\mathfrak{pgl}_{n+1}(\mathbb{R}) = \mathfrak{m} \oplus \mathfrak{gl}_n(\mathbb{R}) \oplus \mathfrak{m}^*$, and represent the curvature form as $(\rho^i, \rho^i_j, \rho_j)$. We call ρ^i the *torsion* and (ρ^i_j, ρ_j) the *curvature* of ∇ as a projective connection.

Lemma 4.26. *We have*

$$\begin{aligned}\rho^i &= -\frac{1}{n+1}\alpha \wedge dx, \\ \rho^i_j &= d\alpha + \alpha \wedge \alpha - \frac{1}{n+1}(dx \wedge \beta - \beta \wedge dx I_n), \\ &= d\alpha + \alpha \wedge \alpha + dx \wedge \beta' - \beta' \wedge dx I_n, \\ \rho_j &= d\beta + \beta \wedge \alpha \\ &= -(n+1)(d\beta' + \beta' \wedge \alpha),\end{aligned}$$

where $\beta' = -\frac{1}{n+1}\beta$.

Definition 4.27. We define the Ricci curvature $\text{Ric}(\nabla)$ of a TW-connection ∇ by

$$\begin{aligned}\text{Ric}(\nabla)_{jk} &= \rho^i_{jik} \\ &= \frac{\partial \alpha^i_{jk}}{\partial x^i} - \frac{\partial \alpha^i_{ji}}{\partial x^k} + \alpha^i_{\gamma i} \alpha^\gamma_{jk} - \alpha^i_{\gamma k} \alpha^\gamma_{ji} - \frac{1}{n+1}(n\beta_{jk} - \beta_{jk} + \beta_{jk} - \beta_{kj}) \\ &= \frac{\partial \alpha^i_{jk}}{\partial x^i} - \frac{\partial \alpha^i_{ji}}{\partial x^k} + \alpha^i_{\gamma i} \alpha^\gamma_{jk} - \alpha^i_{\gamma k} \alpha^\gamma_{ji} - \frac{1}{n+1}(n\beta_{jk} - \beta_{kj}).\end{aligned}$$

The fundamental theorem for TW-connections by Roberts [7] holds in the following form in the present setting.

Theorem 4.28. *Suppose that $\dim M \geq 2$ and a projective structure is of M is given by an affine connection ∇_M . Let Ψ_M be the canonical positive odd scalar density on $\mathcal{E}(M)$ and μ_M the reduced torsion of ∇_M regarded as a form on $\mathcal{E}(M)$ by pull-back. Then, there exists a unique TW-connection ∇ such that*

- 1) $\nabla \Psi_M = -\mu_M \otimes \Psi_M$.
- 2) ∇ is Ricci-flat.
- 3) ∇ induces the given projective equivalence class on M .

Moreover, there is a unique connection on $\mathcal{E}(M)$ such that α^H is the connection form of ∇_M with respect to $\left(\frac{\partial}{\partial x^i}\right)_{1 \leq i \leq n}$.

Indeed, if $\{\Gamma^i_{jk}\}$ denotes the Christoffel symbols of ∇_M , then we have

$$\begin{aligned}\alpha^i_{jk} &= \Gamma^i_{jk} - \frac{1}{2(n+1)}(\delta^i_k(\Gamma^a_{aj} + \Gamma^a_{ja}) + \delta^i_j(\Gamma^a_{ak} + \Gamma^a_{ka})), \\ \beta_{jk} &= \frac{1}{n-1} \left(n \left(\frac{\partial \alpha^i_{jk}}{\partial x^i} + \frac{\partial \mu_{Mj}}{\partial x^k} - \mu_{Ma} \alpha^a_{jk} - \alpha^a_{jb} \alpha^b_{ak} \right) \right. \\ &\quad \left. + \left(\frac{\partial \alpha^i_{kj}}{\partial x^i} + \frac{\partial \mu_{Mk}}{\partial x^j} - \mu_{Ma} \alpha^a_{kj} - \alpha^a_{kb} \alpha^b_{aj} \right) \right),\end{aligned}$$

where

$$\begin{pmatrix} \alpha & 0 \\ \beta & 0 \end{pmatrix} - \frac{1}{n+1} \begin{pmatrix} I_n dx^{n+1} & dx \\ 0 & dx^{n+1} \end{pmatrix}$$

is the connection matrix of ∇ with respect to \mathcal{F} . The connection of $\mathcal{E}(M)$ is given by $\underline{\omega} = \frac{1}{2}(\Gamma^\alpha_{\alpha j} + \Gamma^\alpha_{j\alpha})$.

Proof. Let $\{\Gamma^i_{jk}\}$ be the Christoffel symbols of ∇_M and set $\alpha^H = (\Gamma^i_{jk} dx^k)$. If we fix a connection $\underline{\omega} = f dx + dx^{n+1}$ on $\mathcal{E}(M)$, then a TW-connection is given by $\begin{pmatrix} \alpha^H - \frac{1}{n+1}(I_n f dx + dx f) & 0 \\ df + \frac{1}{n+1} f dx f - f \alpha^H + \beta^H & 0 \end{pmatrix} - \frac{1}{n+1} \begin{pmatrix} I_n dx^{n+1} & dx \\ 0 & dx^{n+1} \end{pmatrix}$, where β^H is an m^* -valued 1-form (see Remark 4.18). Note that even if we replace ∇ by a projectively equivalent connection, then $\underline{\omega}$ is modified while the TW-connection remains in the same form. We have

$$\nabla \Psi_M = (-\alpha^H)^\alpha_{\alpha j} dx^j + f_j dx^j \otimes \Psi_M = (-\Gamma^\alpha_{\alpha j} dx^j + f_j dx^j) \otimes \Psi_M.$$

By the condition 1), we have $\Gamma^\alpha_{\alpha j} - f_j = \frac{1}{2}(\Gamma^\alpha_{\alpha j} - \Gamma^\alpha_{j\alpha})$ so that

$$f_j = \frac{1}{2}(\Gamma^\alpha_{\alpha j} + \Gamma^\alpha_{j\alpha}).$$

If set $\alpha = \alpha^H - \frac{1}{n+1}(I_n f dx + dx f)$ and $\beta = df + \frac{1}{n+1} f dx f - f \alpha^H + \beta^H$, then we have by the condition 2) that

$$\frac{\partial \alpha^i_{jk}}{\partial x^i} - \frac{\partial \alpha^i_{ji}}{\partial x^k} + \alpha^i_{\gamma i} \alpha^\gamma_{jk} - \alpha^i_{\gamma k} \alpha^\gamma_{ji} - \frac{1}{n+1}(n\beta_{jk} - \beta_{kj}) = 0.$$

It follows that β_{jk} are given as in the statement. Conversely, if we define α^i_{jk} and β_{jk} as in the statement, then ∇ is a TW-connection with the required properties. Since α^i_{jk} and β_{jk} are independent of $\underline{\omega}$, ∇ is unique. \square

It is natural to introduce the following

Definition 4.29. We call the TW-connection given by Theorem 4.28 the *normal TW-connection*.

Remark 4.30. If we only require uniqueness of normal TW-connections, then we can modify the normalizing conditions 1) and 2) in Theorem 4.28 by similar reasons as in Remark 2.22. The conditions are so chosen that components of the normal TW-connections coincide with the normal Cartan projective connections up to multiplication of constants. Actually, α^i_{jk} and β'_{jk} coincide with Π^i_{jk} and Π_{jk} given by Proposition 2.21.

Remark 4.31. Suppose that the projective structure in Theorem 4.28 is torsion-free. Then, ∇_M is always torsion-free so that the condition 1) reduces to $\nabla \Psi_M = 0$,

which is independent of ∇_M . In addition, we have

$$\begin{aligned}\alpha^i_{jk} &= \Gamma^i_{jk} - \frac{1}{n+1}(\delta^i_k \Gamma^a_{aj} + \delta^i_j \Gamma^a_{ak}), \\ \beta_{jk} &= \frac{n+1}{n-1} \left(\frac{\partial \alpha^i_{jk}}{\partial x^i} - \alpha^a_{jb} \alpha^b_{ak} \right).\end{aligned}$$

Remark 4.32. *If we allow to modify the torsion keeping the geodesics, then we can uniquely find a TW-connection which corresponds to the Hlavatý connection (Remark 2.27). We can also uniquely find a TW-connection which corresponds to the connection of which the Christoffel symbols are $\{\frac{1}{2}(\Gamma^i_{jk} + \Gamma^i_{kj})\}$.*

5. STRUCTURAL EQUIVALENCES OF TW-CONNECTIONS

We continue to follow the arguments in [7].

Definition 5.1 ([8]). TW-connections ∇ and ∇' are said to be *structurally equivalent* if ∇ and ∇' induce the same projective structure.

Theorem 5.2. *TW-connections ∇ and ∇' are structurally equivalent if and only if there is a $(0, 2)$ -tensor β on $\mathcal{E}(M)$ such that*

$$(5.2a) \quad \begin{cases} L_\xi \beta = 0, \\ \beta(\xi, \xi) = 0, \end{cases}$$

and

$$(5.2b) \quad \nabla' = \nabla + (\iota'_\xi \beta) \otimes \text{id} + \text{id} \otimes (\iota'_\xi \beta) - \beta \otimes \xi,$$

where $\iota'_\xi \beta = \beta(\cdot, \xi)$. Such a β is unique. If ∇ and ∇' are torsion-free, then β is symmetric.

Before proving Theorem 5.2, we show the following

Lemma 5.3. *If the condition (5.2a) holds, then there is a 1-form $\bar{\beta}$ on M such that $\iota'_\xi \beta = \pi^* \bar{\beta}$.*

Proof. Let ι be the usual inner product. We locally represent β as $\beta = \beta_{ij} dx^i \otimes dx^j$. We have $\iota'_\xi \beta = \beta_{i,n+1} dx^i$. On the other hand, we have $0 = L_\xi \beta = \frac{\partial \beta_{ij}}{\partial x^{n+1}} dx^i \otimes dx^j$. Hence we have $\iota_\xi(\iota'_\xi \beta) = 0$ and $\iota_\xi d(\iota'_\xi \beta) = \frac{\partial \beta_{i,n+1}}{\partial x^{n+1}} dx^i - \frac{\partial \beta_{n+1,n+1}}{\partial x^j} dx^j = \iota'_\xi(L_\xi \beta) = 0$. \square

Remark 5.4. *If (5.2b) holds and if ω is a connection form on $\mathcal{E}(M)$, then we have*

$$\nabla'^\omega = \nabla^\omega + \bar{\beta} \otimes \text{id} + \text{id} \otimes \bar{\beta}.$$

Proof of Theorem 5.2. The proof is essentially identical to that of Theorem 3.6 in [7]. Keep in mind that connections need not be torsion-free. First assume that there exists a β which satisfy (5.2a) and (5.2b). If we set

$$\widehat{\nabla} = \nabla + (\iota'_\xi \beta) \otimes \text{id} + \text{id} \otimes (\iota'_\xi \beta) - \beta \otimes \xi,$$

then $\widehat{\nabla}$ is a TW-connection. Note that β is invariant under the \mathbb{R} -action because $L_\xi \beta = 0$. Let now ω be a connection form on $\mathcal{E}(M)$ and $X, Y \in \mathfrak{X}(M)$. If \widetilde{X} and \widetilde{Y} denote horizontal lifts of X and Y , then we have

$$\widehat{\nabla}_{\widetilde{X}} \widetilde{Y} = \nabla_{\widetilde{X}} \widetilde{Y} + \pi^* \bar{\beta}(\widetilde{X}) \widetilde{Y} + \pi^* \bar{\beta}(\widetilde{Y}) \widetilde{X} - \beta(\widetilde{X}, \widetilde{Y}) \xi$$

for some 1-form $\bar{\beta}$ on M . Hence we have

$$(5.2c) \quad \widehat{\nabla}^{\omega_X} Y = \nabla^{\omega_X} Y + \bar{\beta}(X) Y + \bar{\beta}(Y) X,$$

which means that ∇^{ω} and $\widehat{\nabla}^{\omega}$ are projectively equivalent. Hence ∇ and $\widehat{\nabla}$ are structurally equivalent. Suppose conversely that ∇ and $\widehat{\nabla}$ are structurally equivalent. If we fix a connection form ω , then

$$\widehat{\nabla}^{\omega} = \nabla^{\omega} + \bar{\beta} \otimes \text{id} + \text{id} \otimes \bar{\beta}$$

for some 1-form $\bar{\beta}$ on M . We set, for $\widetilde{X}, \widetilde{Y} \in \mathfrak{X}(\mathcal{E}(M))$,

$$\beta(\widetilde{X}, \widetilde{Y}) = \omega(\nabla_{\widetilde{X}} \widetilde{Y} - \widehat{\nabla}_{\widetilde{X}} \widetilde{Y}) + \pi^* \bar{\beta}(\widetilde{X}) \omega(\widetilde{Y}) + \pi^* \bar{\beta}(\widetilde{Y}) \omega(\widetilde{X}).$$

It is clear that β is a $(0, 2)$ -tensor. We have $L_\xi \beta = 0$ and $\beta(\xi, \xi) = 0$ because ∇ and $\widehat{\nabla}$ are TW-connections. If in addition ∇ and ∇' are torsion-free, then β is symmetric. We will show that the equality (5.2b) holds. Let $\widetilde{X}, \widetilde{Y} \in \mathfrak{X}(\mathcal{E}(M))$. First assume that \widetilde{X} and \widetilde{Y} are horizontal lifts of $X, Y \in \mathfrak{X}(M)$. Then, the equality (5.2c) holds. If $\widetilde{\nabla}^{\omega_X} Y$ and $\widetilde{\widehat{\nabla}}^{\omega_X} Y$ denote the horizontal lifts of $\nabla^{\omega_X} Y$ and $\widehat{\nabla}^{\omega_X} Y$, then we have

$$\widetilde{\nabla}_{\widetilde{X}} \widetilde{Y} = \widetilde{\nabla}^{\omega_X} Y + \omega(\nabla_{\widetilde{X}} \widetilde{Y}) \xi,$$

$$\widetilde{\widehat{\nabla}}_{\widetilde{X}} \widetilde{Y} = \widetilde{\widehat{\nabla}}^{\omega_X} Y + \omega(\widehat{\nabla}_{\widetilde{X}} \widetilde{Y}) \xi.$$

It follows that

$$\begin{aligned} \widetilde{\widehat{\nabla}}_X Y &= \widetilde{\widehat{\nabla}}^{\omega_X} Y + \omega(\widehat{\nabla}_X Y) \xi \\ &= \widetilde{\nabla}^{\omega_X} Y + \pi^* \bar{\beta}(\widetilde{X}) \widetilde{Y} + \pi^* \bar{\beta}(\widetilde{Y}) \widetilde{X} + \omega(\widehat{\nabla}_X Y) \xi \\ &= \nabla_X Y - \omega(\nabla_X Y) \xi + \pi^* \bar{\beta}(\widetilde{X}) \widetilde{Y} + \pi^* \bar{\beta}(\widetilde{Y}) \widetilde{X} + \omega(\widehat{\nabla}_X Y) \xi. \end{aligned}$$

On the other hand, we have

$$\begin{aligned} \iota'_\xi \beta(\widetilde{X}) &= \omega(\nabla_{\widetilde{X}} \xi - \widehat{\nabla}_{\widetilde{X}} \xi) + \pi^* \bar{\beta}(\widetilde{X}) \\ &= \bar{\beta}(X). \end{aligned}$$

Similarly, we have $\iota'_\xi \beta(\tilde{Y}) = \bar{\beta}(Y)$. Hence we have

$$\begin{aligned}\widehat{\nabla}_X Y &= \nabla_X Y - \omega(\nabla_X Y)\xi + \pi^* \bar{\beta}(\tilde{X})\tilde{Y} + \pi^* \bar{\beta}(\tilde{Y})\tilde{X} + \omega(\widehat{\nabla}_X Y)\xi \\ &= \nabla_X Y + \iota'_\xi \beta(\tilde{X})\tilde{Y} + \iota'_\xi \beta(\tilde{Y})\tilde{X} + \omega(\widehat{\nabla}_X Y - \nabla_X Y)\xi \\ &= \nabla_X Y + \iota'_\xi \beta(\tilde{X})\tilde{Y} + \iota'_\xi \beta(\tilde{Y})\tilde{X} - \beta(\tilde{X}, \tilde{Y})\xi.\end{aligned}$$

Next, we assume that $\tilde{Y} = \xi$. We have $\beta(\tilde{X}, \tilde{Y}) = \pi^* \bar{\beta}(\tilde{X})$ so that

$$\begin{aligned}\nabla_{\tilde{X}} \xi + \iota'_\xi \beta(\tilde{X})\xi + \iota'_\xi \beta(\xi)\tilde{X} - \beta(\tilde{X}, \xi)\xi \\ = -\frac{1}{n+1}\tilde{X} \\ = \widehat{\nabla}_{\tilde{X}} \xi.\end{aligned}$$

We assume lastly that $\tilde{X} = \xi$. We have

$$\begin{aligned}\nabla_\xi \tilde{Y} + \iota'_\xi \beta(\xi)\tilde{Y} + \iota'_\xi \beta(\tilde{Y})\xi - \beta(\xi, \tilde{Y})\xi \\ = \nabla_\xi \tilde{Y} + \iota'_\xi \beta(\tilde{Y})\xi - \omega(\nabla_\xi \tilde{Y} - \widehat{\nabla}_\xi \tilde{Y})\xi - \pi^* \bar{\beta}(\tilde{Y})\xi \\ = \widehat{\nabla}_\xi \tilde{Y}.\end{aligned}$$

Therefore, the equality (5.2b) holds. Finally, suppose that β' also satisfy the equalities (5.2a) and (5.2b) if we replace β with β' . Then we have $\iota'_\xi \beta = \bar{\beta}$ and $\iota'_\xi \beta' = \bar{\beta}'$ for some 1-forms β and β' . By Remark 5.4, we have $\bar{\beta} = \bar{\beta}'$. On the other hand, we have

$$\begin{aligned}\nabla'_{\tilde{X}} \tilde{Y} - \nabla_{\tilde{X}} \tilde{Y} &= \iota'_\xi \beta(\tilde{X})\tilde{Y} + \iota'_\xi \beta(\tilde{Y})\tilde{X} - \beta(\tilde{X}, \tilde{Y})\xi \\ &= \bar{\beta}(X)\tilde{Y} + \bar{\beta}(Y)\tilde{X} - \beta(\tilde{X}, \tilde{Y})\xi.\end{aligned}$$

Similarly, we have

$$\nabla'_{\tilde{X}} \tilde{Y} - \nabla_{\tilde{X}} \tilde{Y} = \bar{\beta}(X)\tilde{Y} + \bar{\beta}(Y)\tilde{X} - \beta'(\tilde{X}, \tilde{Y})\xi.$$

Hence we have $\beta = \beta'$. □

6. EXAMPLES

We introduce examples of which the torsions are non-trivial and the curvatures are trivial.

Let $T^2 = \mathbb{R}^2/\mathbb{Z}^2$ be the standard torus and (x^1, x^2) the standard coordinates. We study projective structures of T^2 which are curvature-free and invariant under the standard T^2 action. First of all, Christoffel symbols of connections are constants.

Let

$$\begin{aligned}\mathcal{T} &= \{\text{projective structures of } T^2 \text{ invariant under the } T^2\text{-action and is curvature-free}\}, \\ \mathcal{T}' &= \{\tau \in \mathcal{T} \mid \tau \text{ is with torsion}\}.\end{aligned}$$

Let $\omega = (\omega^i, \omega^i_j, \omega_j)$ denote the normal projective connection associated with the projective structure given by an affine connection ∇ , σ the section given by

Proposition 2.21. Let $(\Omega^i, \Omega^i_j, \Omega_j)$ be the torsion and the curvature of ω . We have $\sigma^*\omega^i = dx^i$. We have naturally $\tilde{P}^2(T^2) \cong T^2 \times \tilde{G}^2$. If $P \subset \tilde{P}^2(T^2)$ is a projective structure, then we have $P \cong T^2 \times H^2 \subset T^2 \times \tilde{G}^2$.

Example 6.1. We consider an affine connection ∇ of which the Christoffel symbols are

$$\begin{aligned} \Gamma^1_{11} &= 1, & \Gamma^1_{12} &= -\frac{1}{2}, & \Gamma^1_{21} &= -\frac{1}{2}, & \Gamma^1_{22} &= 0, \\ \Gamma^2_{11} &= 1, & \Gamma^2_{12} &= \frac{3}{2}, & \Gamma^2_{21} &= -\frac{1}{2}, & \Gamma^2_{22} &= -1. \end{aligned}$$

We set $g = (\delta^i_j, -\Gamma^i_{jk}) \in \tilde{G}^2$, which does not belong to H^2 because $\Gamma^2_{21} \neq \Gamma^2_{12}$. We define $\sigma_0: T^2 \rightarrow \tilde{P}^2(T^2)$ by $\sigma(p) = (p, g)$ and define an H^2 -subbundle P of $\tilde{P}^2(T^2)$ by

$$P = \{u \in \tilde{P}^2(T^2) \mid \exists p \in T^2, h \in H^2, u = \sigma_0(p).h\}.$$

We have $\Gamma^\alpha_{\alpha 1} = \frac{1}{2}$, $\Gamma^\alpha_{\alpha 2} = -\frac{3}{2}$, $\Gamma^\alpha_{1\alpha} = \frac{5}{2}$ and $\Gamma^\alpha_{2\alpha} = -\frac{3}{2}$ so that

$$\begin{aligned} \mu_1 &= -1, & \mu_2 &= 0, \\ \nu_1 &= -\frac{1}{2}, & \nu_2 &= \frac{1}{2}. \end{aligned}$$

It follows that

$$\begin{aligned} \Pi^1_{11} &= 0, & \Pi^1_{12} &= 0, & \Pi^1_{21} &= 0, & \Pi^1_{22} &= 0, \\ \Pi^2_{11} &= 1, & \Pi^2_{12} &= 1, & \Pi^2_{21} &= -1, & \Pi^2_{22} &= 0, \\ \Pi_{11} &= -1, & \Pi_{12} &= 0, & \Pi_{21} &= 0, & \Pi_{22} &= 0. \end{aligned}$$

We have therefore that

$$\begin{aligned} \sigma^*\Omega^1 &= 0, & \sigma^*\Omega^2 &= -2dx^1 \wedge dx^2, \\ \sigma^*\Omega^i_j &= 0, \\ \sigma^*\Omega_j &= 0. \end{aligned}$$

Hence the connection ∇ gives an element of \mathcal{T} of which the torsion is non-trivial.

The normal TW-connection which corresponds to ∇ is given as follows. We have $\mathcal{E}(T^2) = T^2 \times \mathbb{R}$. Let t be the standard coordinate for \mathbb{R} . Then, the normal TW-connection is given by

$$\begin{aligned} \omega &= \begin{pmatrix} \Pi^1_{1\alpha} dx^\alpha & \Pi^1_{2\alpha} dx^\alpha & 0 \\ \Pi^2_{1\alpha} dx^\alpha & \Pi^2_{2\alpha} dx^\alpha & 0 \\ -3\Pi_{1\alpha} dx^\alpha & -3\Pi_{2\alpha} dx^\alpha & 0 \end{pmatrix} - \frac{1}{3} \begin{pmatrix} dt & 0 & dx^1 \\ 0 & dt & dx^2 \\ 0 & 0 & dt \end{pmatrix} \\ &= \begin{pmatrix} 0 & 0 & 0 \\ dx^1 + dx^2 & -dx^1 & 0 \\ 3dx^1 & 0 & 0 \end{pmatrix} - \frac{1}{3} \begin{pmatrix} dt & 0 & dx^1 \\ 0 & dt & dx^2 \\ 0 & 0 & dt \end{pmatrix}, \end{aligned}$$

which is with torsion. We have

$$R(\omega) = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & \frac{2}{3}dx^1 \wedge dx^2 \\ 0 & 0 & 0 \end{pmatrix}$$

so that ω is with torsion as a projective connection. On the other hand, ω is curvature-free. The correspondence between $(\Omega^i, \Omega^i_j, \Omega_j)$ and the components of $R(\omega)$ is given by Lemma 4.26.

Projective structures with torsion are abundant even if we assume the curvatures to be trivial.

Theorem 6.2. *The space \mathcal{T} is a cubic subvariety of \mathbb{R}^6 of dimension 4. The space \mathcal{T}' is an open subvariety of \mathcal{T} and induces a subvariety of $\mathbb{R}P^5$ of dimension 3.*

If we work in the complex category, then \mathbb{R}^6 and $\mathbb{R}P^5$ are replaced by \mathbb{C}^6 and $\mathbb{C}P^5$.

Proof. We make use of notations in Lemma 2.20. Let $\psi^i_j = \Pi^i_{jk}dx^k$ and $\psi_j = \Pi_{jk}dx^k$. We have

$$\mu_j = \Pi^\alpha_{\alpha j} = -\Pi^\alpha_{j\alpha},$$

where μ is the reduced torsion. This is equivalent to

$$(6.2-1) \quad 2\Pi^1_{11} + \Pi^2_{21} + \Pi^2_{12} = 0,$$

$$(6.2-2) \quad 2\Pi^2_{22} + \Pi^1_{12} + \Pi^1_{21} = 0.$$

We have

$$\Pi_{jk} = \frac{1}{3} \left(2(\mu_\alpha \Pi^\alpha_{jk} + \Pi^\alpha_{j\beta} \Pi^\beta_{\alpha k}) + (\mu_\alpha \Pi^\alpha_{kj} + \Pi^\alpha_{k\beta} \Pi^\beta_{\alpha j}) \right).$$

It follows that

$$\Pi_{jk} = \frac{1}{3} \left(2(-\Pi^\beta_{\alpha\beta} \Pi^\alpha_{jk} + \Pi^\alpha_{j\beta} \Pi^\beta_{\alpha k}) + (-\Pi^\beta_{\alpha\beta} \Pi^\alpha_{kj} + \Pi^\alpha_{k\beta} \Pi^\beta_{\alpha j}) \right)$$

If $j = k$, then we have

$$\begin{aligned} -\Pi^\beta_{\alpha\beta} \Pi^\alpha_{11} + \Pi^\alpha_{1\beta} \Pi^\beta_{\alpha 1} &= -\Pi^1_{11} \Pi^1_{11} - \Pi^1_{21} \Pi^2_{11} - \Pi^2_{12} \Pi^1_{11} - \Pi^2_{22} \Pi^2_{11} \\ &\quad + \Pi^1_{11} \Pi^1_{11} + \Pi^1_{12} \Pi^2_{11} + \Pi^2_{11} \Pi^1_{21} + \Pi^2_{12} \Pi^2_{21} \\ &= -\Pi^2_{12} \Pi^1_{11} - \Pi^2_{22} \Pi^2_{11} + \Pi^1_{12} \Pi^2_{11} + \Pi^2_{12} \Pi^2_{21}, \\ -\Pi^\beta_{\alpha\beta} \Pi^\alpha_{22} + \Pi^\alpha_{2\beta} \Pi^\beta_{\alpha 2} &= -\Pi^1_{11} \Pi^1_{22} - \Pi^1_{21} \Pi^2_{22} + \Pi^1_{21} \Pi^1_{12} + \Pi^2_{21} \Pi^1_{22}. \end{aligned}$$

If $i \neq j$, then we have

$$\begin{aligned}
-\Pi^{\beta}_{\alpha\beta}\Pi^{\alpha}_{12} + \Pi^{\alpha}_{1\beta}\Pi^{\beta}_{\alpha 2} &= -\Pi^1_{11}\Pi^1_{12} - \Pi^1_{21}\Pi^2_{12} - \Pi^2_{12}\Pi^1_{12} - \Pi^2_{22}\Pi^2_{12} \\
&\quad + \Pi^1_{11}\Pi^1_{12} + \Pi^1_{12}\Pi^2_{12} + \Pi^2_{11}\Pi^1_{22} + \Pi^2_{12}\Pi^2_{22} \\
&= -\Pi^1_{21}\Pi^2_{12} + \Pi^2_{11}\Pi^1_{22} \\
-\Pi^{\beta}_{\alpha\beta}\Pi^{\alpha}_{21} + \Pi^{\alpha}_{2\beta}\Pi^{\beta}_{\alpha 1} &= -\Pi^1_{11}\Pi^1_{21} - \Pi^1_{21}\Pi^2_{21} - \Pi^2_{12}\Pi^1_{21} - \Pi^2_{22}\Pi^2_{21} \\
&\quad + \Pi^1_{21}\Pi^1_{11} + \Pi^1_{22}\Pi^2_{11} + \Pi^2_{21}\Pi^1_{21} + \Pi^2_{22}\Pi^2_{21} \\
&= -\Pi^2_{12}\Pi^1_{21} + \Pi^1_{22}\Pi^2_{11}.
\end{aligned}$$

Hence we have

$$(6.2-3) \quad \Pi_{11} = -\Pi^2_{12}\Pi^1_{11} - \Pi^2_{22}\Pi^2_{11} + \Pi^1_{12}\Pi^2_{11} + \Pi^2_{12}\Pi^2_{21},$$

$$(6.2-4) \quad \Pi_{12} = \Pi_{21} = -\Pi^2_{12}\Pi^1_{21} + \Pi^1_{22}\Pi^2_{11},$$

$$(6.2-5) \quad \Pi_{22} = -\Pi^1_{11}\Pi^1_{22} - \Pi^1_{21}\Pi^2_{22} + \Pi^1_{21}\Pi^1_{12} + \Pi^2_{21}\Pi^1_{22}.$$

These are the defining equalities for Π_{ij} .

On the other hand, we have

$$\begin{aligned}
\Omega^i &= \begin{pmatrix} -\Pi^1_{12} + \Pi^1_{21} \\ -\Pi^2_{12} + \Pi^2_{21} \end{pmatrix} dx^1 \wedge dx^2, \\
\Omega^i_j &= \begin{pmatrix} \Pi^1_{2k}\Pi^2_{1l}dx^k \wedge dx^l & (\Pi^1_{1k}\Pi^1_{2l} + \Pi^1_{2k}\Pi^2_{2l})dx^k \wedge dx^l \\ (\Pi^2_{1k}\Pi^1_{1l} + \Pi^2_{2k}\Pi^2_{1l})dx^k \wedge dx^l & \Pi^2_{1k}\Pi^1_{2l}dx^k \wedge dx^l \end{pmatrix} \\
&\quad + \begin{pmatrix} 2\Pi_{12} - \Pi_{21} & \Pi_{22} \\ -\Pi_{11} & -2\Pi_{21} + \Pi_{12} \end{pmatrix} dx^1 \wedge dx^2, \\
\Omega_j &= ((\Pi_{1k}\Pi^1_{1l} + \Pi_{2k}\Pi^2_{1l})dx^k \wedge dx^l \quad (\Pi_{1k}\Pi^1_{2l} + \Pi_{2k}\Pi^2_{2l})dx^k \wedge dx^l).
\end{aligned}$$

The projective structure is with torsion if and only if we have

$$(6.2-6) \quad \Pi^1_{12} \neq \Pi^1_{21} \quad \text{or} \quad \Pi^2_{12} \neq \Pi^2_{21},$$

while it is curvature-free, namely, $(\Omega^i_j, \Omega_j) = (0, 0)$ if and only if we have

$$(6.2-7) \quad \Pi^1_{21}\Pi^2_{12} - \Pi^1_{22}\Pi^2_{11} + 2\Pi_{12} - \Pi_{21} = 0,$$

$$(6.2-8) \quad \Pi^1_{11}\Pi^1_{22} - \Pi^1_{12}\Pi^1_{21} + \Pi^1_{21}\Pi^2_{22} - \Pi^1_{22}\Pi^2_{21} + \Pi_{22} = 0,$$

$$(6.2-9) \quad \Pi^2_{11}\Pi^1_{12} - \Pi^2_{12}\Pi^1_{11} + \Pi^2_{21}\Pi^2_{12} - \Pi^2_{22}\Pi^2_{11} - \Pi_{11} = 0,$$

$$(6.2-10) \quad \Pi^2_{11}\Pi^1_{22} - \Pi^2_{12}\Pi^1_{21} - 2\Pi_{21} + \Pi_{12} = 0,$$

$$(6.2-11) \quad \Pi_{11}\Pi^1_{12} - \Pi_{12}\Pi^1_{11} + \Pi_{21}\Pi^2_{12} - \Pi_{22}\Pi^2_{11} = 0,$$

$$(6.2-12) \quad \Pi_{11}\Pi^1_{22} - \Pi_{12}\Pi^1_{21} + \Pi_{21}\Pi^2_{22} - \Pi_{22}\Pi^2_{21} = 0.$$

The equalities (6.2-8) and (6.2-9) are equivalent to the equalities (6.2-5) and (6.2-3).

The equalities (6.2-7) and (6.2-10) are equivalent to the equality (6.2-4). Hence we always have $\Omega^i_j = 0$.

We consider $\tau = (\Pi^1_{12}, \Pi^1_{21}, \Pi^1_{22}, \Pi^2_{11}, \Pi^2_{12}, \Pi^2_{21})$ as coordinates. Let $F(\tau)$ be the left hand side of the equality (6.2-11) and $G(\tau)$ be the left hand side of the

equality (6.2-12). We have

$$\begin{aligned}
F(\tau) &= \frac{1}{2}\Pi^2_{12}\Pi^2_{12}\Pi^1_{12} + \frac{3}{2}\Pi^2_{12}\Pi^2_{21}\Pi^1_{12} + \frac{3}{2}\Pi^1_{12}\Pi^2_{11}\Pi^1_{12} \\
&\quad - \frac{3}{2}\Pi^2_{12}\Pi^1_{21}\Pi^2_{12} - \frac{1}{2}\Pi^2_{12}\Pi^1_{21}\Pi^2_{21} + \Pi^1_{22}\Pi^2_{11}\Pi^2_{12} \\
&\quad - \frac{1}{2}\Pi^1_{21}\Pi^1_{21}\Pi^2_{11} - \Pi^1_{21}\Pi^1_{12}\Pi^2_{11} - \Pi^2_{21}\Pi^1_{22}\Pi^2_{11} \\
&= \frac{1}{2}\Pi^2_{12}\Pi^2_{12}(\Pi^1_{12} - \Pi^1_{21}) + \Pi^2_{12}\Pi^2_{21}(\Pi^1_{12} - \Pi^1_{21}) - \Pi^2_{12}\Pi^1_{21}(\Pi^2_{12} - \Pi^2_{21}) \\
&\quad + \frac{1}{2}\Pi^2_{12}\Pi^2_{21}(\Pi^1_{12} - \Pi^1_{21}) + \frac{1}{2}(\Pi^1_{12}\Pi^1_{12} - \Pi^1_{21}\Pi^1_{21})\Pi^2_{11} + \Pi^1_{12}\Pi^2_{11}(\Pi^1_{12} - \Pi^1_{21}) \\
&\quad + \Pi^1_{22}\Pi^2_{11}(\Pi^2_{12} - \Pi^2_{21}).
\end{aligned}$$

Similarly, we have

$$\begin{aligned}
G(\tau) &= -\frac{1}{2}\Pi^1_{21}\Pi^1_{21}\Pi^2_{21} - \frac{3}{2}\Pi^1_{21}\Pi^1_{12}\Pi^2_{21} - \frac{3}{2}\Pi^2_{21}\Pi^1_{22}\Pi^2_{21} \\
&\quad + \frac{3}{2}\Pi^1_{21}\Pi^2_{12}\Pi^1_{21} + \frac{1}{2}\Pi^1_{21}\Pi^2_{12}\Pi^1_{12} - \Pi^2_{11}\Pi^1_{22}\Pi^1_{21} \\
&\quad + \frac{1}{2}\Pi^2_{12}\Pi^2_{12}\Pi^1_{22} + \Pi^2_{12}\Pi^2_{21}\Pi^1_{22} + \Pi^1_{12}\Pi^2_{11}\Pi^1_{22} \\
&= \frac{1}{2}\Pi^1_{21}\Pi^1_{21}(\Pi^2_{12} - \Pi^2_{21}) + \Pi^1_{21}\Pi^1_{12}(\Pi^2_{12} - \Pi^2_{21}) - \Pi^1_{21}\Pi^2_{12}(\Pi^1_{12} - \Pi^1_{21}) \\
&\quad + \frac{1}{2}\Pi^1_{21}\Pi^1_{12}(\Pi^2_{12} - \Pi^2_{21}) + \frac{1}{2}(\Pi^2_{12}\Pi^2_{12} - \Pi^2_{21}\Pi^2_{21})\Pi^1_{22} + \Pi^2_{21}\Pi^1_{22}(\Pi^2_{12} - \Pi^2_{21}) \\
&\quad + \Pi^2_{11}\Pi^1_{22}(\Pi^1_{12} - \Pi^1_{21}).
\end{aligned}$$

Suppose conversely that we can find $\tau = (\Pi^i_{jk})$, where $(i, j, k) \neq (1, 1, 1), (2, 2, 2)$, such that $F(\tau) = G(\tau) = 0$. We define Π^1_{11} and Π^2_{22} by (6.2-1) and (6.2-2), and Π_{ij} by (6.2-3), (6.2-4) and (6.2-5). Then, the projective structure determined by τ is curvature-free. It is with torsion if and only if the condition (6.2-6) is satisfied. Therefore, we have

$$\mathcal{T} = \{\tau = (\Pi^i_{jk}) \mid F(\tau) = G(\tau) = 0\}.$$

Note that if $\tau \in \mathcal{T}$ is torsion-free, then τ is flat, because τ is curvature-free. In this example, if we assume $\Pi^1_{12} = \Pi^1_{21}$ and $\Pi^2_{12} = \Pi^2_{21}$, then $F(\tau) = G(\tau) = 0$ are equal to zero so that $\Omega_j = 0$. This is analogous to the case of dimension greater than two. In the latter case, the vanishing of Ω_j is guaranteed by Proposition 1.9.

Affine connections which induce a given normal projective connection is obtained as follows. Let $\nu_1, \nu_2 \in \mathbb{R}$ be arbitrary, and set $\Gamma^i_{jk} = \Pi^i_{jk} - (\delta^i_j \nu_k + \delta^i_k \nu_j)$ for $(i, j, k) \neq (1, 1, 1), (2, 2, 2)$, where $\delta^i_j = \begin{cases} 1, & i = j, \\ 0, & i \neq j. \end{cases}$ We have then $-6\nu_1 - (\Gamma^\alpha_{\alpha 1} + \Gamma^\alpha_{1\alpha}) = -6\nu_1 - 2\Gamma^1_{11} - \Pi^2_{21} - \Pi^2_{12} + \nu_1 + \nu_1 = -4\nu_1 - 2\Gamma^1_{11} + 2\Pi^1_{11}$. Hence we have $\Pi^1_{11} = \Gamma^1_{11} + 2\nu_1$. Similarly, we have $\Pi^2_{22} = \Gamma^2_{22} + 2\nu_2$. Thus defined affine connection induces the projective structure given by $\tau = (\Pi^i_{jk})$.

Finally, let $F^i_{jk} = \frac{\partial F}{\partial \Pi^i_{jk}}$ and $G^i_{jk} = \frac{\partial G}{\partial \Pi^i_{jk}}$. We have

$$\begin{aligned}
F^1_{12}(\tau) &= \frac{1}{2}\Pi^2_{12}\Pi^2_{12} + \Pi^2_{12}\Pi^2_{21} + \frac{1}{2}\Pi^2_{12}\Pi^2_{21} + \Pi^1_{12}\Pi^2_{11} \\
&\quad + 2\Pi^1_{12}\Pi^2_{11} - \Pi^2_{11}\Pi^1_{21}, \\
F^1_{21}(\tau) &= -\frac{1}{2}\Pi^2_{12}\Pi^2_{12} - \Pi^2_{12}\Pi^2_{21} - \Pi^2_{12}(\Pi^2_{12} - \Pi^2_{21}) - \frac{1}{2}\Pi^2_{12}\Pi^2_{21} \\
&\quad - \Pi^1_{21}\Pi^2_{11} - \Pi^1_{12}\Pi^2_{11}, \\
F^1_{22}(\tau) &= \Pi^2_{11}(\Pi^2_{12} - \Pi^2_{21}), \\
F^2_{11}(\tau) &= \frac{1}{2}(\Pi^1_{12}\Pi^1_{12} - \Pi^1_{21}\Pi^1_{21}) + \Pi^1_{12}(\Pi^1_{12} - \Pi^1_{21}) + \Pi^1_{22}(\Pi^2_{12} - \Pi^2_{21}), \\
F^2_{12}(\tau) &= \Pi^2_{12}(\Pi^1_{12} - \Pi^1_{21}) + \Pi^2_{21}(\Pi^1_{12} - \Pi^1_{21}) - 2\Pi^2_{12}\Pi^1_{21} + \Pi^1_{21}\Pi^2_{21} \\
&\quad + \frac{1}{2}\Pi^2_{21}(\Pi^1_{12} - \Pi^1_{21}), \\
F^2_{21}(\tau) &= \Pi^2_{12}(\Pi^1_{12} - \Pi^1_{21}) + \Pi^2_{12}\Pi^1_{21} + \frac{1}{2}\Pi^2_{12}(\Pi^1_{12} - \Pi^1_{21}) - \Pi^1_{22}\Pi^2_{11}, \\
G^1_{12}(\tau) &= -\Pi^1_{21}(\Pi^2_{21} - \Pi^2_{12}) - \Pi^1_{21}\Pi^2_{12} - \frac{1}{2}\Pi^1_{21}(\Pi^2_{21} - \Pi^2_{12}) + \Pi^2_{11}\Pi^1_{22}, \\
G^1_{21}(\tau) &= -\Pi^1_{21}(\Pi^2_{21} - \Pi^2_{12}) - \Pi^1_{12}(\Pi^2_{21} - \Pi^2_{12}) + 2\Pi^1_{21}\Pi^2_{12} - \Pi^2_{12}\Pi^1_{12} \\
&\quad - \frac{1}{2}\Pi^1_{12}(\Pi^2_{21} - \Pi^2_{12}), \\
G^1_{22}(\tau) &= -\frac{1}{2}(\Pi^2_{21}\Pi^2_{21} - \Pi^2_{12}\Pi^2_{12}) - \Pi^2_{21}(\Pi^2_{21} - \Pi^2_{12}) - \Pi^2_{11}(\Pi^1_{21} - \Pi^1_{12}), \\
G^2_{11}(\tau) &= -\Pi^1_{22}(\Pi^1_{21} - \Pi^1_{12}), \\
G^2_{12}(\tau) &= \frac{1}{2}\Pi^1_{21}\Pi^1_{21} - \Pi^1_{21}\Pi^1_{12} + \Pi^1_{21}(\Pi^1_{21} - \Pi^1_{12}) + \frac{1}{2}\Pi^1_{21}\Pi^1_{12} \\
&\quad + \Pi^2_{12}\Pi^1_{22} + \Pi^2_{21}\Pi^1_{22}, \\
G^2_{21}(\tau) &= -\frac{1}{2}\Pi^1_{21}\Pi^1_{21} - \Pi^1_{21}\Pi^1_{12} - \frac{1}{2}\Pi^1_{21}\Pi^1_{12} - \Pi^2_{21}\Pi^1_{22} \\
&\quad - 2\Pi^2_{21}\Pi^1_{22} + \Pi^1_{22}\Pi^2_{12}.
\end{aligned}$$

If $\Pi^1_{12} = \Pi^1_{21}$ and if $\Pi^2_{12} = \Pi^2_{21}$, then we have

$$\begin{aligned}
F^1_{12}(\tau) &= 2(\Pi^2_{12}\Pi^2_{12} + \Pi^1_{12}\Pi^2_{11}), & G^1_{12}(\tau) &= -\Pi^1_{12}\Pi^2_{12} + \Pi^1_{22}\Pi^2_{11}, \\
F^1_{21}(\tau) &= -2(\Pi^2_{12}\Pi^2_{12} + \Pi^1_{12}\Pi^2_{11}), & G^1_{21}(\tau) &= \Pi^1_{12}\Pi^2_{12}, \\
F^1_{22}(\tau) &= F^2_{11}(\tau) = 0, & G^1_{22}(\tau) &= G^2_{11}(\tau) = 0, \\
F^2_{12}(\tau) &= -\Pi^1_{12}\Pi^2_{12}, & G^2_{12}(\tau) &= 2(\Pi^1_{12}\Pi^1_{12} + \Pi^2_{12}\Pi^1_{22}), \\
F^2_{21}(\tau) &= \Pi^1_{12}\Pi^2_{12} - \Pi^1_{22}\Pi^2_{11}, & G^2_{21}(\tau) &= -2(\Pi^1_{12}\Pi^1_{12} + \Pi^2_{12}\Pi^1_{22}).
\end{aligned}$$

Hence $\left(\frac{\partial F}{\partial \tau}(\tau) \quad \frac{\partial G}{\partial \tau}(\tau)\right)$ is of rank 2 for almost every τ . If $\tau \in \mathcal{T}'$, then we have $\Pi^1_{12} \neq \Pi^1_{21}$ or $\Pi^2_{12} \neq \Pi^2_{21}$. In particular, one of $\Pi^1_{12}, \Pi^1_{21}, \Pi^2_{12}$ and Π^2_{21} is non-zero. Hence \mathcal{T}' induces an open subvariety of $\mathbb{R}P^5$. \square

An open subset of dimension 4 of \mathcal{T} exists by the implicit function theorem, however, it seems difficult to find explicit ones. We will present a family of elements of \mathcal{T} with three parameters.

Example 6.3. Suppose that $\Pi^1_{12} = \Pi^1_{21} = \Pi^1_{22} = 0$. Then we have $F(\tau) = G(\tau) = 0$ and $\Pi^2_{22} = 0$. It follows that

$$\begin{aligned}\Pi_{11} &= -\Pi^2_{12}\Pi^1_{11} + \Pi^2_{21}\Pi^2_{12} \\ &= \frac{3}{2}\Pi^2_{12}\Pi^2_{21} + \frac{1}{2}\Pi^2_{12}\Pi^2_{12}, \\ \Pi_{12} &= \Pi_{21} = 0, \\ \Pi_{22} &= 0.\end{aligned}$$

Let $a = \Pi^2_{11}$, $b = \Pi^2_{12}$ and $c = \Pi^2_{21}$. The normal TW-connection is given by

$$\omega = \begin{pmatrix} -\frac{b+c}{2}dx^1 & 0 & 0 \\ adx^1 + bdx^2 & cdx^1 & 0 \\ -\frac{3}{2}(3bc + b^2)dx^1 & 0 & 0 \end{pmatrix} - \frac{1}{3} \begin{pmatrix} dt & dx^1 \\ & dt & dx^2 \\ & & dt \end{pmatrix}$$

We have $\Omega^1 = 0$ and $\Omega^2 = \frac{1}{3}(b-c)dx^1 \wedge dx^2$. The torsion of ω is equal to $\begin{pmatrix} 0 \\ -b+c \end{pmatrix} dx^1 \wedge dx^2$. By setting $a = b = 1$ and $c = -1$, we obtain Example 6.1. Note that the ratio $a : b : c$ is relevant.

We have another kind of a one-parameter family.

Example 6.4. Let $\Pi^1_{12} = -\Pi^1_{21} = \sin \theta$ and $\Pi^2_{21} = -\Pi^2_{12} = \cos \theta$. We have $\Pi^1_{11} = \Pi^2_{22} = 0$ by (6.2-1) and (6.2-2). On the other hand, we have

$$\begin{aligned}F(\tau) &= 2(\sin^2 \theta - (\cos \theta)\Pi^1_{22})\Pi^2_{11}, \\ G(\tau) &= -2(\cos^2 \theta - (\sin \theta)\Pi^2_{11})\Pi^1_{22}.\end{aligned}$$

- 1) If $\sin \theta = 0$, then we have $\cos \theta \neq 0$. Since $G(\tau) = 0$, we have $\Pi^1_{22} = 0$. Hence $\Pi_{12} = \Pi_{21} = 0$ by (6.2-4). We have $\Pi_{11} = -1$ and $\Pi_{22} = 0$ by (6.2-3) and (6.2-5). The normal TW-connection is given by

$$\begin{pmatrix} 0 & 0 & 0 \\ \Pi^2_{11}dx^1 \pm dx^2 & \mp dx^1 & 0 \\ 3dx^1 & 0 & 0 \end{pmatrix} - \frac{1}{3} \begin{pmatrix} dt & dx^1 \\ & dt & dx^2 \\ & & dt \end{pmatrix},$$

where the double signs correspond and Π^2_{11} is arbitrary.

2) If $\cos \theta = 0$, then the normal TW-connection is given by

$$\begin{pmatrix} \pm dx^2 & \mp dx^1 + \Pi^1_{22} dx^2 & 0 \\ 0 & 0 & 0 \\ 0 & 3dx^2 & 0 \end{pmatrix} - \frac{1}{3} \begin{pmatrix} dt & dx^1 \\ dt & dx^2 \\ dt & dt \end{pmatrix}.$$

3) If $\sin \theta \neq 0$ and if $\cos \theta \neq 0$, then either $\Pi^1_{22} = \Pi^2_{11} = 0$ or $\Pi^1_{22} = \frac{\sin^2 \theta}{\cos \theta}$, $\Pi^2_{11} = \frac{\cos^2 \theta}{\sin \theta}$. In the first case, the normal TW-connection is given by

$$\begin{pmatrix} \sin \theta dx^2 & -\sin \theta dx^1 & 0 \\ -\cos \theta dx^2 & \cos \theta dx^1 & 0 \\ 0 & 0 & 0 \end{pmatrix} - \frac{1}{3} \begin{pmatrix} dt & dx^1 \\ dt & dx^2 \\ dt & dt \end{pmatrix}.$$

In the second case, the normal TW-connections is given by

$$\begin{pmatrix} \sin \theta dx^2 & -\sin \theta dx^1 + \frac{\sin^2 \theta}{\cos \theta} dx^2 & 0 \\ \frac{\cos^2 \theta}{\sin \theta} dx^1 - \cos \theta dx^2 & \cos \theta dx^1 & 0 \\ 0 & 0 & 0 \end{pmatrix} - \frac{1}{3} \begin{pmatrix} dt & dx^1 \\ dt & dx^2 \\ dt & dt \end{pmatrix}.$$

In the both cases, the torsion is given by $2 \begin{pmatrix} -\sin \theta \\ \cos \theta \end{pmatrix} dx^1 \wedge dx^2$. Hence the ratio $K^1_{12} : K^2_{12}$ can take any value. The latter connection can be slightly generalized as

$$\begin{pmatrix} r \sin^2 \theta \cos \theta dx^2 & -r(\sin^2 \theta \cos \theta dx^1 + \sin^3 \theta dx^2) & 0 \\ r(\cos^3 \theta dx^1 - \sin \theta \cos^2 \theta dx^2) & r \sin \theta \cos^2 \theta dx^1 & 0 \\ 0 & 0 & 0 \end{pmatrix} - \frac{1}{3} \begin{pmatrix} dt & dx^1 \\ dt & dx^2 \\ dt & dt \end{pmatrix}.$$

of which the torsion is given by $2r \sin \theta \cos \theta \begin{pmatrix} -\sin \theta \\ \cos \theta \end{pmatrix} dx^1 \wedge dx^2$.

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